

Low Cost Development Testbeds for Implementing the Digital Thread

Russ Waddell, AMT – The Association For Manufacturing Technology

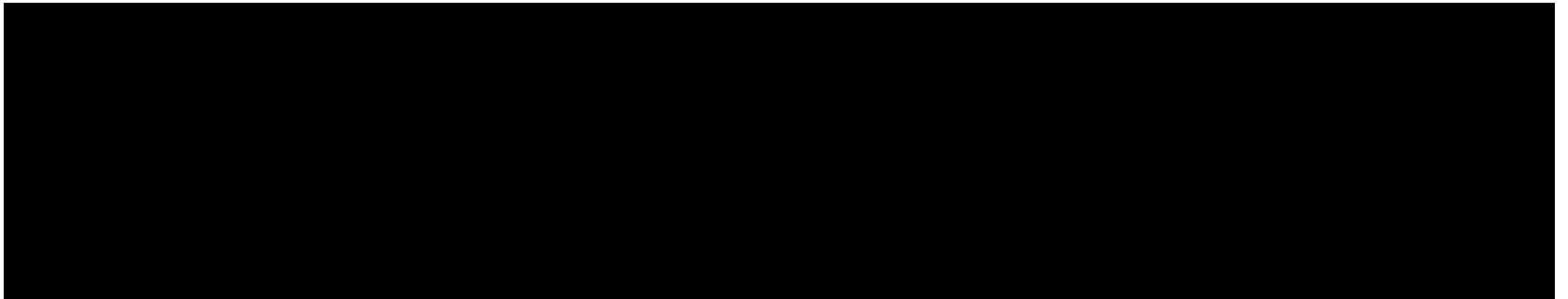
Roby Lynn, Georgia Tech

Kyle Saleeby, Georgia Tech

Stephen LaMarca, AMT – The Association For Manufacturing Technology

Shaurabh K. Singh, AMT – The Association For Manufacturing Technology

Background



Digital Thread is
great

Digital Thread is

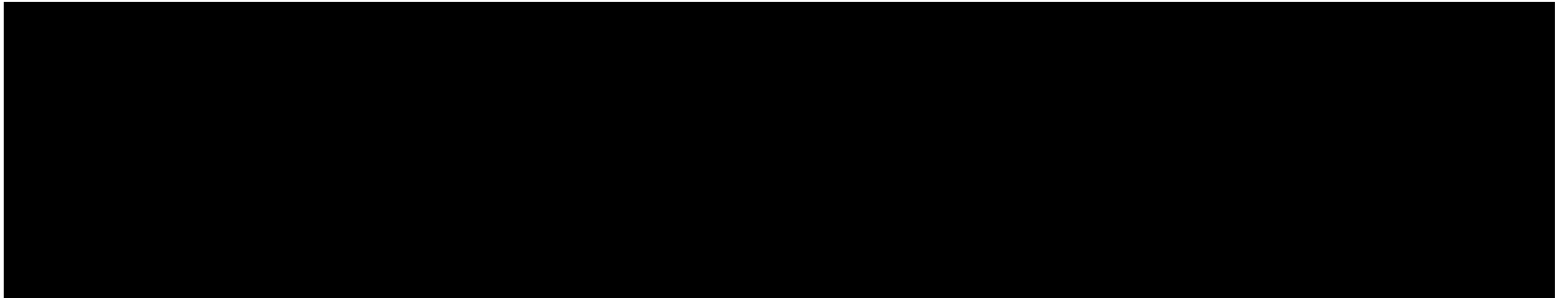
(going to be)

great

1. Research platforms
are helping fill gaps.

2. PocketNC desktop
5-axis is cheap*.

Research Platforms



Research platforms are helping fill gaps.

NIST

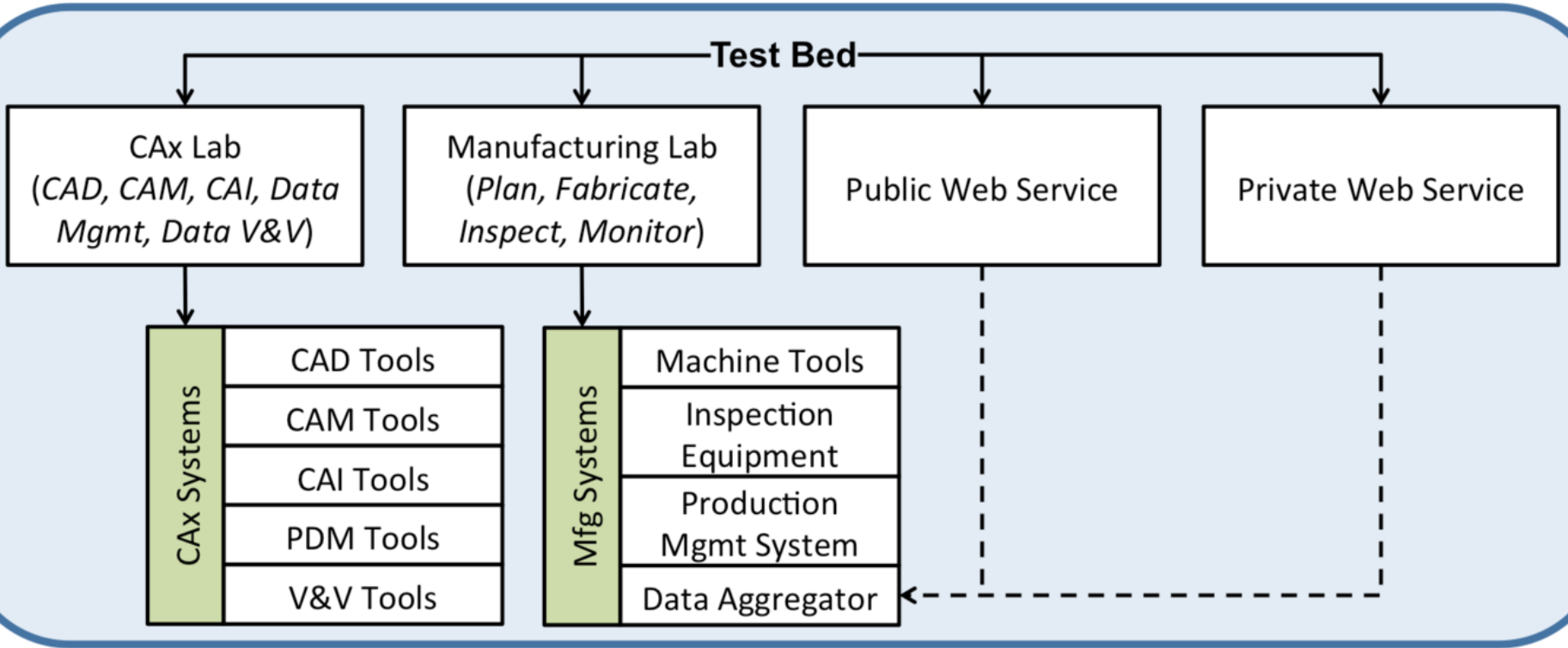
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NIST

Smart Mfg Systems Testbed





AMT

Pop Up Shop







STAN SMITH 2

MADE IN GERMANY
PARCEL: 30-1000000

ORIGINALS
ORIGINALS

SP/WH/NEON
BLAC/BLAC/OW/

G17080

US	8
UK	7½
D	7½
E	41½
J	260
CHN	255



Store

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PEOPLE WANT TO WORK FOR, BUY FROM, AND INVEST IN BUSINESSES THEY BELIEVE IN. B CORP CERTIFICATION IS THE MOST POWERFUL WAY TO BUILD CREDIBILITY, TRUST, AND VALUE FOR YOUR BUSINESS.

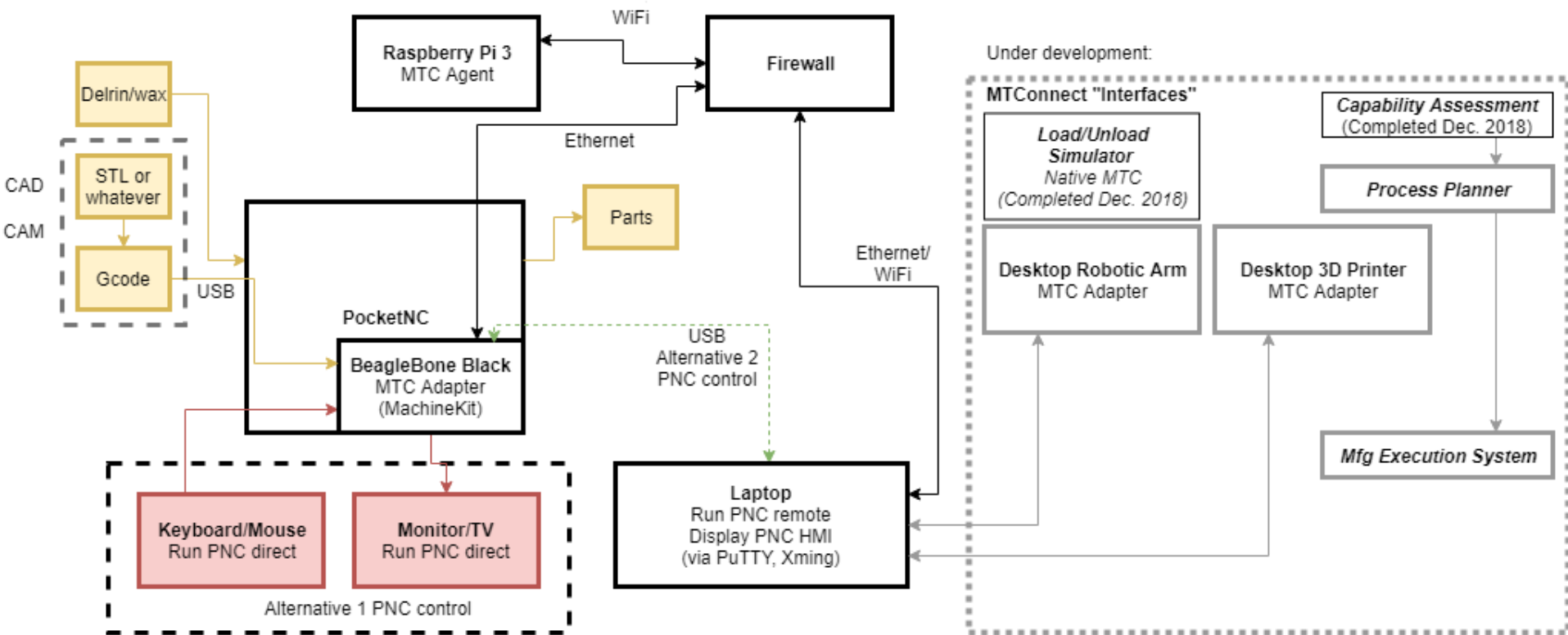
BUY

Certified



Corporation

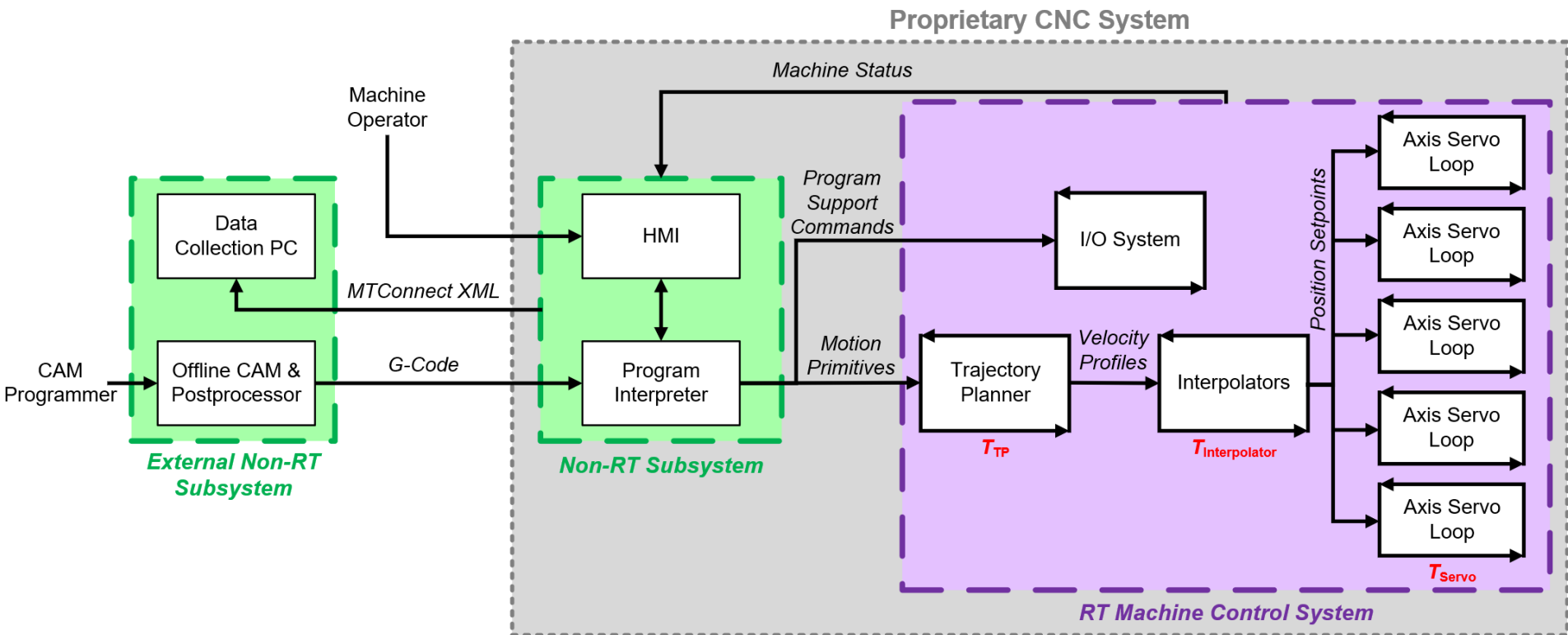
PRODUCTS HERE



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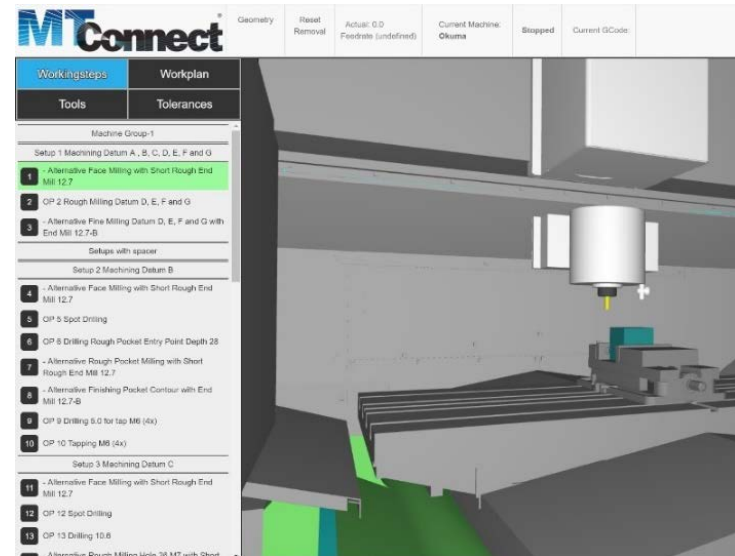


Typical CAM → CNC System



Alternative Data Flow Standards

- **Feedback:** MTConnect, OPC-UA, proprietary APIs
 - Low frequency feedback: typically less than 100s of Hz for *some* data items
 - Limitations on flow direction
 - Okuma THINC, Mazak Smooth API
- **Control:** STEP-NC
 - Object-oriented machine tool programming
 - Interoperability between different types of machine tools
 - Online trajectory planning
- NC.js
 - Realtime machining simulation of a STEP-NC program using MTConnect data



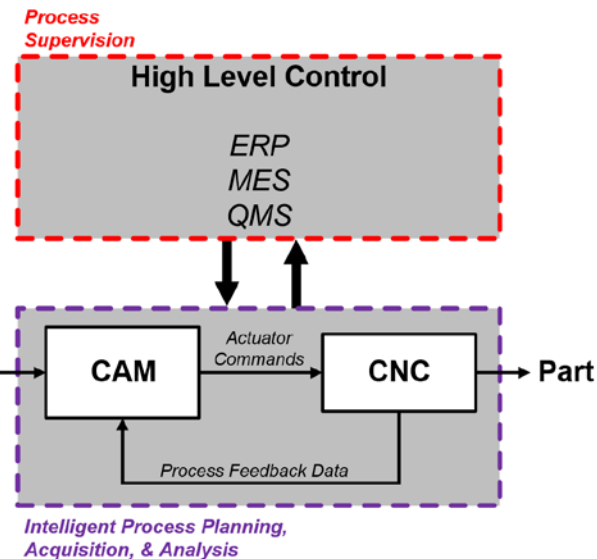
Direct Servo Control from Voxel-Based CAM: Research Objectives



More Control

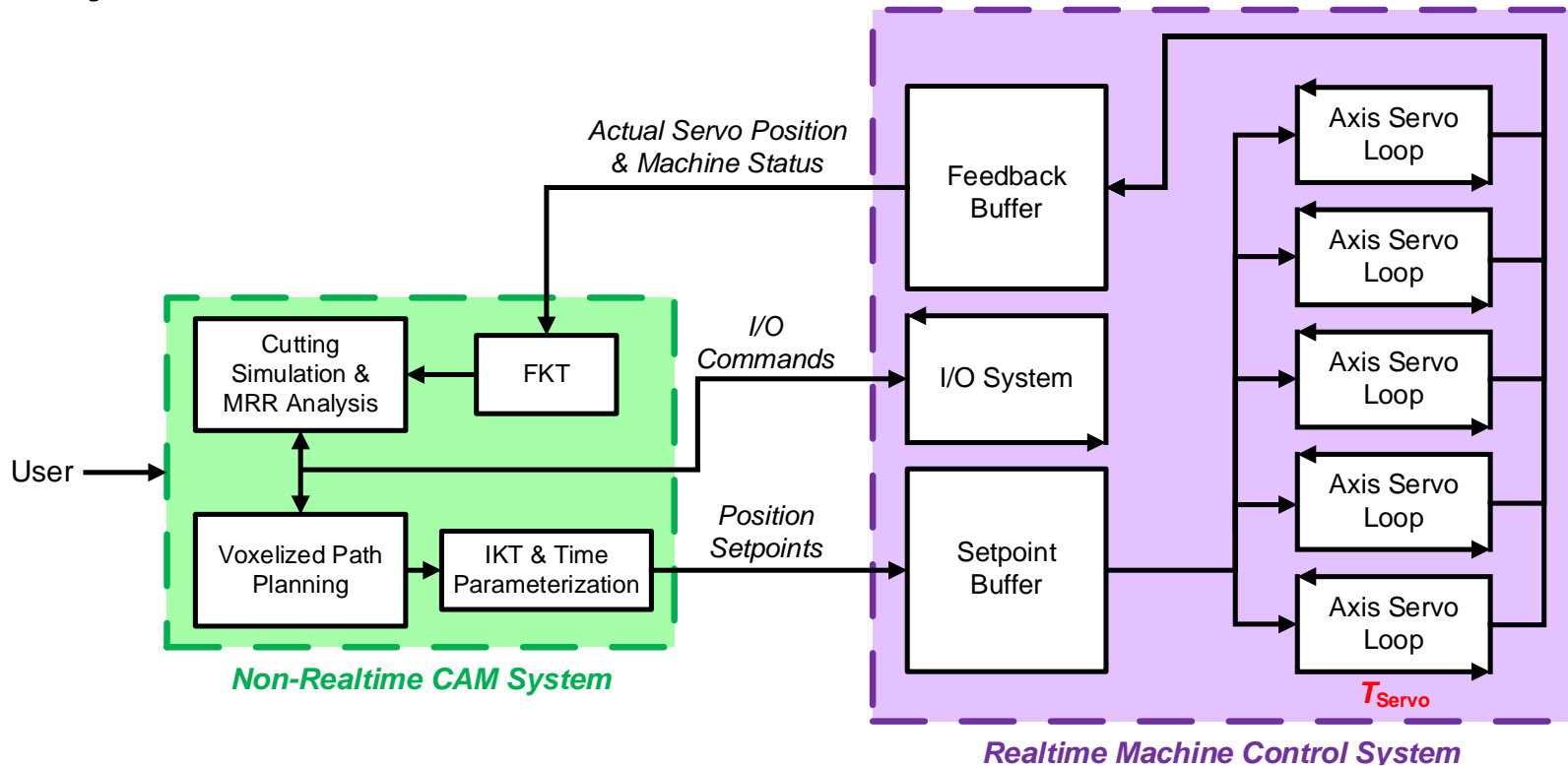
Higher Data Availability

Increased Autonomy



- Framework for a smarter and more integrated realtime machine tool control system
 - Software and hardware, experimental motion profiles, performance analysis

Direct Servo Control from Voxel-Based CAM: System Architecture



Future Factory Software Architecture & Supporting Applications

Boeing PI: Al Salour

Ga. Tech PIs: Dr. Tom Kurfess; Andy Dugenske

Research Team: Daniel Newman, Kyle Saleeby

- Digital Architecture Implementation
- PocketNC Connect Desktop Implementation
- Live Machine Monitoring Testbed

Digital Architecture Implementation

- MQTT machine monitoring architecture
- JSON data structure
- Many-to-many communication pattern
- Robust and flexible for diverse machines and processes

Live Machine Monitoring Testbed

- Three OKUMA Genos machines connected and monitored
- 800 Parts machined each semester via ME2110: Creative Decision and Design
- Data integration with Digital Twin modeling efforts

PocketNC

*Cheap = Total cost under \$10,000 for a reasonable facsimile of a manufacturing cell

PocketNC

desktop 5-axis mill

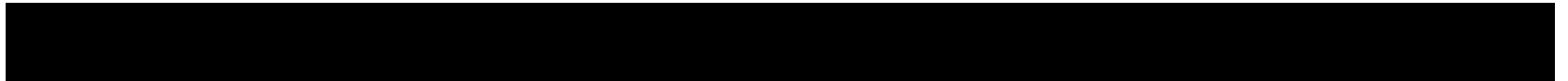
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Tec De Monterrey

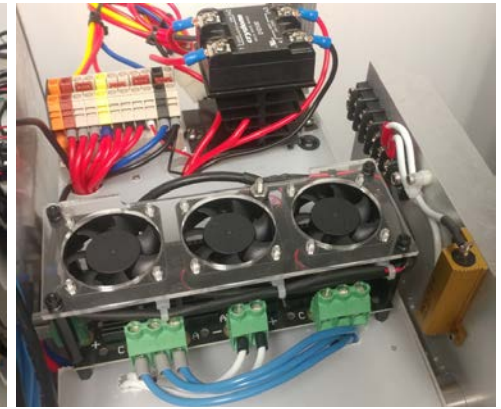
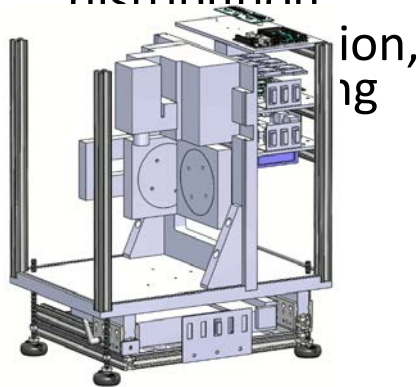
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Roby Lynn



Research Machine Tool: Hardware

- VMC conversion of PocketNC
 - Expandability, \$50 BBB
 - Axis encoders
 - Closed-loop spindle control
 - Power distribution



CAM-Controlled PocketNC

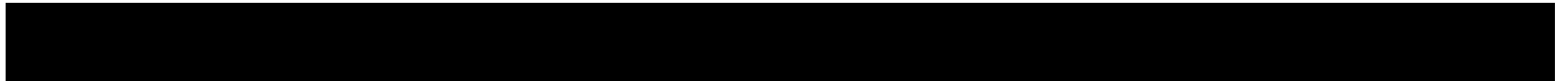
Pocket NC (V1)	4,000
Frame	700
Electronics	300
Sensors	600
Control PC	2,000

TOTAL, Directly-Controlled Desktop CNC	\$7,600
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Daniel Newman

Kyle Saleeby



PocketNC Connect Desktop Implementation

- PocketNC 5-axis desktop CNC machine
- Full in-house implementation without cloud connectivity
- Secure for classified facilities
- Increased sample frequency and higher data quality

PocketNC Connect Desktop Implementation



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Pop Up Shop



AMT Pop Up Shop, current scope

Pocket NC (V2)	5,500
Pocket NC enclosure	549
Vise	60
Travel case	299
Raspberry Pi (bundle)	85
Laptop	600
TOTAL, Desktop CNC	\$7,093

AMT Pop Up Shop, future scope

Ufactory xArm	7,000
xArm gripper	1,500
TOTAL, Desktop CNC + Desktop Robotic Arm	\$15,593

CONCLUSIONS

Researchers should:

Review existing testbed models

Publish system architectures

Share findings with suppliers

Bridge gaps from lab to shop

See also:

research platform, manufacturing system architecture, low-cost hardware

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Standards developers should pursue:

Openness

Modularity

Pluggable architectures

Harmonization

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