A Channel Propagation Model for the 700 MHz Band

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Abstract—Conversion from analog television in the United States combined with the appeal for broadband public safety communications is generating a lot of interest in the so-called 700 MHz band between 698-806 MHz. To our knowledge, no channel propagation model for this band exists to date. In this work, we derive such a model reduced from a measurement campaign realized through a stepped-frequency system. The campaign includes 89 transmitter-receiver configurations in seven different environments relevant to residential, commercial and public safety communications, ranging from subterranean mine tunnels to an oil refinery, from mid-size to high-rise buildings. The stochastic impulse response model complete from 17 parameters which enables reconstruction for use in simulation engines, amongst others.

Index Terms—Public safety bands; LTE

I. INTRODUCTION

The conversion from analog television in the United States combined with the appeal for broadband public safety communications, is generating a lot of interest in the 700 MHz band. Thus, the 764-776 MHz and 794-806 MHz blocks have been dedicated to public safety while the others have been auctioned off to vendors for commercial services, and some blocks for joint use between the two [1]. This so-called 700 MHz band offers excellent penetration through buildings, which is particularly useful for emergency responders and Enhanced 911 services. For commercial vendors, the investment is motivated by the favorable propagation characteristics which extend coverage significantly for the same transmission power, translating into less infrastructure: while it requires nine cells at 2400 MHz and four cells at 1900 MHz to span 100 m, it is projected to require only one cell at 700 MHz [2].

However before any network technology can be developed and deployed in this band, there is a need to characterize and understand the propagation environment in which it must operate.

To our knowledge, no channel propagation model for the 700 MHz band exists in the open literature to date. In this work, we derive such a model, reduced from a measurement campaign conducted in seven different environments relevant to most usage scenarios, ranging from subterranean mine tunnels to an oil refinery, from mid-size to high-rise buildings.

The paper reads as follows: Section II describes the stepped-frequency technique used to measure the propagation channel between a transmitter and receiver. The subsequent section explains our measurement system realized through a vector network analyzer, and outlines the campaign. Section IV features the proposed stochastic model characterizing the channel impulse response with parameters reported individually for each environment. The last section summarizes our results.

II. THE CHANNEL IMPULSE RESPONSE

The impulse response \( h(t) \) characterizes the static propagation channel, appropriate for use in public-safety applications where responders move slowly and in stages through a structure. It is composed from an infinite number of multipath arrivals indexed through \( k \):

\[
h(t) := \sum_{k=1}^{\infty} a_k e^{j\phi_k} \delta(t - \tau_k),
\]

where \( \tau_k \) denotes the delay of the arrival in propagation between the transmitter and receiver and the complex-amplitude \( a_k e^{j\phi_k} \) accounts for attenuation and phase change due to reflection, diffraction, and other specular effects introduced by walls (and other objects) on its path.

The impulse response has a frequency response

\[
H(f) = \sum_{k=1}^{\infty} a_k e^{j\phi_k} e^{-j2\pi f \tau_k},
\]

suggesting that the channel can be characterized through the stepped-frequency technique. We sample \( H(f) = \frac{Y(f)}{X(f)} \) at rate \( \Delta f \) by transmitting tones \( X(f) \) across the channel and then measuring \( Y(f) \) at the receiver. Characterizing the channel in the frequency domain offers an advantage over transmitting a UWB pulse and recording the impulse response directly: a subband with bandwidth \( B \) and center frequency \( f_c \) can be selected a posteriori in reconstructing the channel. The discrete frequency spectrum \( X(f) \) transforms to a signal with period \( \frac{1}{\Delta f} \) in the time domain [3], and so choosing \( \Delta f = 0.375 \) MHz allows for a maximum multipath spread of 2667 ns which proves sufficient throughout...
all seven environments for the arrivals to subside within one period and avoid time aliasing.

The impulse response $h(t)$ can then be recovered through the Inverse Discrete Fourier Transform (IDFT) of the frequency response by synthesizing all the frequencies in the subband as

$$h(t) = \frac{1}{B} \sum_{l=1}^{B} H(f)e^{j2\pi ft},$$

where $f = f_c - \frac{B}{2} + l \cdot \Delta f$.

III. THE MEASUREMENT SYSTEM AND CAMPAIGN

A. The measurement system

Fig. 1(a) displays the block diagram of our measurement system. As explained in the previous section, the vector network analyzer (VNA) emits a series of tones with frequency $f$ at Port 1 and measures the relative complex amplitude $S_{21}(f)$ at Port 2 with respect to Port 1, providing automatic synchronization between the two. The 200 m optical link enables measurement of the one-way propagation channel for variable placement of the transmitter and receiver antennas from each other throughout the test area. The optical fiber itself combines ultra-low loss and dispersion up to 100 GHz frequencies with immunity to electrical interference, preventing cross-talk between cables and pickup of environmental noise. The identical discone transmit and receive antennas were mounted on tripods with height fixed of 1.5 m and the output power at Port 1 was set to -13 dBm. After radiating from the transmitter, the signal propagates across the channel. Once detected by the receiver, it passes through the optical link before being fed back to Port 2.

The $S_{21}(f)$-parameter of the network in Fig. 1(a) can be expressed as a product of the $Tx$-antenna, the propagation channel $H$, the $Rx$-antenna, and the $Rx$-branch:

$$S_{21}(f) = H_{Tx}^{ant}(f) \cdot H(f) \cdot H_{Rx}^{ant}(f) \cdot H^{bra}_{Rx}(f)$$

The response $H^{bra}_{Rx}$, including the non-ideal VNA electronics, connectors, cables, amplifiers, and optical fiber link, is calibrated out using a standard VNA calibration technique where known impedance standards are connected sequentially at both ports. The response of the antennas and their connecting cables, $H_{Tx}^{ant}$ and $H_{Rx}^{ant}$, are calibrated out in a subsequent step by separating the antennas by 3 m and recording the free-space parameter $S_{21}^{Fs}$ for which $H = H_{Fs}$, the response of the 3 m free-space channel. $S_{21}^{Fs}$ is subsequently time-gated to remove both the ground bounce between the antennas and the spurious environmental effects as shown in Fig. 1(b). Finally the sought measured response $H$ between any transmitter-receiver configuration can be extracted from the measured parameter $S_{21}$ by dividing it by the free-space parameter such that $H = \frac{S_{21}}{S_{21}^{Fs}} H_{Fs}$, which also accounts for $H_{Fs}$ given through the Friis transmission equation [4]. Complete details of the measurement system are available in [5].

B. The measurement campaign

The measurement campaign was conducted in several different environments in Colorado and California [5], [6], as summarized in Table I. A total of 89 experiments were recorded mostly in non-line-of-sight conditions, except for a few in the mine tunnels. As the environments are representative of public safety scenarios, the majority was taken by placing the transmitter outside, typically at a command post, and the receiver inside, simulating

\footnote{This ensures operation within the far-field of the antennas while minimizing environmental reflections.}
an emergency responder. The ground-truth distance \( d \) between the transmitter and receiver was recorded for each experiment.

<table>
<thead>
<tr>
<th>environment</th>
<th>location</th>
<th>range (m)</th>
<th>Tx-Rx config.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Oil Refinery</td>
<td>Commerce City CO</td>
<td>33.8-135.4</td>
<td>outside–outside²</td>
</tr>
<tr>
<td>Greathouse Mine Tunnel</td>
<td>Antioch, CA</td>
<td>4.7-101.4</td>
<td>inside–inside</td>
</tr>
<tr>
<td>Hazel-Atlas Mine Tunnel</td>
<td>Antioch, CA</td>
<td>4.3-114.2</td>
<td>outside–inside</td>
</tr>
<tr>
<td>Horizon West Apartments</td>
<td>Boulder, CO</td>
<td>59.1-107.7</td>
<td>outside–inside</td>
</tr>
<tr>
<td>NIST Lab</td>
<td>Boulder, CO</td>
<td>54.2-137.6</td>
<td>outside–inside</td>
</tr>
<tr>
<td>Convention Center</td>
<td>Denver, CO</td>
<td>13.4-189.6</td>
<td>outside–inside</td>
</tr>
<tr>
<td>Republic Plaza³</td>
<td>Denver, CO</td>
<td>12.7-52.0</td>
<td>outside–inside</td>
</tr>
</tbody>
</table>

**IV. THE PROPOSED CHANNEL PROPAGATION MODEL**

This section describes the proposed channel propagation model. It is divided into two components: 1) the reference impulse response characterizes the shape of the multipath profile \( h(t) \) while 2) the pathgain scales its amplitude according to the distance between the transmitter and receiver. The two corresponding subsections explain the extraction and modeling of the parameters of each component, following by a subsection that outlines in pseudocode how to employ the parameters to generate a stochastic impulse response in each of the environments.

**A. The pathgain model**

The excess pathgain⁴ is defined as

\[
PG(d) := \frac{1}{2\pi f} \sum_{l=1}^{d} |H(f)|^2, \tag{5}
\]

where \( f = f_c - \frac{b}{2} + l \cdot \Delta f \). Each data point is computed from the measured frequency response for \( f = 698–806 \) MHz from an experiment with distance \( d \). In order to generate a model for the pathgain, consider decomposing the arrival amplitude in (2)

\[
a_k = \hat{a}_k \left( \frac{d}{d_0} \right)^{-\frac{n}{2}} \tag{6}
\]

as a product of the reference amplitude \( \hat{a}_k \) valid at reference point \( d_0 \) and the pathgain factor representing the distance dependence of the amplitude. By substituting (2) into (5) and expanding, the pathgain model can be written as

\[
(a) \quad PG(d) = PG(d_0) \left( \frac{d}{d_0} \right)^{-\frac{n}{2}}; \tag{7}
\]

\[
(b) \quad PG(d_0) = \sum_{k=1}^{\infty} \hat{a}_k^2. \tag{8}
\]

The reference pathgain \( PG(d_0) \) for \( d_0 = 1 \) m and the attenuation coefficient \( n \) were extracted by robust fitting⁵ of the model above to the data points from (5). We actually found the breakpoint model [8]

\[
PG(d) = \begin{cases} 
PG(d_0) \left( \frac{d}{d_0} \right)^{-\frac{n_0}{2}} \cdot 10^\frac{s_1}{n_0}, & d \leq d_1 \\
PG(d_1) \left( \frac{d}{d_1} \right)^{-\frac{n_1}{2}} \cdot 10^\frac{s_2}{n_1}, & d > d_1 
\end{cases} \tag{9}
\]

to represent the data more accurately in some environments. For example, in the mine tunnel environments, the first segment for \( d \leq d_1 \) were in line-of-sight conditions while in the second segment the receiver was positioned around a corner passage and so in non-line-of-sight conditions. As well, in Oil Refinery, the first segment was also in line-of-sight conditions however in the second a train of large metal columns obstructed the receiver.

The pathgain in (8) is augmented by the well-established parameter \( s_d \sim \mathcal{N}(s_d; 0, \sigma_d) \), normally distributed, which quantifies the variation between our model and the data points and in that capacity represents the stochastic nature of the pathgain. This is of particular use when simulating time diversity systems [9]. The model parameters for each of the seven environments appear in Table II.

**B. The reference impulse response model**

Our model for the reference impulse response \( \hat{h}(t) \) valid at \( d_0 \) essentially follows from (1) by exchanging \( a_{jk} \) with \( \hat{a}_{jk} \):

\[
\hat{h}(t) = \sum_{j=1}^{\infty} \sum_{k=1}^{\infty} \hat{a}_{jk} e^{j2\pi f \Delta t} \delta(t - \tau_{jk}) \tag{10}
\]

It partitions the arrivals indexed through \( k \) into clusters indexed through \( j \), as illustrated in Fig. 2(a) for a recorded impulse response in Oil Refinery. The notion of clusters harkens back to the well-known phenomenon first witnessed in [10] caused by larger scatterers in the environment which induce a group delay in the resultant arrivals with respect to those of the first cluster. We identified the clusters visually.

³Dense piping presented an environment similar to inside–outside, as discussed in [6].

³The Republic Plaza is a high-rise building located in the downtown metropolitan area.

⁴There are alternative definitions to ours for the pathgain as summarized in [4].

⁵Robust fitting henceforth denotes the Trust-Region method explained in [7].
In order to extract the parameters of the model, \( \hat{h}(t) \) was computed for each experiment through the IDFT in (3) for \( f = 698–806 \) MHz. However, the recorded frequency response was first normalized by the pathgain factor, replacing it instead with \( \tilde{H}(f) = \frac{H(f)}{d_0 - n_2} \). Note that the parameters of the pathgain model in the previous subsection are needed in this step and so were extracted beforehand. As the receiver was placed indoors in all but \textit{Oil Refinery}, the smaller indoor dimensions caused the arrivals to appear faster than the conventional delay resolution \( \frac{1}{B} \) of the IDFT for \( B = 108 \) MHz. As a result, we chose to implement the super-resolution algorithm in [3] to generate a pseudospectrum in the place of \( \tilde{h}(t) \). From it, the arrival delays \( jk \) were extracted followed by the least-squares fit in [11] to estimate \( (\tilde{a}_{jk}, \varphi_{jk}) \). The latter also estimates the number of arrivals automatically through a minimum description length criteria as opposed to arbitrary selection above a certain amplitude threshold.

1) The delay \( jk \):

The equations in (10) govern the arrival delays. The ground-truth delay \( \tau_0 \) in (10a) is the time elapsed for the signal to travel the distance \( d \) at the speed of light \( c \). The inter-cluster delay between the first cluster and the ground-truth delay \( \tau_1 = \tau_0 \), as well as between the other clusters \( \tau_j - \tau_{j-1} \), \( j \geq 1 \), depends on the randomly located larger scatterers in the environment such as doors and hallways. The widely accepted Saleh-Valenzuela (S-V) model proposes that the inter-cluster delay obeys the Exponential Distribution [8], [10], [12], [13]; we believe that this consensus is rather an artifact of small measurement bandwidth coupled with conventional IDFT techniques which place the sub-resolution delays within the smallest bin by default, neglecting the distribution within this bin and in turn artificially inflating its concentration with respect to the others; this lends the overall distribution a seemingly exponential appearance. As some other authors [14], [15], we found through using super-resolution techniques that the Weibull Distribution

\[
W(\tau_j - \tau_{j-1}; \Lambda, K) = \frac{K}{\Lambda} \left( \frac{\tau_j - \tau_{j-1}}{\Lambda} \right)^{K-1} e^{-\left( \frac{\tau_j - \tau_{j-1}}{\Lambda} \right)^K},
\]

which reduces to the Exponential Distribution for \( K = 1 \), allows a more exact fitting of the curve to the data for \( (\tau_j - \tau_{j-1}) \) in (10b). Likewise the \textit{inter-arrival delay} \( (\tau_{jk} - \tau_{j,k-1}) \) between arrivals within cluster \( j \) also obeys the Weibull Distribution in (10c) due to randomly located smaller scatterers such as furniture, as shown for \textit{Oil Refinery} in Fig. 3.

\[
\begin{align*}
(10) & \\
(a) & \tau_0 = \frac{d}{c} \\
(b) & (\tau_j - \tau_{j-1}) \sim W(\tau_j - \tau_{j-1}; \Lambda, K), \ j \geq 1 \\
(c) & (\tau_{jk} - \tau_{j,k-1}) \sim W(\tau_{jk} - \tau_{j,k-1}; \lambda, \kappa), \ j \geq 2
\end{align*}
\]

In order to fit the parameters of the distributions, the clusters were first isolated visually from the multipath profile of each experiment and indexed according to the cluster delay \( \tau_j \). The two parameters of the Weibull distribution were then robust fit to the inter-cluster delays given from all the experiments in a particular environment; in the same manner, the two parameters were fit to all the inter-arrival delays.

2) The complex reference amplitude \( \tilde{a}_{jk} e^{j\varphi_{jk}} \):

In the original S-V model and in reference to Fig. 2(a), the cluster amplitude \( \tilde{a}_j \) fades exponentially versus the cluster delay \( \tau_j \) according to the cluster decay constant \( \Gamma(\tau_j) \) in (11a) for \( \Gamma_1 = -1 \). We found that allowing...
\[ \Gamma_1 \geq 0 \] gives a better fit as illustrated in (dB) for *Oil Refinery* in Fig. 4(a), showing that the cluster amplitude in fact fades slower than exponential, with variation from the curve \( s_\Gamma \). Also in the original model and as displayed in Fig. 2(a), the arrival amplitude \( \tilde{a}_{jk} \) fades exponentially versus the intra-cluster delay \( (\tau_{jk} - \tau_j) \) according to the arrival decay constant \( \gamma(\tau_j) \) in (11b) for \( \gamma_1 = \gamma_2 = 0 \). Some researchers [8], [12], though, have found \( \gamma(\tau_j) \) to be a function of the cluster delay \( \tau_j \) and so have allowed \( \gamma_1 = 1 \); we found that unrestricting \( \gamma_1 \) gives an even better fit with variation from the curve \( s_{\gamma_j} \), as illustrated for *Oil Refinery* in Fig. 4(b). Finally, the arrival phase \( \varphi_{jk} \) in (11c) is well-established in literature as uniformly distributed [3].

\[
\begin{align*}
(a) & \quad \tilde{a}_j = \tilde{a}_0 \cdot 10^{-\frac{1}{2} \frac{\Gamma(\tau_j)}{10^2}}; \\
& \quad \Gamma(\tau_j) = \frac{1}{\Gamma_0} \left( \frac{\tau_j}{\tau_{ns}} \right)^{\gamma_1} + s_\Gamma, \\
& \quad s_\Gamma \sim \mathcal{N}(s_\Gamma; 0, \sigma_\Gamma) \\
(b) & \quad \tilde{a}_{jk} = \tilde{a}_j \cdot 10^{-\frac{1}{2} \frac{\gamma(\tau_j)(\tau_{jk} - \tau_j) + s}{10^2}} ; \\
& \quad \gamma(\tau_j) = \frac{1}{\gamma_0} \left( \frac{\tau_j}{\tau_{ns}} \right)^{-\gamma_1} + \gamma_2 + s_{\gamma_j}, \\
& \quad s_{\gamma_j} \sim \mathcal{N}(s_{\gamma_j}; 0, \sigma_{\gamma_j}), \\
& \quad s \sim \mathcal{N}(s; 0, \sigma) \\
(c) & \quad \varphi_{jk} \sim \mathcal{U}(\varphi_{jk}; 0, 2\pi)
\end{align*}
\]

In order to determine the parameters in (11a-b), assuming an exponential decay for the arrival amplitude as explained above, we equivalently robust fit a line to it in (dB) in Fig. 4(c) with \( s \) capturing the variation from the curve. Each fit in turn yields a data point for both the cluster amplitude in Fig. 4(a) and the arrival decay constant in Fig. 4(b) versus the cluster delay \( \tau_j \). Subsequently, we robust fit the curves shown to the data points collected from all the clusters in order to extract \((\Gamma_0, \Gamma_1, \sigma_\Gamma)\) and \((\gamma_0, \gamma_1, \gamma_2, \sigma_\gamma)\) respectively.

In *NIST Lab* and *Republic Plaza*, there is virtually no penetration of the direct path given the density of the building materials and so the first cluster in particular experiences a strong exponential rise to the peak, typical of non line-of-sight conditions, before the normal decay of the arrivals. This exponential rise can be modeled in the same manner as the decay through (11b), however by replacing \((\gamma_0, \gamma_1, \gamma_2)\) with \((\gamma_0^+, \gamma_1^+, \gamma_2^+)\) = (-7.294e-5, 1.941, 1.890e-2) and (-1.304e-1, 0.116, 4.260) in *NIST Lab* and *Republic Plaza* respectively. Fig. 2 highlights a recorded impulse response with an exponential rise in the first cluster in *NIST Lab* (b) in comparison to one without in *Oil Refinery* (a).

### C. Reconstructing the impulse response

A stochastic impulse response can be reconstructed from our model through the following steps:

1) Select \( d \) (and in turn \( \tau_0 = \frac{d}{c} \)) and the parameters from one of the seven environments in Table II;

2) Generate the stochastic variables \((\tilde{a}_{jk}, \varphi_{jk}, \tau_{jk})\) of the arrivals from the reference impulse response model in Section IV-B: set \( \tilde{a}_0 = 1 \) in (11a) and then normalize the amplitudes to satisfy (7b), keeping only those clusters and arrivals with amplitude above some threshold;

3) Choose a subband in \( f = 698–806 \text{ MHz} \) with bandwidth \( B \) and center frequency \( f_c \), and sample interval \( \Delta f \); compute \( H(f) \) in (2) for each sample frequency from the pathgain model in Section IV-A and the generated arrivals;

4) Compute the sought impulse response \( h(t) \) through (3).

### V. Conclusions

In this paper, we have proposed a channel propagation model for the 700 MHz band in seven environments. The stochastic model is described through a channel impulse response complete with 17 parameters extracted from data collected from 89 transmitter-receiver configurations using the stepped-frequency measurement technique. Ours breaks from the original Saleh-Valenzuela model to evidence a slower than exponential decay in the cluster amplitude as well as an exponential decay in the arrival amplitude dependent on the cluster delay. In addition, we employed a super-resolution algorithm as opposed to the conventional Inverse Discrete Fourier Transform to expose that the inter-arrival delays are actually Weibull distributed.
Table II

<table>
<thead>
<tr>
<th>Environment</th>
<th>Cluster Amplitude $A_0$ (dB)</th>
<th>$n_0$</th>
<th>$n_1$</th>
<th>$d_1$ (m)</th>
<th>$\sigma_d$ (dB)</th>
<th>$\lambda$ (ns)</th>
<th>$K$</th>
<th>$\lambda^*$ (ns)</th>
<th>$\alpha$</th>
<th>$\Gamma_0$ (dB)</th>
<th>$\Gamma_1$ (dB)</th>
<th>$\Gamma_2$ (dB)</th>
<th>$\sigma_r$ (dB)</th>
<th>$\sigma_c$ (dB)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Oil Refinery</td>
<td>1.94</td>
<td>0.52</td>
<td>0.38</td>
<td>0.56</td>
<td>3.67</td>
<td>0.11</td>
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<td>2.10</td>
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<td>1.451e-1</td>
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<td>-1.84</td>
<td>0.52</td>
<td>0.53</td>
<td>0.53</td>
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<td>Horizon West Apartments</td>
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<td>Republic Plaza</td>
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<td>582.97</td>
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Fig. 4. Parameter fitting for the reference amplitude $\alpha_{jk}$.

References