

## RoboCupRescue Robot League Competition Padua, Italy July 4-11, 2003

## PARTICIPANT INFORMATION SHEET

TEAM NAME:	ORGANIZATION:
UvA Flying Rescue 2003	Universiteit van Amsterdam
CONTACT NAME:	COUNTRY:
Arnoud Visser	the Netherlands
TOTAL NUMBER OF TEAM PERSONNEL:	EMAIL:
2	arnoud@science.uva.nl
ROBOT NAMES:	TELEPHONE:
Dummy	+31 20 525 7532
WIRELESS FREQUENCIES (PER ROBOT):	FAX NUMBER:
27 Mhz range	+31 20 525 7490
□ PRE-REGISTERED □ REGISTERED	$\Box$ Arrived on site $\Box$ competition ready

TEAM DESCRIIPTION (WITH EMBEDDED PICTURES):

Locomotion: floating



Plantraco Turbofan Airship.

Sensors used for navigation: visual

Sensors used for victim identification: visual

Control scheme: teleoperation

Our participation is just a proof of concept before we start a project to full autonomy

## Communications:

one of the following 4 channels.

Channel A = 26.995 MHz Channel B = 27.095 MHz Channel C = 27.195 MHz Channel D = 27.255 MHz

The R/C system is low power and approved globally.

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