

Should there be "Appendix F"- type Standards and Device Certification for Face Image Capture Devices?

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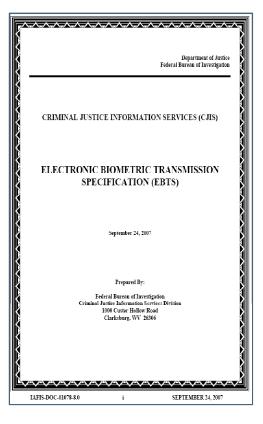
Outline

- What is EBTS Appendix F and what are its metrics?
- What are some equivalent metrics for face images and how could they be measured?
- Examples of such measurements for two cameras
- Conclusions and Recommendations



Appendix F

- Appendix F, *IAFIS Image Quality Specifications*, of the *Electronic Biometric Transmission Specification* (EBTS), Ver. 8, 9/24/2007, prepared by FBI
- "Applies to systems that scan and capture fingerprints ..., including hardcopy scanners such as ten-print card scanners, and live scan devices" ...and fingerprint printers

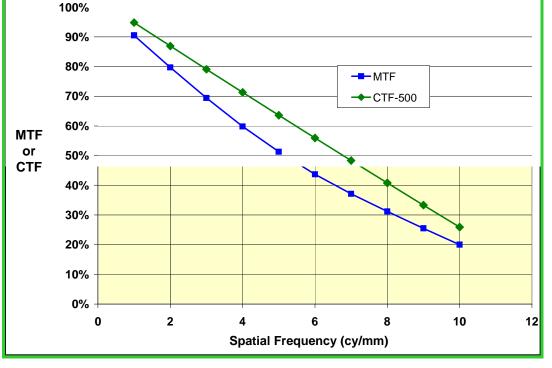


• Scanner "must be capable of producing images that exhibit good geometric fidelity, sharpness, detail rendition, gray-level uniformity, and gray-scale dynamic range, with low noise characteristics."



Appendix F Metrics for FP Scanners

- Output Resolution
- Linearity
- Geometric accuracy
- Spatial Frequency Response (MTF or CTF)
- SNR



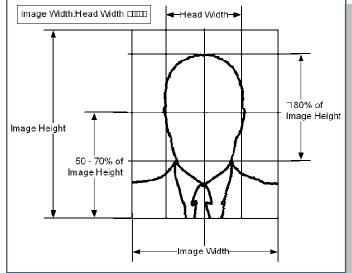
Gray-Level Uniformity



An Appendix F for Faces?

- <u>The challenge</u>: A much more complicated imaging environment for face images
 - Nonuniform or uncontrolled lighting
 - 3-dimensional structure
 - Need for color
 - Uncontrolled backgrounds
 - Variable apertures & exposure times
- Face image interchange standards provide limited guidance (e.g., Full Frontal specs in ISO 19794-5)
 - No saturation (over or under exposure) on the face
 - In focus from nose to ears and chin to crown
 - $\ge 2mm$ spatial resolution (≥ 1 cy/mm, or ≥ 0.5 cy/mm?)
 - No noticeable distortion
 - \geq 7 bits of intensity variation (128 values) in the facial region
 - ≥ 180 pixels for the width of the head
 - should be converted to a defined standard RGB space, such as sRGB

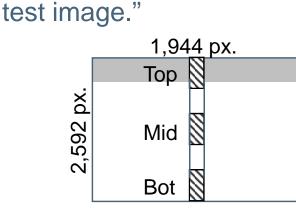




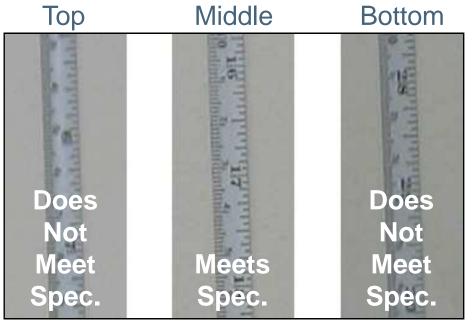
Simple Visual Check of Resolution

ISO 19794-5 A.2.5, Focus and depth of field (Informative)

"Greater than one millimetre resolution will be considered accomplished if the individual millimetre markings of rulers placed on the subject's nose and ear facing the camera can be seen Portions of field of view simultaneously in a captured

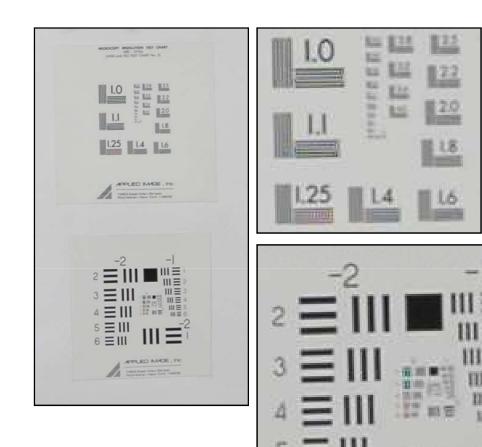


"Point & shoot" digital camera Focal Length: 9.9mm (~ 48 mm equiv.) ISO 50, 1/5 sec, F/4.5 Used in landscape mode Distance to subject: ~ 1.2m (4 ft.) Vertical field of view: ~ 25 inches





Visual Measurement of Resolution



Line pairs per millimeter (each pair consisting of one black bar & one white bar)

Element	Factor	Factor
of Group	(math)	(numerical)
1	2 ⁰	1.00000
2	2 ^{-1/6}	0.89090
3	2 ^{-2/6}	0.79370
4	2 ^{-3/6}	0.70711
5	2-4/6	0.62996
6	2 ^{-5/6}	0.56123



 $\equiv III$

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Calculation of Depth of Field

1/1.8-inch CCD (8.9mm diagonal, 7.2mm width) 2592 x 1944 pixels (~5Mpixels) Focal length (f) = 9.9mm Subject distance (s) = 1.2 m (4 ft.) F Stop (F) = 4.5 Assume diameter of circle of confusion (c) = pixel pitch = 0.00278 mm

$$D_{front} = \frac{cFs(s-f)}{f^2 + cF(s-f)}$$

$$D_{rear} = \frac{cFs(s-f)}{f^2 - cF(s-f)}$$

$$D_{DoF} \cong \frac{2cs^2F}{f^2}$$

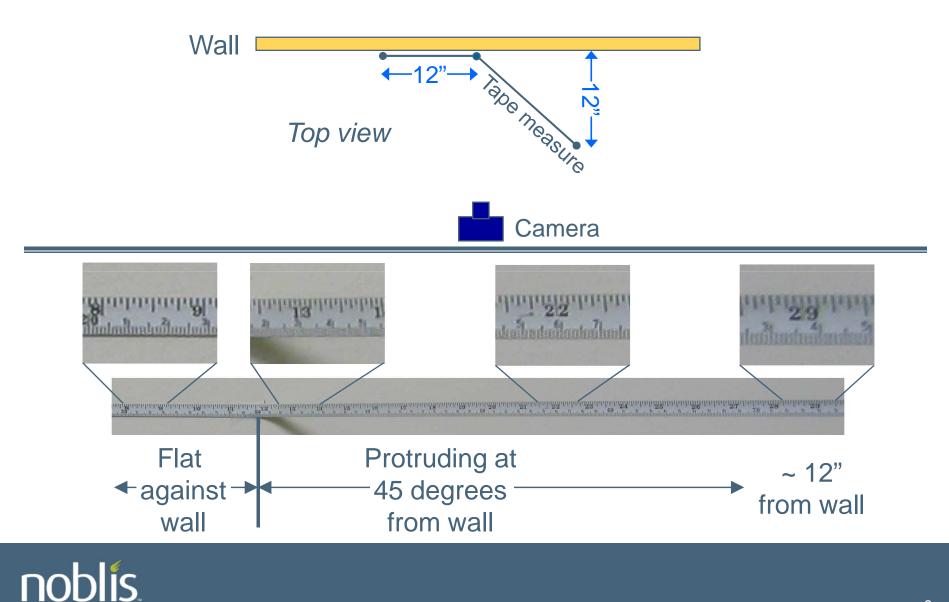
$$D_{DoF} \cong \frac{2cs^2F}{f^2}$$

$$D_{DoF} \cong \frac{14.5''}{16}$$



Simple Measurement of Depth of Field

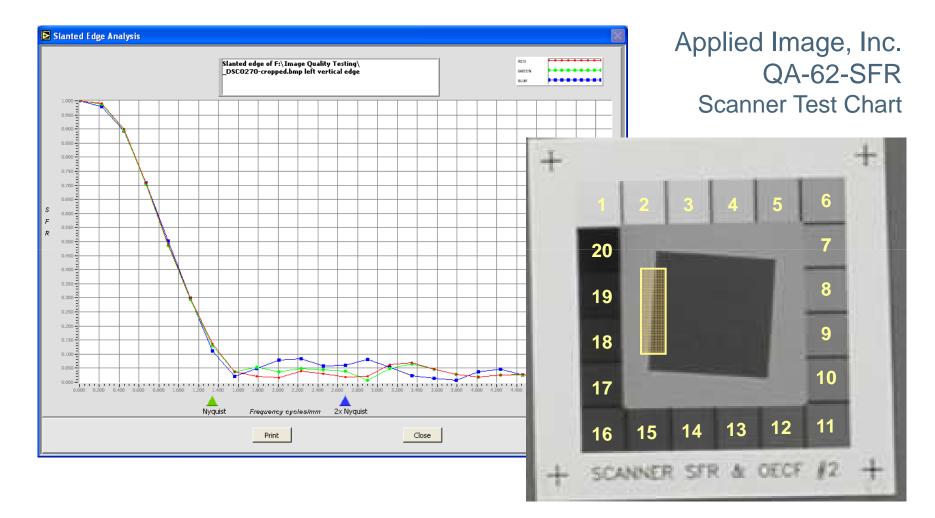
For the best of reasons



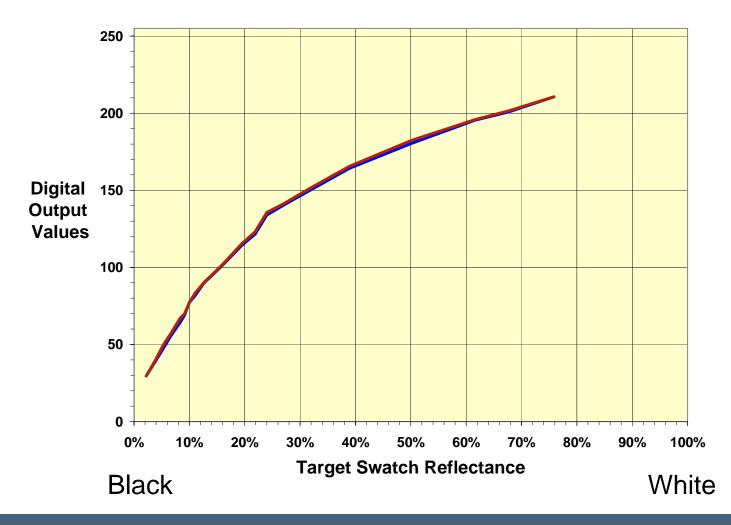
Quantitative Measurement of Resolution: Horizontal SFR for a Digital SLR

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For the best of reasons

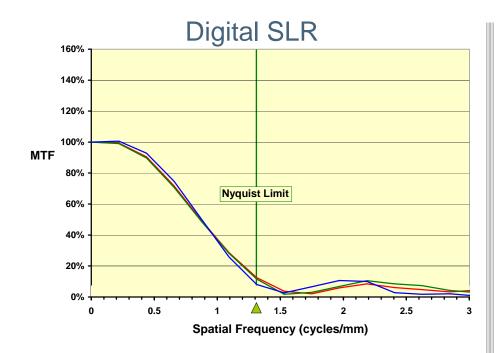


Measured OECFs for a Digital SLR (using Adobe RGB color space)

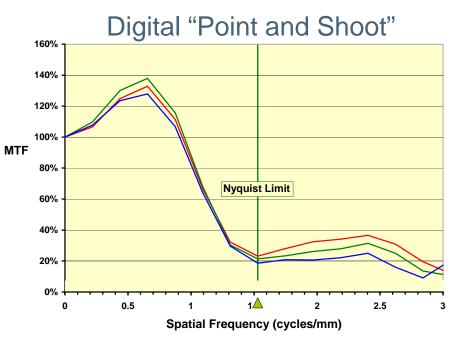




Horizontal SFRs for Two Digital Cameras



Well behaved Moderate drop-off at high frequencies Minimal aliasing expected



Response boosted at intermediate frequencies Some aliasing expected



Red, Green, and Blue Values for the 20 Gray Steps in the QA-62 (for a Digital SLR)

Pat	tch	Red avg.	Grn avg.	Blu avg.	Red stdev	Grn stdev	Blu stdev
	1	210.7	210.7	210.5	1.6	1.4	1.4
	2	201.5	201.5	200.7	1.5	1.2	1.2
	3	196.0	196.0	195.5	1.6	1.2	1.2
	4	182.3	182.3	180.4	1.2	1.1	1.1
	5	165.5	165.5	164.2	1.7	1.2	1.2
	6	151.1	151.1	149.7	1.8	1.5	1.5
	7	141.0	141.0	140.1	1.7	1.3	1.3
	8	135.6	135.7	133.9	2.0	1.5	1.4
	9	123.1	123.1	121.5	1.7	1.5	1.5
	10	115.5	115.5	114.5	2.1	1.4	1.4
	11	101.3	101.3	100.8	1.7	1.4	1.4
	12	90.1	90.1	89.8	2.1	1.8	1.8
	13	82.9	82.9	81.4	1.6	1.2	1.1
	14	77.3	77.3	77.3	1.4	1.4	1.4
	15	70.0	70.0	69.0	1.4	1.1	1.1
	16	66.7	67.1	64.2	2.6	1.6	1.7
	17	56.9	57.0	55.4	1.8	1.4	1.4
	18	49.2	49.5	47.3	2.0	1.9	1.7
	19	39.6	39.6	38.8	1.9	1.3	1.3
	20	29.5	29.5	29.5	1.8	1.6	1.6

Camera was carefully white balanced R, G, and B values are almost identical for all patches Standard deviations are quite low

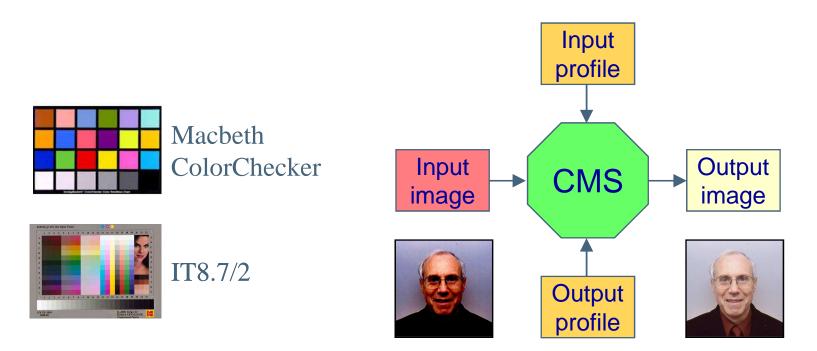


Color Channel Misregistration (in pixels) for Two Digital Cameras

Left Vertical Edge		Digital SLR		Point & Shoot	
Red	Transition	Red Green	Green Blue	Red Green	Green Blue
	Left Vertical	0.01254	-0.11959	0.26206	-0.15877
Green	Right Vertical	0.03471	0.12691	-0.08028	0.48164
Blue	Lower Horizontal	0.07711	0.08563	0.30137	0.26658
	Upper Horizontal	0.01735	0.05052	0.04387	-0.05623



Color Measurement



Color error can be measured in Lab space

$$\Delta E = \sqrt{(\Delta L)^2 + (\Delta a)^2 + (\Delta b)^2}$$



Potential Face Camera Metrics

- Sampling frequency (ppi) and geometric distortion
- Quantization (bpp)

OECF (Capture γ and exposure accuracy) - ISO 14524

Spatial resolution (MTF) and depth of field - ISO 12233 and ISO 16067-1

Channel registration and color accuracy

- v Noise (S:N) ISO 15739 and uniformity
- v Dynamic range
- v Vignetting & flare



Conclusions and a Recommendation

- qMegapixel digital still cameras and some video cameras can
produce face images compliant with ISO 19794-5
- qHowever, camera specifications for face capture are needed to
ensure high quality
- qAn Appendix F-like set of specifications for face image capture
can be written and should be based upon existing ISO standards
- qSpecifications for lighting and the capture environment are
important and should be developed separately
- Government agencies using or considering the use of face recognition should be involved in the development of camera specifications
- However, a camera certification program does not seem feasible
 too many camera makes and models; newer models replace
 previous versions every few months

