Section Outline

- 1. Non-Constant Variation
- 2. Outliers

Non-constant variation across the levels of the predictor variables violates one of the usual assumptions of least squares regression.

However non-constant variation is often found in data used for building regression models as an inherent part of the measurement or other type of process.

Because non-constant variation is frequently encountered, techniques to improve the validity of the standard assumptions and techniques based on alternative assumptions have been developed to lessen the impact of this problem.

Effect of Non-Constant Standard Deviation on Function Fitting

If all of the other assumptions for the analysis are met, except for constant standard deviation across all combinations of the predictors, the usual parameter estimates will still be correct on average, or unbiased.

However, the deviation of the fitted function from the true function will be larger, on average, than that from other techniques, unlike the case of constant standard deviation.

Effect of Non-Constant Standard Deviation on Function Fitting

The least squares estimates are found by minimizing the sum of the squared differences of the predicted values and the observed y's, Q, to find the $\hat{\beta}$'s.

$$Q = \sum_{i=1}^{n} [y_i - f(x_{1i}, x_{2i}, \dots, x_{ki}; \hat{\beta}_1, \hat{\beta}_2, \dots, \hat{\beta}_p)]^2$$

All deviations count the same using the LSS fitting criterion, even if the variation differs across the data.

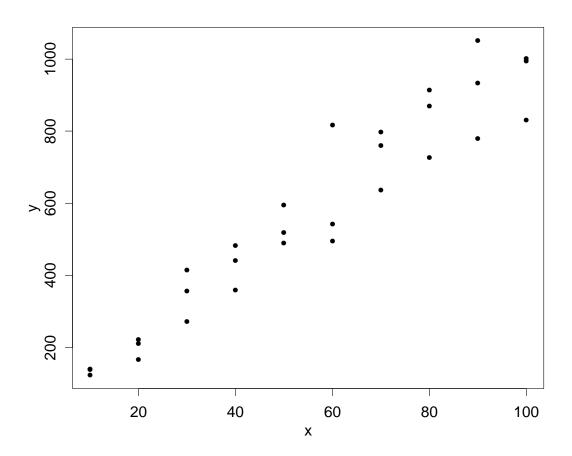
However, where the variation is larger, the deviations of the data from their corresponding means will also be larger, indicating that the regression function should not be constrained to be as near that data as it is to data that varies less.

Effect of Non-Constant Standard Deviation on Prediction

In addition to increasing the variance of estimating the regression function, non-constant standard deviation impacts the uncertainty of predictions, if unaccounted for.

Predictions made where variation is relatively low, will tend to have larger stated uncertainties than necessary. Predictions made where uncertainty is relatively large will have smaller stated uncertainties than necessary.

Heteroscedastic Data

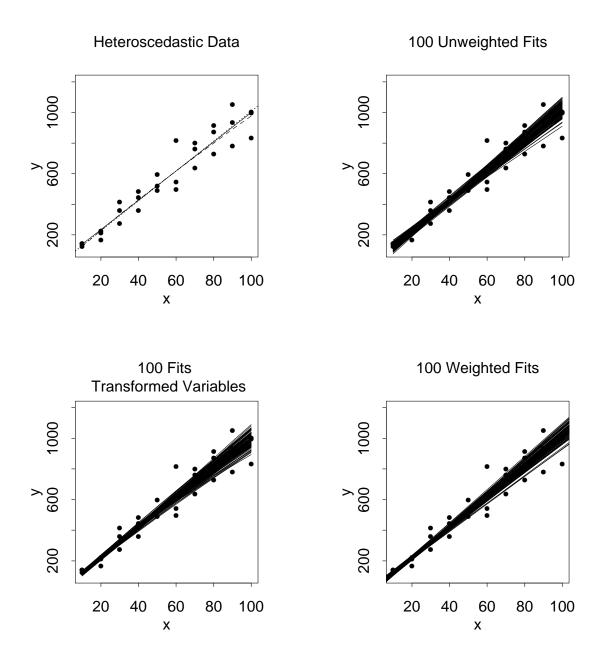


Improved Fitting Methods

There are basically two approaches to getting improved parameter estimates for data with non-constant standard deviations:

- 1. transformation of the data so it meets the standard assumptions, and
- 2. use of weights in parameter estimation to account for the unequal standard deviations.

Comparison of Fitting Procedures for Data with Non-Constant Variation



Transformations

The basic steps for using transformations to handle data with unequal subpopulation standard deviations are:

- 1. Transform the response variable to equalize the variation across the levels of the predictor variables
- 2. Transform the predictor variables if necessary to attain or restore a simple functional form for the regression function.
- 3. Fit and validate the model in the transformed variables.
- 4. Transform the function back into the original units, if necessary, using the inverse of the transformation originally applied to the response variable.

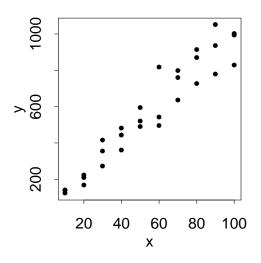
Transformations

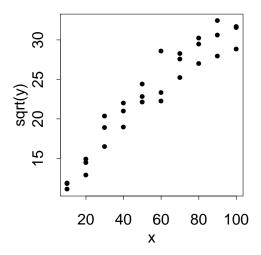
Appropriate transformations to stabilize the variability may be suggested by scientific knowledge or selected using the data.

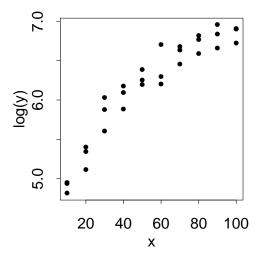
Three transformations that are often effective is equalizing the standard deviations across the values of the predictor are:

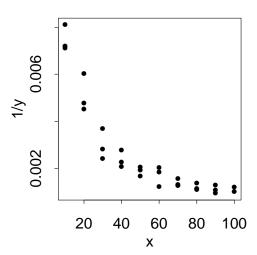
- 1. \sqrt{y}
- $2.\log(y)$, and
- 3. 1/y.

Data in the Original Units and 3 Basic Tranformations of the Response Variable

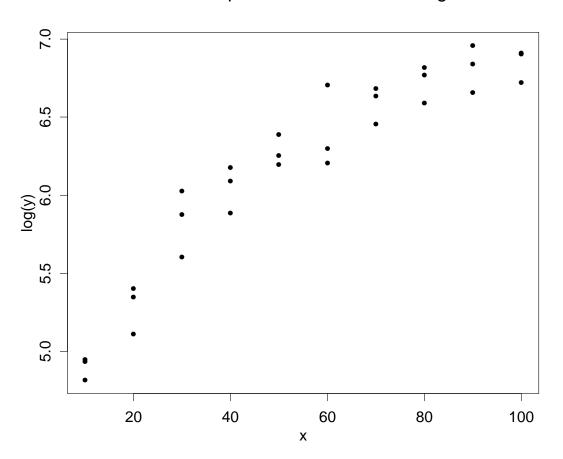




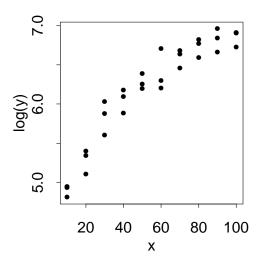


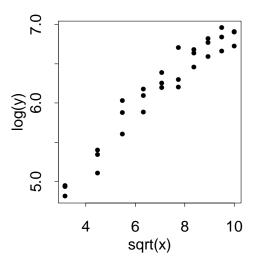


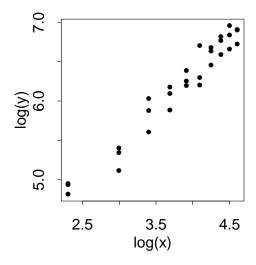
Transformed Response vs Predictor in Original Units

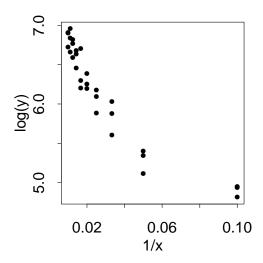


Transformed Response vs Basic Tranformations of the Predictor Variable

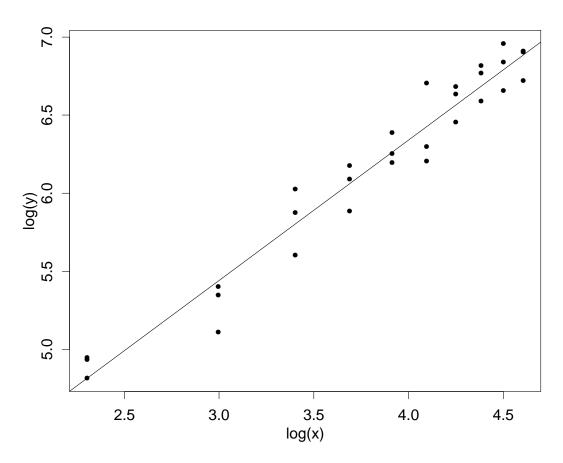






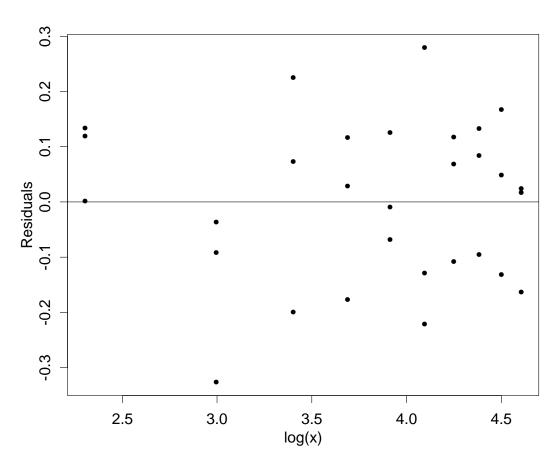


Transformed Response vs Transformed Predictor

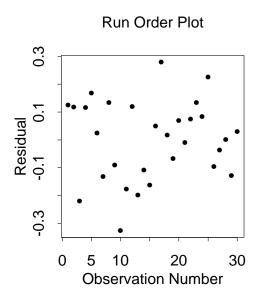


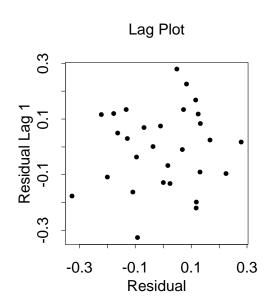
Residuals From Fit to Transformed Variables

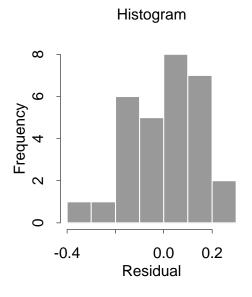
121

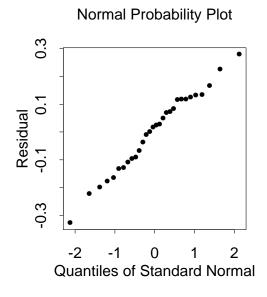


Residuals From Fit to Transformed Variables









Weighted Least Squares

Weighted least squares estimates are found by minimizing:

$$Q = \sum_{i=1}^{n} w_i [y_i - f(x_{1i}, x_{2i}, \dots, x_{ki}; \hat{\beta}_1, \hat{\beta}_2, \dots, \hat{\beta}_p)]^2$$

where

$$w_i \propto \frac{1}{\sigma_i^2}$$

These relative weights give optimal results, when known.

Weighted Least Squares

Unfortunately the true weights are rarely known, so they have to be estimated.

The obvious way to estimate the w_i , if there are replicates in the data, is

$$w_i = \frac{1}{\hat{\sigma}_i^2} = \frac{1}{s_i^2} = \left[\frac{\sum_{i=1}^{n_i} (y_{ij} - \bar{y}_i)^2}{n_i - 1}\right]^{-1}$$

for the i^{th} set of replicates in the data set.

However, this rarely works well because the weights are extremely variable when estimate this way.

Weighted Least Squares

A better strategy for estimating the weights is to find a function which relates s_i^2 to x_i .

If

$$s_i^2 \propto f(x_{1i}, x_{2i}, \dots, x_{ki})$$

then use

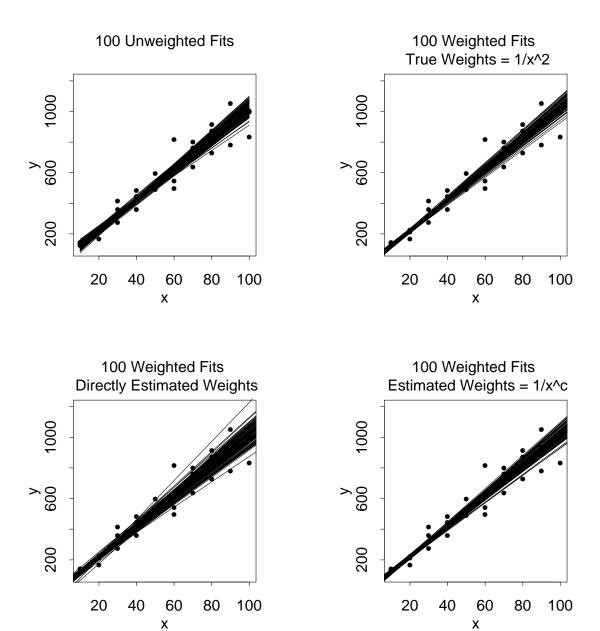
$$w_i = \frac{1}{f(x_{1i}, x_{2i}, \dots, x_{ki})}$$

as the weights.

One model that *often* works well for modeling the variances is

$$s_i^2 \propto x_i^c$$

Comparison of Weighting Procedures for Data with Non-Constant Variation



Estimation of the Weights - Replicates Available

To estimate the weights using the power function shown above, fit the function

$$\log(s_i^2) = \beta_1 + \beta_2 \log(x_i)$$

to the variances from each set of replicates in the data.

The use $\hat{c} = \hat{\beta}_2$ (the slope of the fit) to estimate c, and

$$w_i = \frac{1}{x_i^{\hat{c}}}$$

to as the weights.

Check the residuals from the fit used to estimate c just to make sure everything looks reasonable. The fit does not have to meet the standards usually used, however.

Estimation of the Weights - No Replicates Available

If there are few or no replicates in the data, divide the data into several ranges in which the responses have fairly similar means.

Treat each range as replicates and compute $\bar{x_i}$ and s_i^2 for each range.

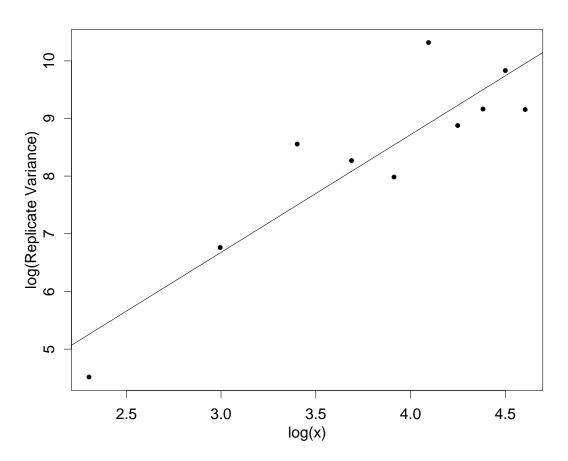
Then fit

$$\log(s_i^2) = \beta_1 + \beta_2 \log(\bar{x}_i)$$

and define the weights by

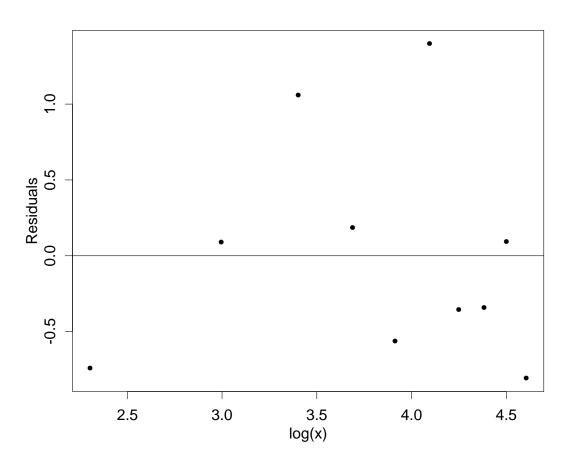
$$w_i = \frac{1}{x_i^{\hat{\beta}_2}}$$

Estimation of the Weights



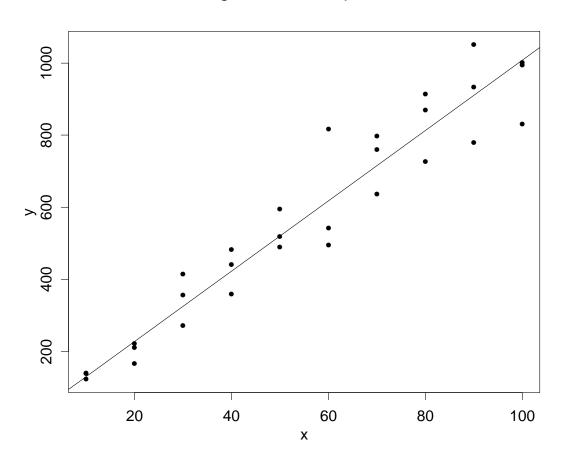
Output from Fit for Weight Estimation

Residuals from Estimation of Weights



Weighted Least Squares Fit

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Weighted Residuals

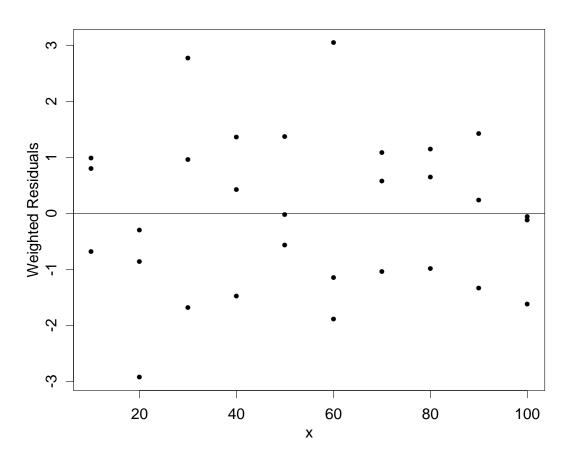
One complication with weighted analyses is the fact that the distribution of the residuals can vary substantially with the different values of the predictor variables.

This necessitates the use of weighted residuals when plotting residuals.

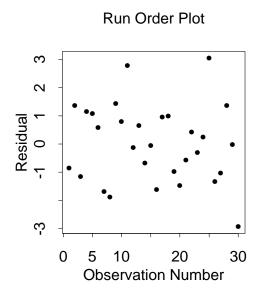
The weighted residuals are given by

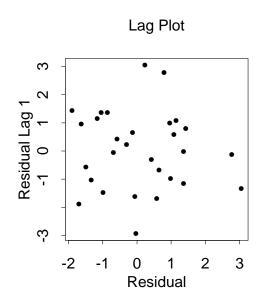
$$e_i = \sqrt{w_i}(y_i - f(x_{1i}, \dots, x_{ki}; \hat{\beta}_1, \dots, \hat{\beta}_p))$$

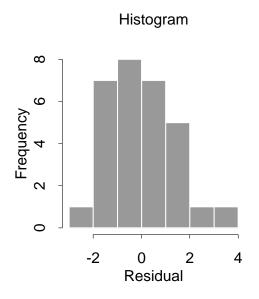
Weighted Residuals From WLS Fit with Weights 1/x^2.04

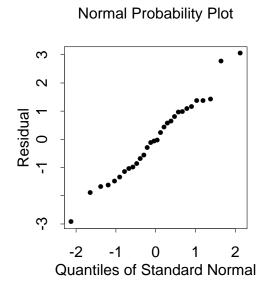


Weighted Residuals From WLS Fit with Weights 1/x^2.04

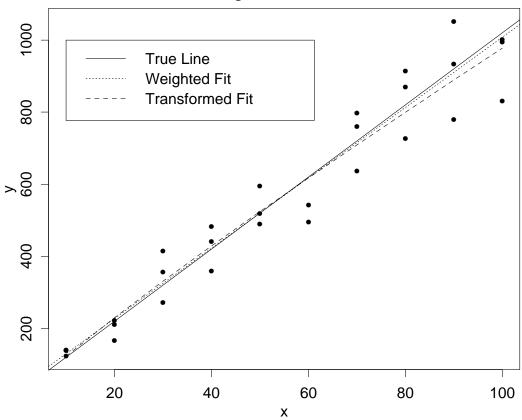


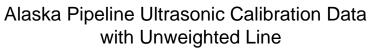


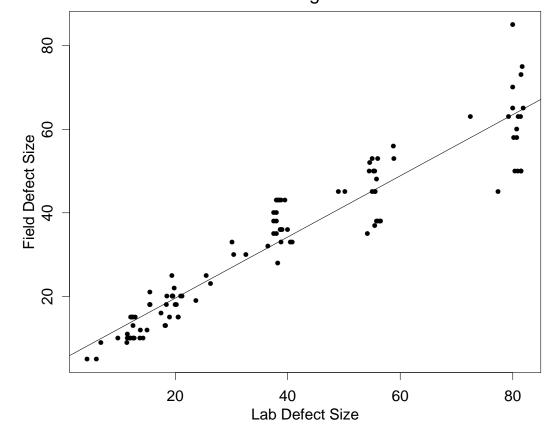




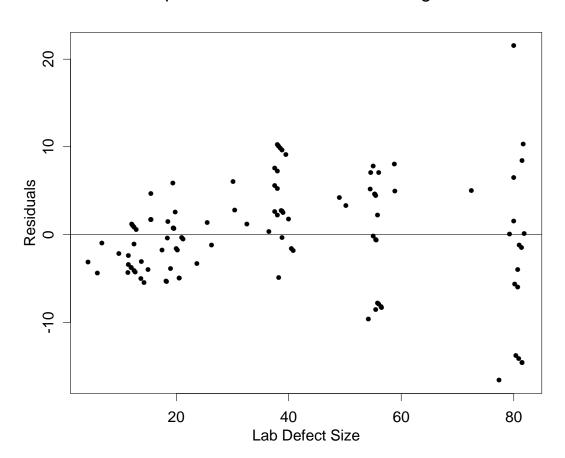
Data with True Line, WLS Fit, and Fit Using Transformed Variables







AK Pipeline Data Residuals - Unweighted Fit



AK Pipeline Data Output from Unweighted Fit

N = 107

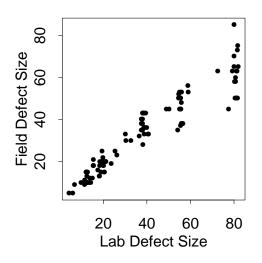
Residual Standard Error = 6.080924

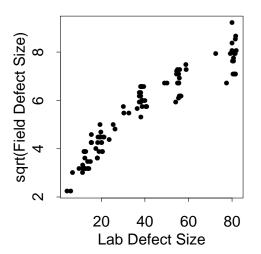
Multiple R-Square = 0.8941251

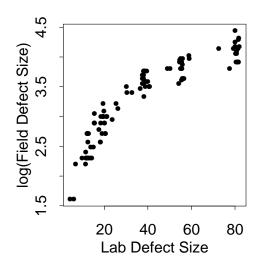
F-statistic = 886.7366 on 1 and 105 df, p-value = 0

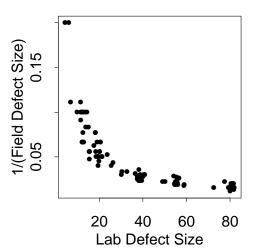
coef std.err t.stat p.value Intercept 4.9936799 1.12565780 4.436233 2.263517e-05 X 0.7311111 0.02455195 29.778123 0.000000e+00

Transformations of Response Variable

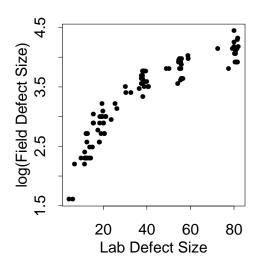


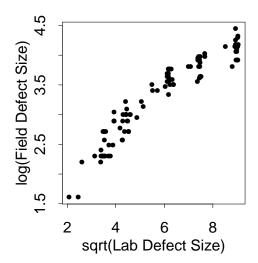


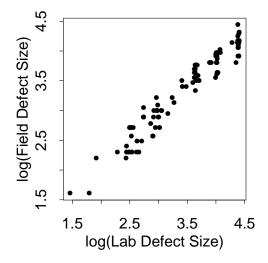


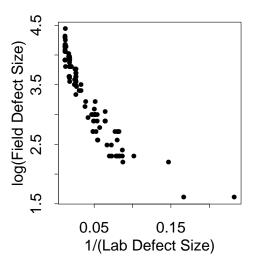


Transformations of Predictor Variable

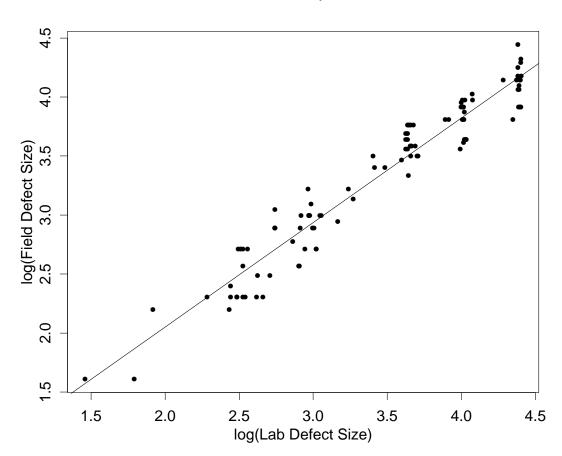




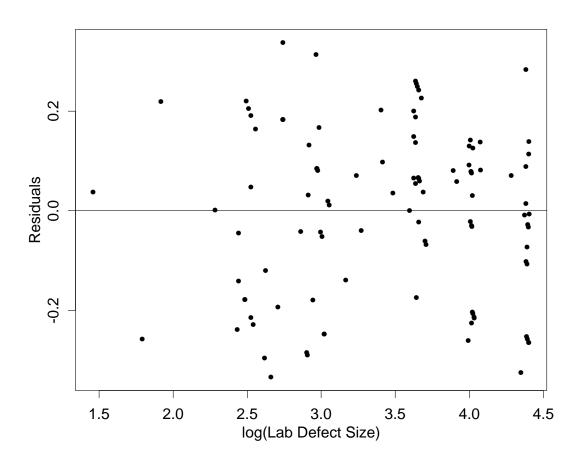


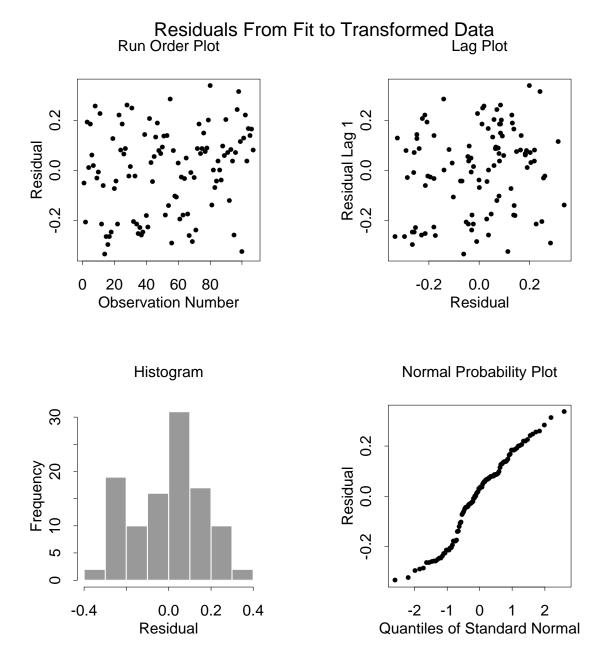


Transformed Alaska Pipeline Data with Fit



Residuals From Fit to Transformed Data





AK Pipeline Data Output from Fit on Transformed Variables

N = 107

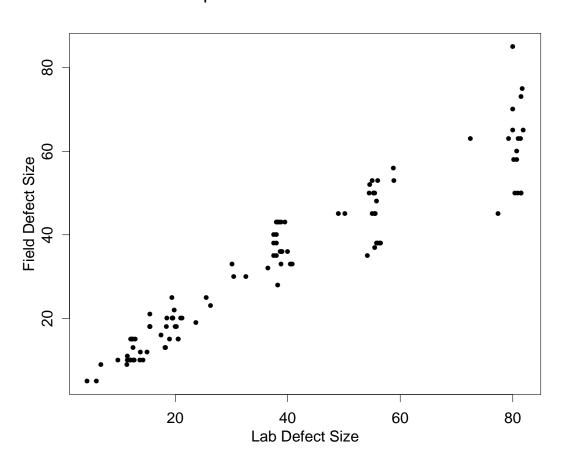
Residual Standard Error = 0.1682604

Multiple R-Square = 0.9337104

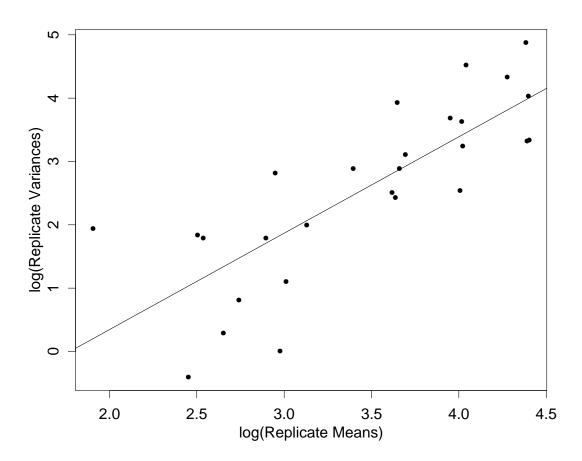
F-statistic = 1478.958 on 1 and 105 df, p-value = 0

coef std.err t.stat p.value
Intercept 0.2813838 0.08092894 3.476924 0.0007390395
X 0.8851754 0.02301714 38.457221 0.0000000000

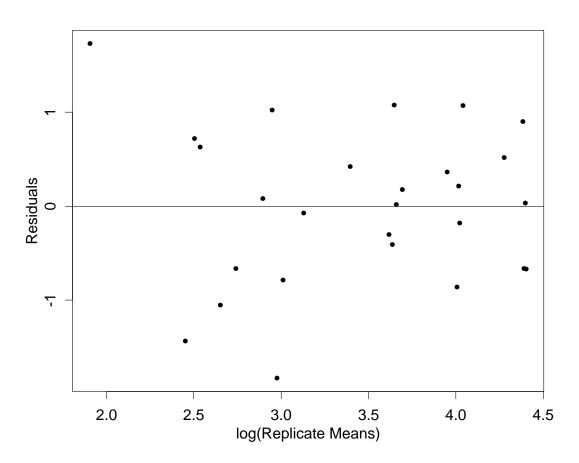
Alaska Pipeline Ultrasonic Calibration Data



Fit for Estimating Weights



Residuals From Weight Estimation Fit



AK Pipeline Data Output from Weight Estimation Fit

N = 27

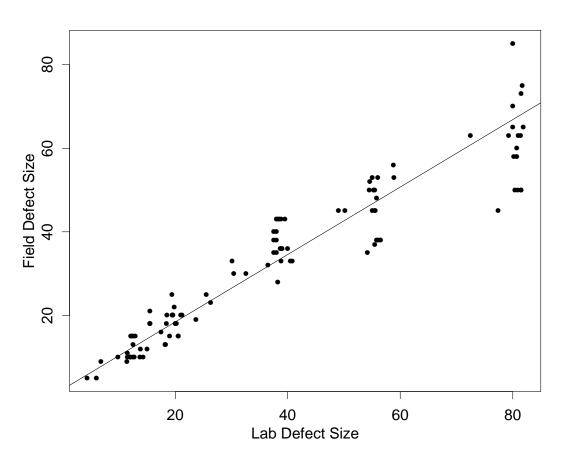
Residual Standard Error = 0.8545392

Multiple R-Square = 0.6286482

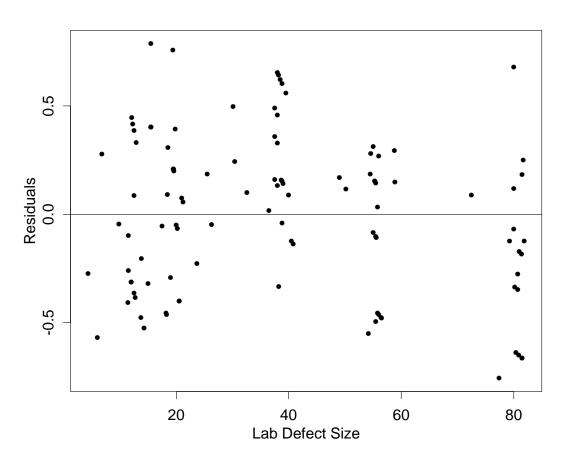
F-statistic = 42.32161 on 1 and 25 df, p-value = 8.178602e-07

coef std.err t.stat p.value Intercept -2.696496 0.8250090 -3.268444 3.140569e-03 X 1.522101 0.2339712 6.505506 8.178602e-07

Data with WLS Fit - Weights 1/LDS^1.5



Weighted Residuals From WLS Fit to Original Data



Weighted Residuals From WLS Fit Run Order Plot Lag Plot 0.5 0.5 Residual Lag 1 -0.5 0.0 0. Residual 0.0 -0.5 20 40 60 80 -0.5 0.0 0.5 0 **Observation Number** Residual Histogram Normal Probability Plot 25 0.5 20 Frequency Residual 0.0 15 10 -0.5 2 0 0.0 Residual -0.5 -2 -1 0 1 2 Quantiles of Standard Normal 0.5

AK Pipeline Data Output from Weighted Fit

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N = 107

Residual Standard Error = 0.3646

Multiple R-Square = 0.9235

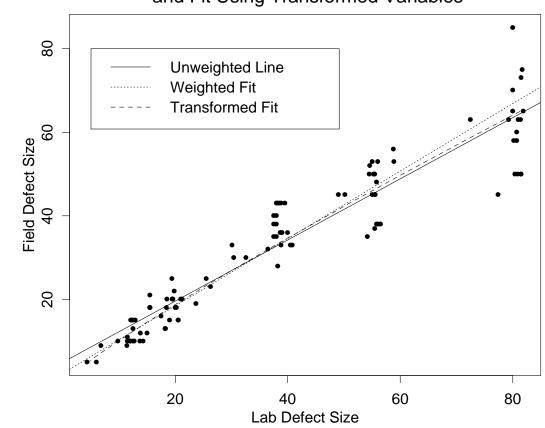
F-statistic = 1267.024 on 1 and 105 df, p-value = 0

coef std.err t.stat p.value

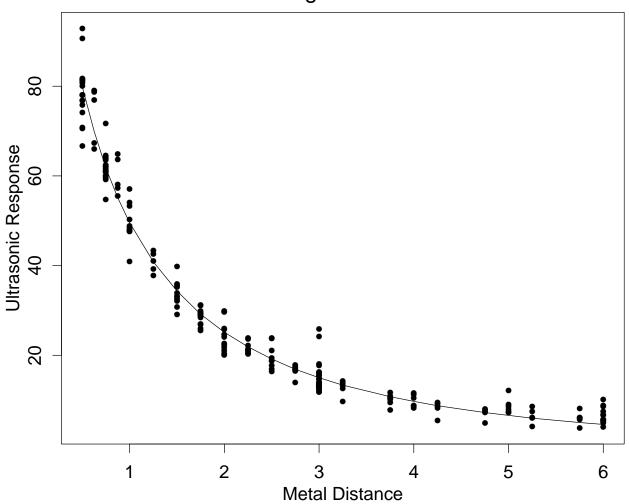
Intercept 2.3523 0.5431 4.3312 0

X 0.8064 0.0227 35.5953 0

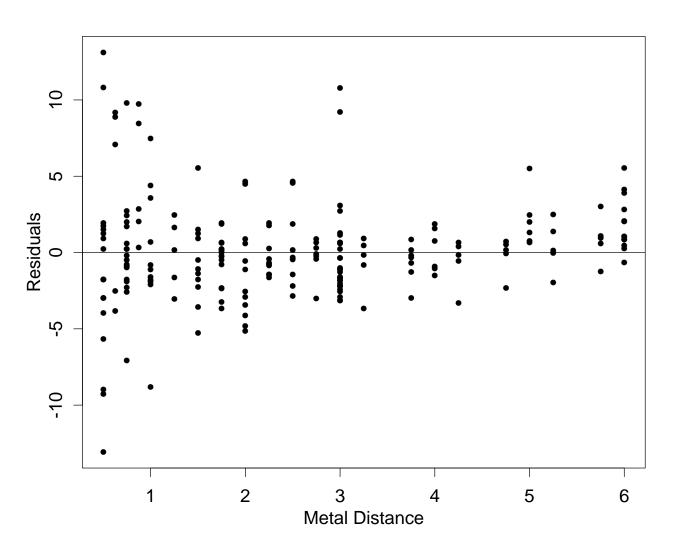
Data with Unweighted Line, WLS Fit, and Fit Using Transformed Variables



Ultrasonic Calibration Data with Unweighted Nonlinear Fit



Ultrasonic Calibration Data Residuals - Unweighted Fit



Ultrasonic Calibration Data Output from Unweighted Exp/Linear Fit

Parameters:

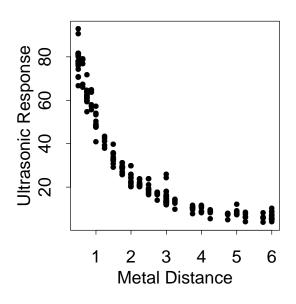
Value Std. Error t value b1 0.19027400 0.021938300 8.67312 b2 0.00613137 0.000345001 17.77200 b3 0.01053100 0.000792818 13.28300

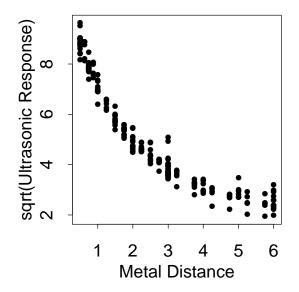
Residual standard error: 3.36167 on 211 degrees of freedom

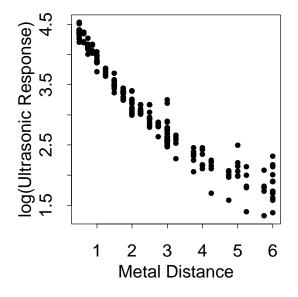
Correlation of Parameter Estimates:

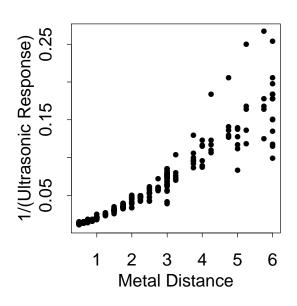
b1 b2 b2 0.839 b3 -0.950 -0.949

Transformations of Response Variable

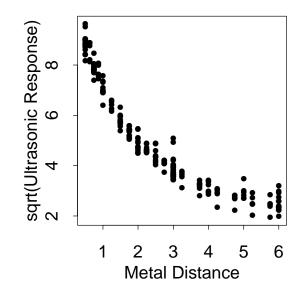


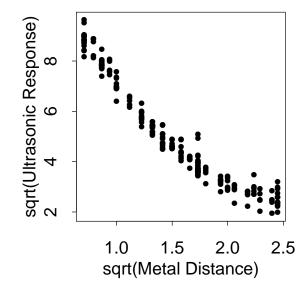


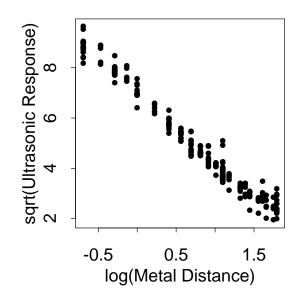


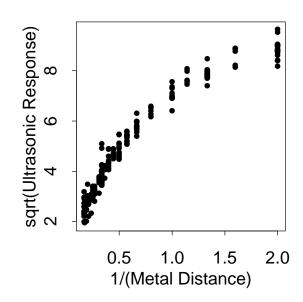


Transformations of Predictor Variable

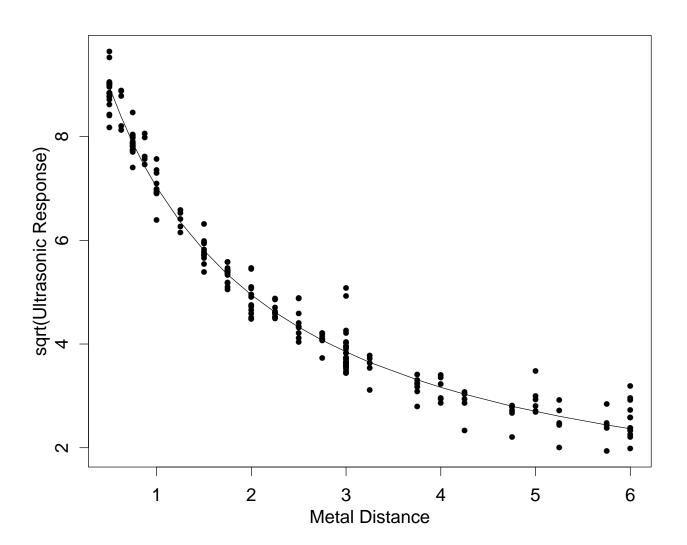




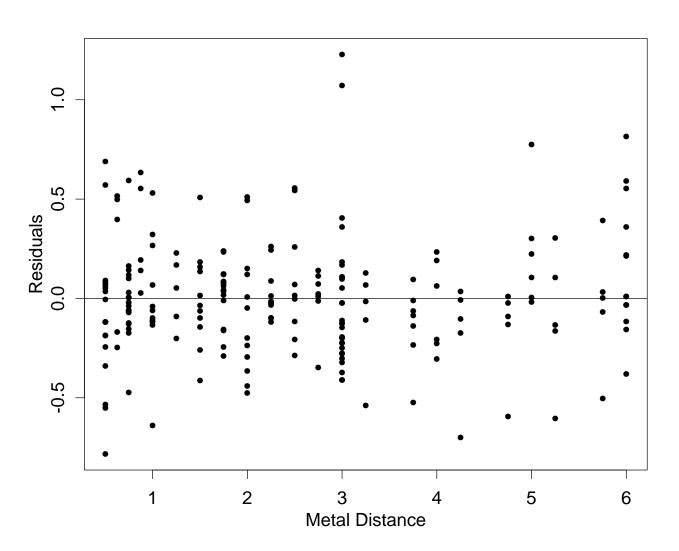


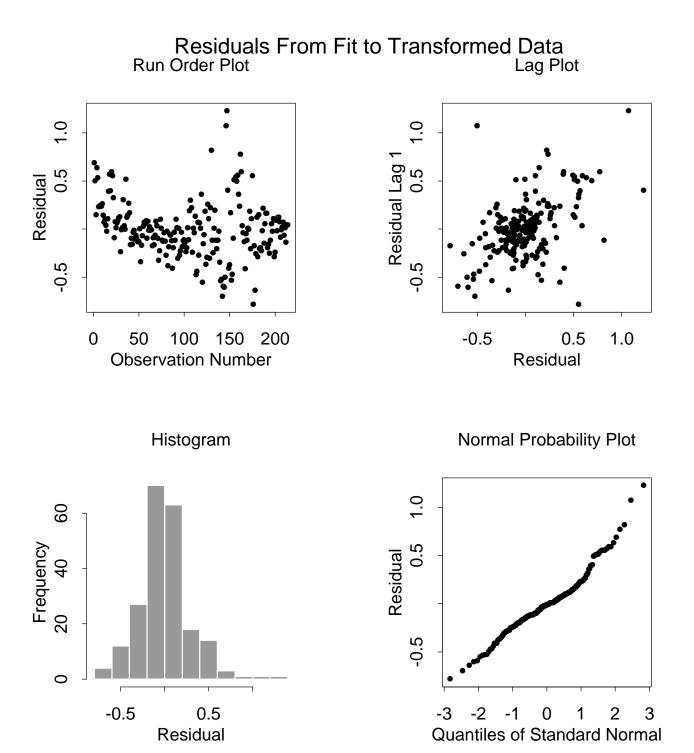


Transformed Data with Fit



Residuals From Fit to Transformed Data





Ultrasonic Calibration Data Output from Fit to Transformed Data

Parameters:

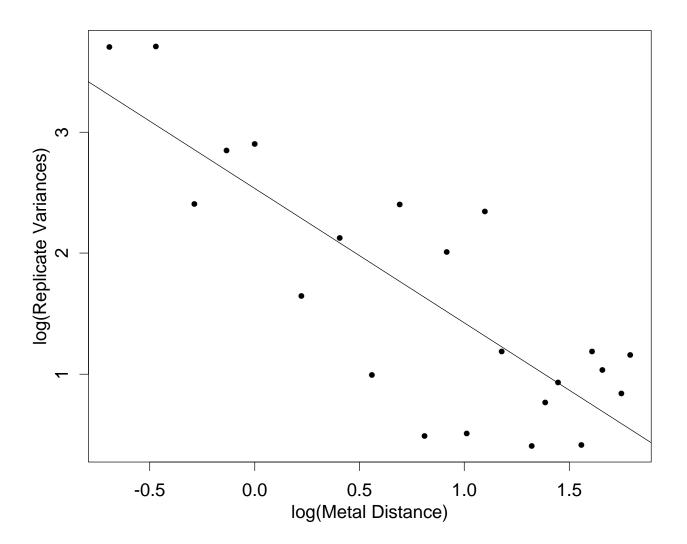
```
Value Std. Error t value
b1 -0.0154274 0.00861101 -1.79159
b2 0.0806725 0.00150574 53.57670
b3 0.0638570 0.00288001 22.17250
```

Residual standard error: 0.29715 on 211 degrees of freedom

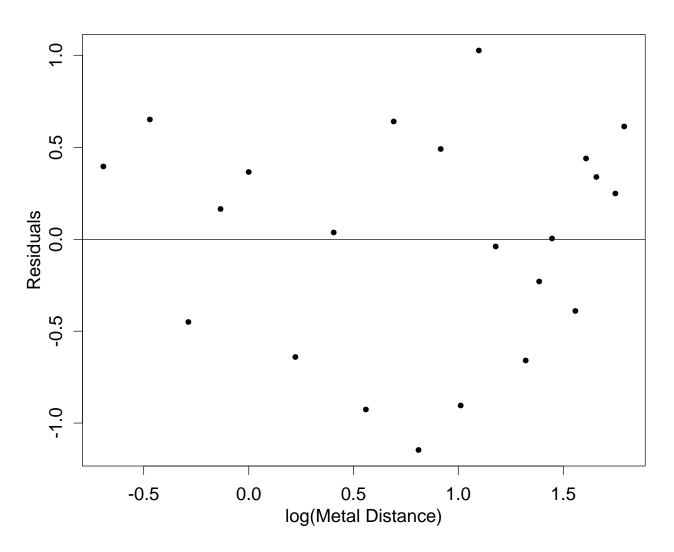
Correlation of Parameter Estimates:

b1 b2 b2 0.793 b3 -0.960 -0.899

Fit for Estimating Weights



Residuals From Weight Estimation Fit



Ultrasonic Calibration Data Output from Weight Estimation Fit

N = 22

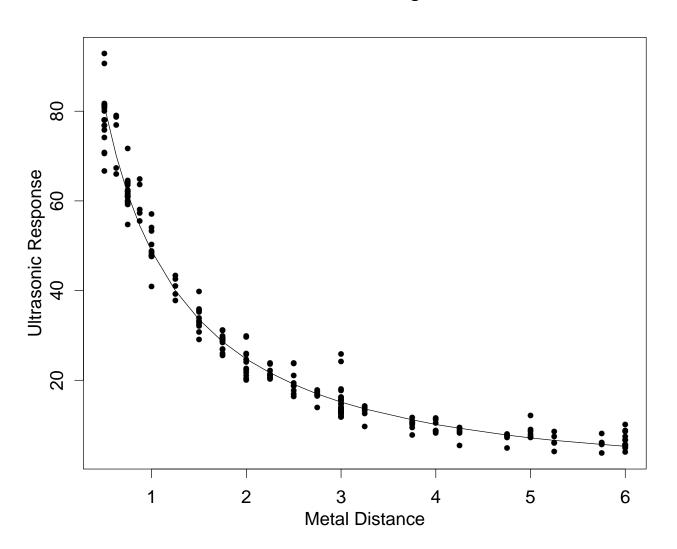
Residual Standard Error = 0.6099457

Multiple R-Square = 0.6712342

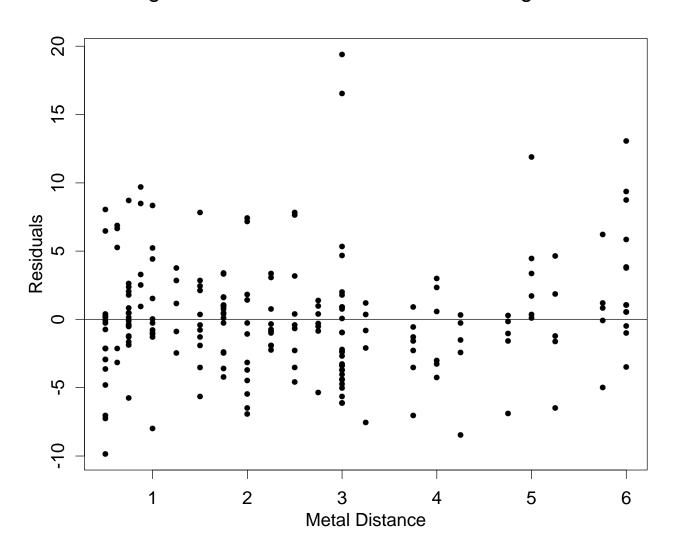
F-statistic = 40.83357 on 1 and 20 df, p-value = 3.10602e-06

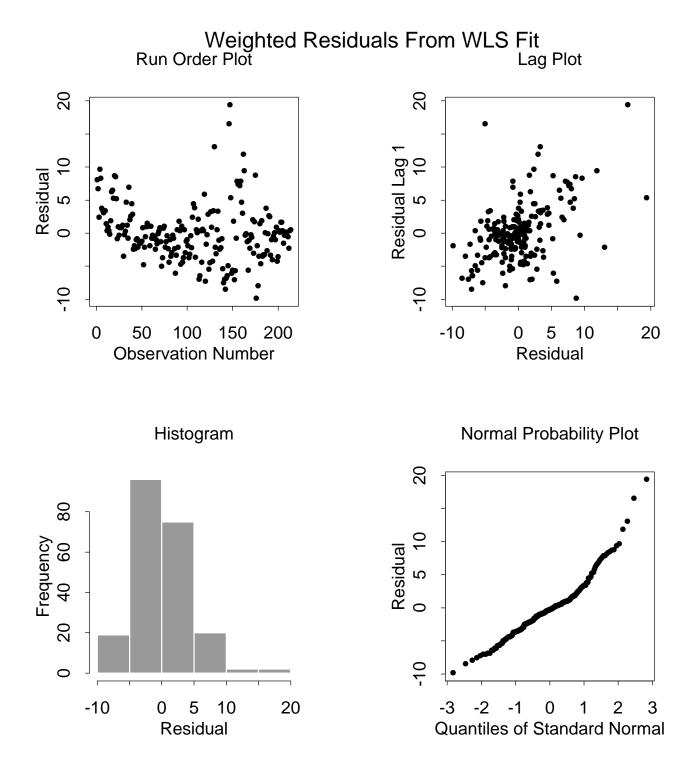
coef std.err t.stat p.value Intercept 2.536866 0.1919360 13.217253 2.421219e-11 X -1.112763 0.1741382 -6.390115 3.106020e-06

Data with WLS Fit - Weights 1/MD^-1.1



Weighted Residuals From WLS Fit to Original Data





Ultrasonic Calibration Data Output from Weighted Fit

```
LEAST SQUARES NON-LINEAR FIT

SAMPLE SIZE N = 214

MODEL--Y =EXP(-B1*X)/(B2+B3*X)

REPLICATION CASE

REPLICATION STANDARD DEVIATION = 0.3281762600D+01

REPLICATION DEGREES OF FREEDOM = 192

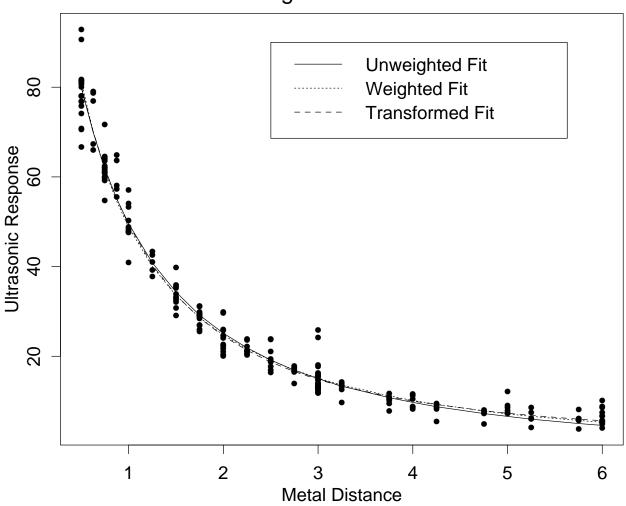
NUMBER OF DISTINCT SUBSETS = 22
```

FINAL PARAMETER

		ESTIMATES	(APPROX. ST. DEV.)	T	VALUE
1	B1	0.143378	(0.1476E-01)		9.7
2	B2	0.518479E-02	(0.4191E-03)		12.
3	В3	0.125719E-01	(0.7508E-03)		17.

```
RESIDUAL STANDARD DEVIATION = 4.2653684616
RESIDUAL DEGREES OF FREEDOM = 211
REPLICATION STANDARD DEVIATION = 3.2817625999
REPLICATION DEGREES OF FREEDOM = 192
LACK OF FIT F RATIO = 8.6545 = THE 100.0000% POINT OF THE F DISTRIBUTION WITH 19 AND 192 DEGREES OF FREEDOM
```

Data with Unweighted Fit, WLS Fit, and Fit Using Transformed Variables



Outliers

In a broad sense, outliers are points that do not follow the general pattern or structure in the data.

If present in the data, outliers can unduly affect the model-building process and invalidate predictions or calibrations.

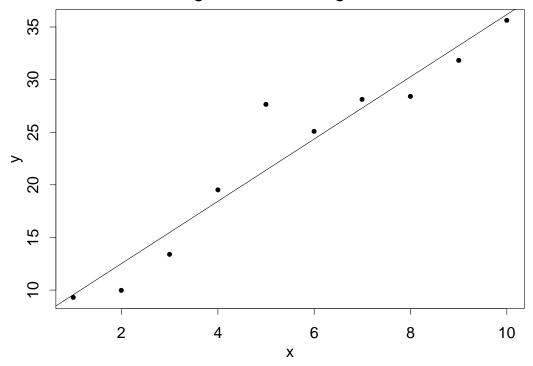
More Specifically . . .

outlier - an observed value of the response variable that appears to be unusually large or small relative to its apparent population.

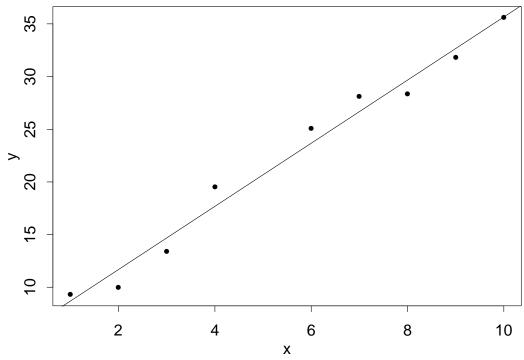
- high leverage point a point from the observed set of predictor variables that is unusual in size or structure relative to the other predictor variable points.
- influential observation an observation that has a large effect on the model derived from the data.

Note: Not all outliers or high leverage points are influential observations.

Dataset with an Outlier and a Straight Line Fit Using All n Points



Dataset with an Outlier and a Straight Line Fit Without the Outlier

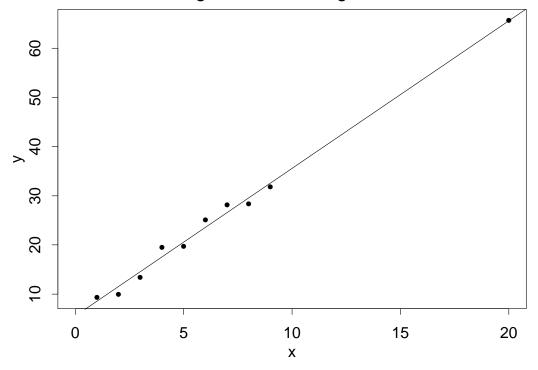


Regression Output for Data with Outlier

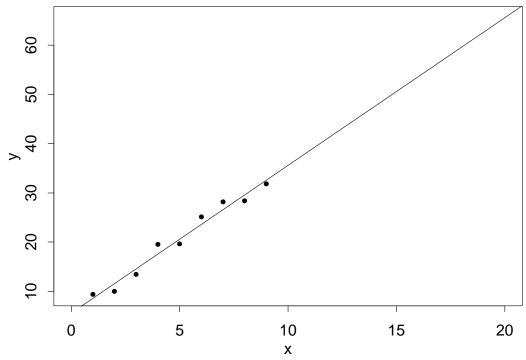
Regression Output for Data with Outlier Omitted

Outliers Outliers

Dataset with a High Leverage Point and a Straight Line Fit Using All n Points



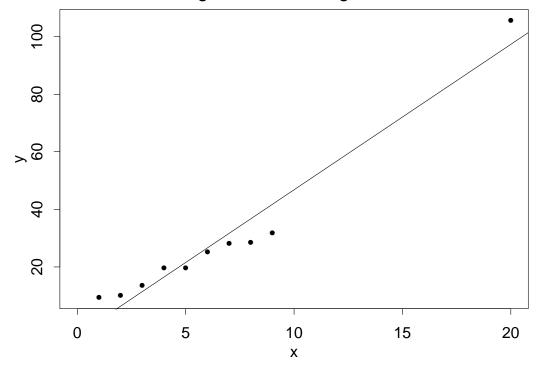
Dataset with a High Leverage Point and a Straight Line Fit Without the HL Point



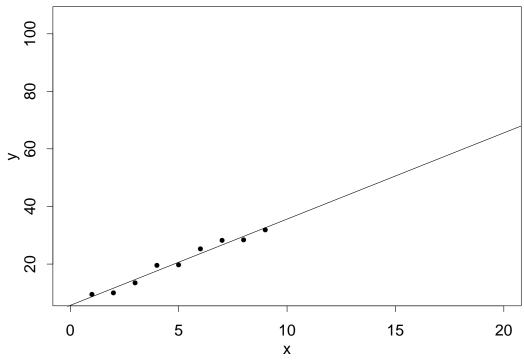
Regression Output for Data with Leverage Point

Regression Output for Data with LP Omitted

Dataset with an Influential Point and a Straight Line Fit Using All n Points



Dataset with an Influential Point and a Straight Line Fit Without the Inf. Point



Regression Output for Data with Influential Point

Regression Output for Data with IP Omitted

Why Outliers Affect LS Regression

As we've seen before, the least squares estimates are found by minimizing the quantity Q to find the $\hat{\beta}$'s.

$$Q = \sum_{i=1}^{n} [y_i - f(x_{1i}, x_{2i}, \dots, x_{ki}; \hat{\beta}_1, \hat{\beta}_2, \dots, \hat{\beta}_p)]^2$$

However, when a few deviations are much larger than the rest (in absolute value), and all of the deviations are squared and added up, the few large deviations tend to dominate the total.

As a result, the values of the $\hat{\beta}$'s that minimize of the least squares criterion are often the values that eliminate large deviations from the model.

Why Outliers Affect LS Regression

The LSS estimates for the straight line regression function $y = \beta_1 + \beta_2 x$ show in detail how both outliers and high leverage points affect the parameter estimates.

$$\hat{\beta}_2 = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2}$$

$$\hat{\beta}_1 = \bar{y} - \hat{\beta}_2 \bar{x}$$

 $\hat{\beta}_2$ is a linear combination of the deviations of the data points, y_i , from their sample mean, \bar{y} , 'weighted' proportional to the deviation of x_i from \bar{x} . Large values of either $(x_i - \bar{x})$ or $(y_i - \bar{y})$ will impact the estimates of both β_1 and β_2 .

The effects of leverage points and outliers are analogous in more complicated models.

Outliers Outliers

General Steps for Handling Outliers

The basic steps for dealing with outliers in regression analysis are:

- 1. identify the outlying and influential points
- 2. determine the reason each of these points was observed, if possible
- 3. eliminate any points that can be shown to be irrelevant to the analysis
- 4. reanalyze the data, both with and without any remaining influential points

Steps 1 and 4 in this general procedure are statistical in nature, while steps 2 and 3 require knowledge of specific experimental details and a thorough understanding of the underlying science.

Outliers Detection Methods

Fortunately, outliers can usually be found using standard model validation procedures. However, in complicated, multivariate data, they can be sometimes be difficult to pick out.

Use of more specialized outlier detection procedures in linear regression problems can help ensure that all outliers are found, and can lead to a deeper understanding of the data and model.

The use and interpretation of the specialized outlier detection methods is harder in nonlinear least squares, though logically possible. As a result, residual plots are the primary means of identifying influential points in nonlinear problems.

Two Classes of Specialized Outlier Detection Methods

There are basically two classes of outlier detection methods:

- 1. methods that rely on the usual LS model fitting criteria, but may (effectively) delete observations from the fit, one-at-a-time, to help determine their influence (LS Methods), and
- 2. methods in which the model fitting criterion is changed to reduce the effect of outliers on model estimation (Robust Methods)

Advantages and Disadvantages of LS Methods

Advantages:

- 1. use the same software as for regular regression analysis
- 2. work reasonably well with small and large data sets
- 3. provide a relatively large amount of information about unusual data points
- 4. are part of a relatively well-developed area of statistical research
- 5. are computationally efficient

Disadvantages:

- 1. do not work well with clusters of unusual points
- 2. require use of many different diagnostic statistics

Advantages and Disadvantages of Robust Methods

Advantages:

- 1. work well with arbitrary numbers and clusters of unusual points
- 2. identify influential points in one step

Disadvantages:

- 1. require specialized software
- 2. require medium-sized to large data sets
- 3. may not identify non-influential outlying points
- 4. are part of a relatively new area of statistical research
- 5. can be computationally difficult

LS Methods for Outlier Detection

Four of the main LS statistics for outlier detection are:

- leverages which are used to identify high leverage points (unusual predictor variable values), regardless of their influence,
- studentized deleted residuals which are used to identify outliers (unusual response variable values) which may or may not be influential,
- Cook's distances which are used to identify points that influence one or more of the estimated parameters, and
- **DFFITS** which are used to identify points which influence one or more of the predicted values.

Leverage Values (aka Hat Values)

Leverage values are the diagonal values of the Hat matrix, H, which is given by:

$$H = X(X^T X)^{-1} X^T$$

where X is the matrix with n rows and p = k + 1 columns, the first of which is a column of 1's for the intercept term, and each of the other columns given by the values of one of the k variables in the model,

$$X = [1|x_1|x_2|\dots|x_k]$$

For the straight line model

$$h_{ii} = \frac{1}{n} + \frac{(x_i - \bar{x})^2}{\sum_{i=1}^n (x_i - \bar{x})^2}$$

Leverages for more complicated models are conceptually analogous to the straight line case.

Leverage Values (aka Hat Values)

The sum of the leverage values is p, the number of parameters in the model, for all multivariable linear regression functions.

Therefore, when an individual leverage value is much larger than the mean leverage p/n, it indicates a high leverage point.

A good cut-off for leverage values is 2.5p/n. Points with values larger than this are likely to be contributing to the fitted model more heavily than most.

High leverage doesn't necessarily indicate an influential point, however. A high leverage point with a y value that is right on target will produce a fit that is similar to one using only low leverage points.

Studentized Deleted Residuals

The i^{th} studentized deleted residual is conceptually obtained by:

- 1. deleting the i^{th} point from the data,
- 2. fitting the model with the other n-1 observations,
- 3. computing the deleted residual, which is the difference of the i^{th} response and corresponding prediction from the fit made without the i^{th} response.
- 4. computing the residual standard deviation using the fit to the n-1 other points, and
- 5. dividing the deleted residual by its standard deviation, which depends on the residual standard deviation with the i^{th} point deleted and the i^{th} leverage value computed using all of the data.

Studentized Deleted Residuals

The conceptual formula for the i^{th} studentized deleted residual is

$$T_i = \frac{y_i - \hat{y}_{(-i)}(x_{1i}, \dots, x_{ki})}{s_{(-i)}/\sqrt{1 - h_{ii}}}$$

where $\hat{y}_{(-i)}(x_{1i}, \dots, x_{ki})$ is the predicted value based on the fit without the i^{th} point, and $s_{(-i)}$ is the corresponding residual standard deviation.

The computational formula is:

$$T_i = e_i \sqrt{\frac{n-p-1}{(n-p)s^2(1-h_{ii})-e_i^2}}$$

where the computations are done using all of the data.

Studentized Deleted Residuals

Technically, T_i has a t distribution with n-p-1 degrees of freedom, and t distribution cut-off values can be used to determine if a particular point is an outlier.

Practically speaking, studentized deleted residuals greater than 2.5 in absolute value indicate that a point is likely to be an outlier.

Remember, however, that large studentized deleted residuals do not necessarily offer any information about the influence of the outlier on the fit of the model.

Cook's Distance

Conceptually, the i^{th} Cook's Distance measures the difference between the values of the parameters estimated using all n observations and the values of the parameters estimated without the i^{th} observation.

It provides an aggregate measure of the difference for all of the parameters simultaneously.

The computational formula for Cook's Distance is:

$$c_i = \frac{h_{ii}}{p} \left(\frac{e_i}{s(1 - h_{ii})}\right)^2$$

computed using all of the data.

Cook's Distance

Points with Cook's Distance values greater than the 50% F distribution cut-off with p and n-p degrees of freedom are likely to influence the estimated parameters in the model.

That is, if a point with a large Cook's Distance is eliminated from the data set, the values of one or more of the parameters will change significantly.

Influential points should be studied carefully to determine if they are valid data points. If not, they should be excluded from the analysis. If there is no evidence that the influential points are invalid, further work will be required to obtain conclusive results from the data.

DFFITS

Conceptually, the i^{th} DFFITS value measures the difference between the i^{th} predicted value estimated using all n observations and estimated without the i^{th} observation.

The conceptual formula for DFFITS is:

DFFITS_i =
$$\frac{\hat{y}_i(x_{1i}, \dots, x_{ki}) - \hat{y}_{(-i)}(x_{1i}, \dots, x_{ki})}{s_{(-i)}\sqrt{h_{ii}}}$$

The computational formula for DFFITS is:

DFFITS_i =
$$T_i \sqrt{\frac{h_{ii}}{1 - h_{ii}}}$$

computed using all of the data.

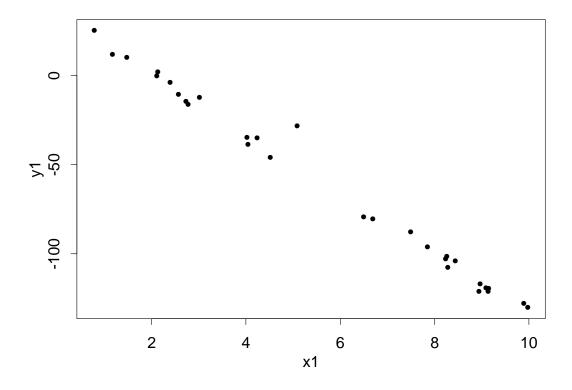
DFFITS

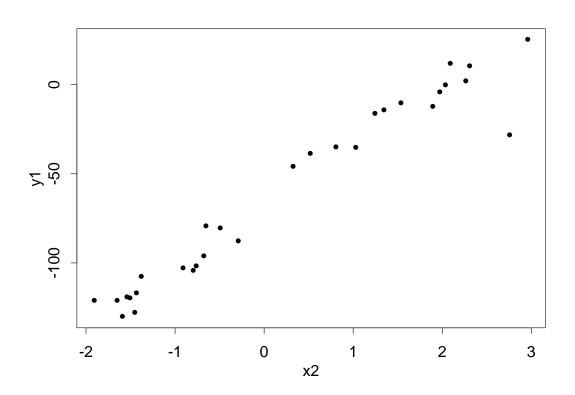
Points with DFFITS values greater than $2.5\sqrt{p/n}$ are likely to influence the predicted values from the model.

That is, if a point with a large DFFITS value is eliminated from the data set, the value of the one or more of the predicted values will change significantly.

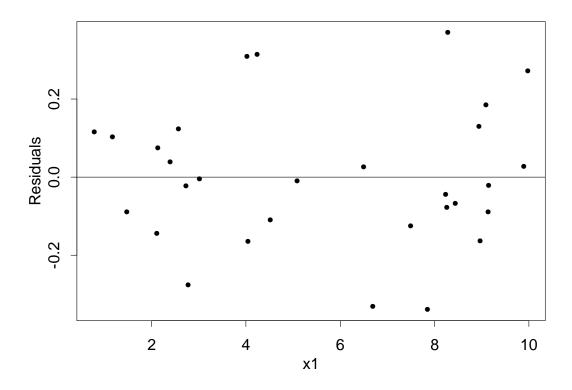
As with influential points identified using Cook's Distance, the validity of points picked out by DFFITS should be examined carefully. If assignable causes are found that indicate the point is not valid, it should be dropped from the analysis. If not, further work will required to obtain conclusive results.

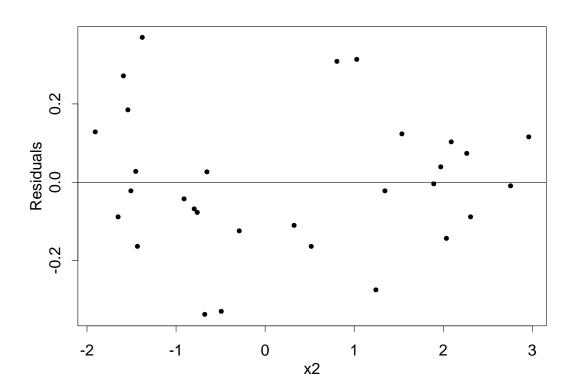
Multivariable Dataset #1 with Potential Outlier



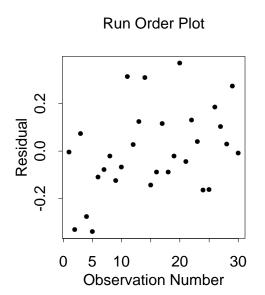


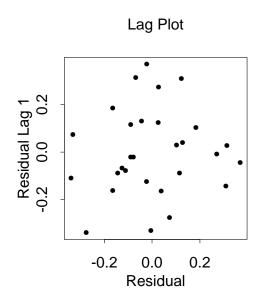
Residuals From Fit with n Points



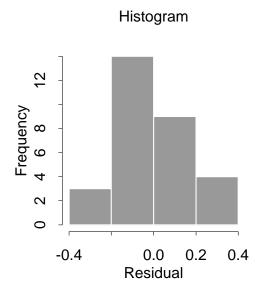


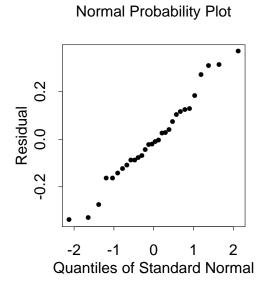
Residuals From Fit with n Points



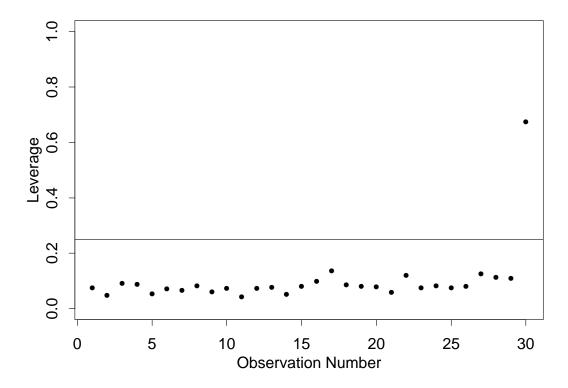


199

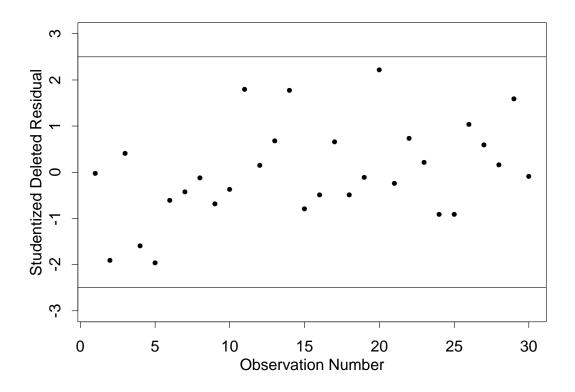




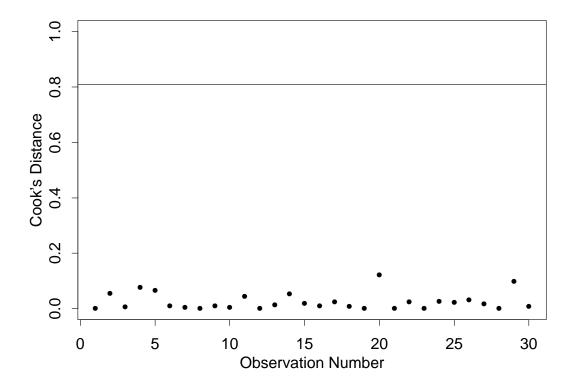
Leverages



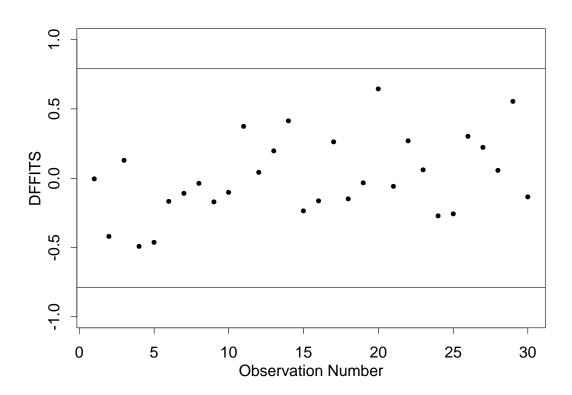
Studentized Deleted Residuals



Cook's Distances



DFFITS



Regression Output Using n Points

```
N = 30
```

Residual Standard Error = 0.1859

Multiple R-Square = 1

F-statistic = 1121069 on 2 and 27 df, p-value = 0

```
coef std.err t.stat p.value
Intercept 4.7251 0.2153 21.9480 0
x1 -11.9502 0.0345 -346.3767 0
x2 10.0313 0.0674 148.9384 0
```

Regression Output Using with the High Leverage Point Deleted

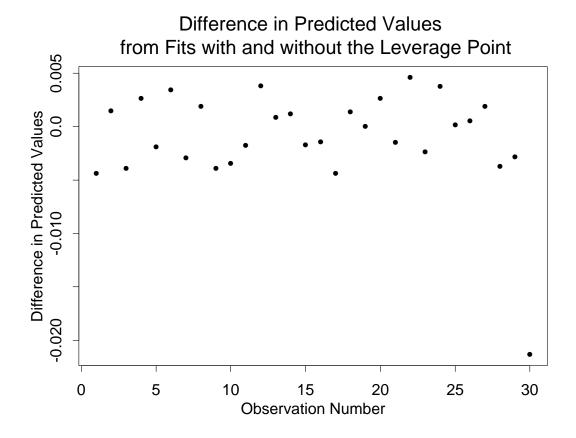
```
N = 29
```

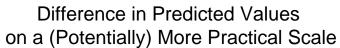
Residual Standard Error = 0.1895

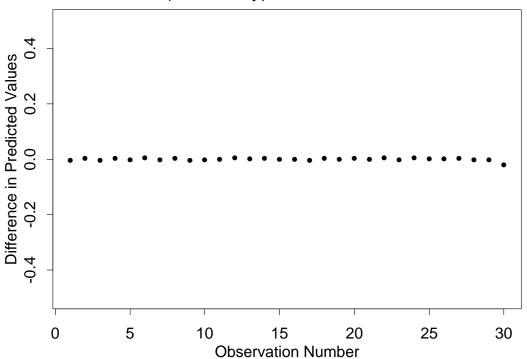
Multiple R-Square = 1

F-statistic = 1065271 on 2 and 26 df, p-value = 0

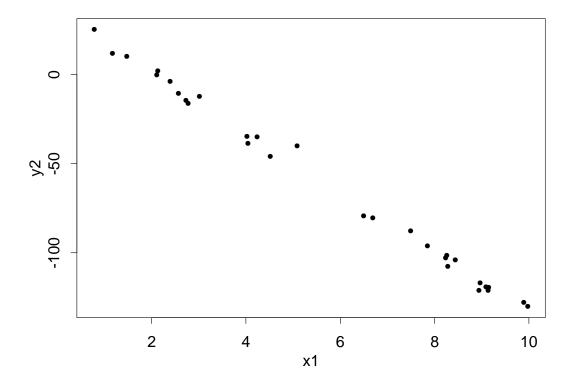
```
coef std.err t.stat p.value
Intercept 4.6989 0.3511 13.3843 0
x1 -11.9458 0.0577 -206.9284 0
x2 10.0405 0.1181 85.0499 0
```

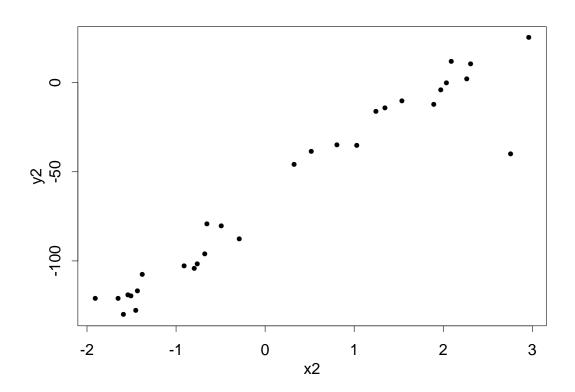




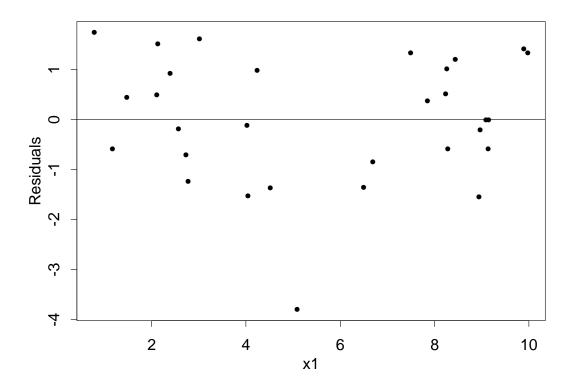


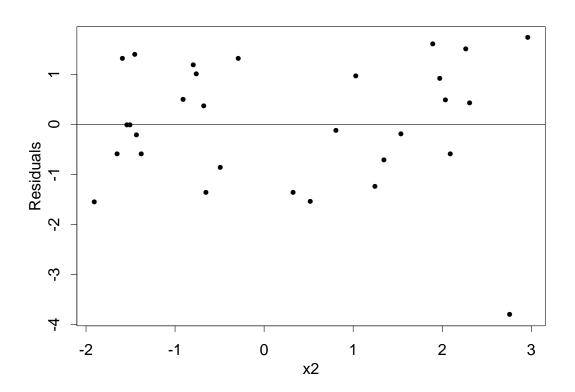
Multivariable Dataset #2 with Potential Outlier





Residuals From Fit with n Points





Residuals From Fit with n Points

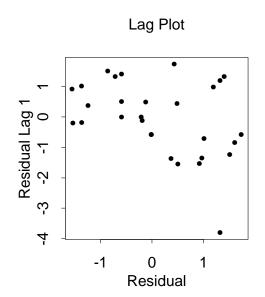
Residual

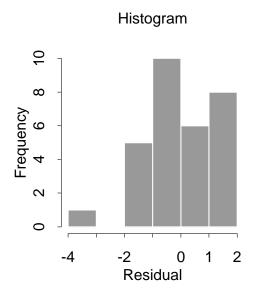
4 -3 -2 -1 0 1

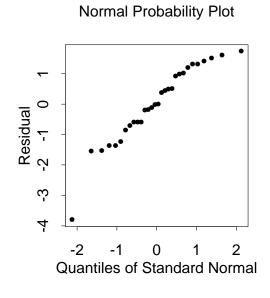
5 10 20 Observation Number

30

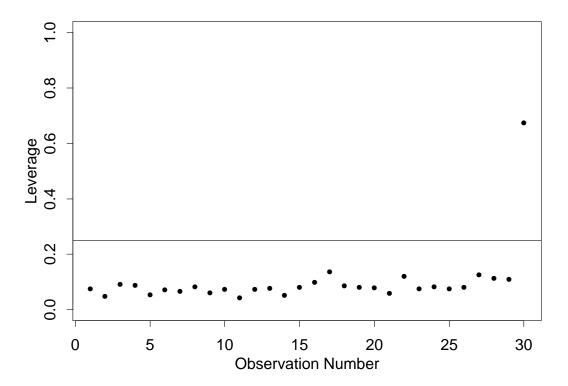
0



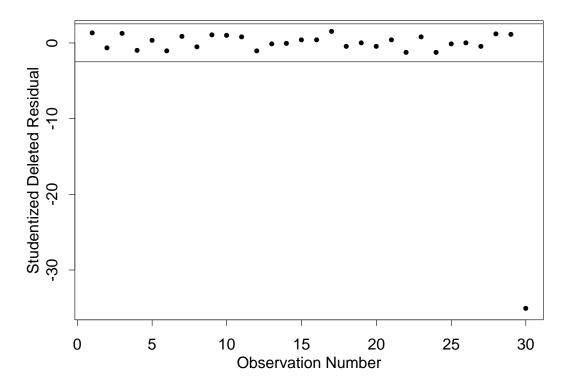




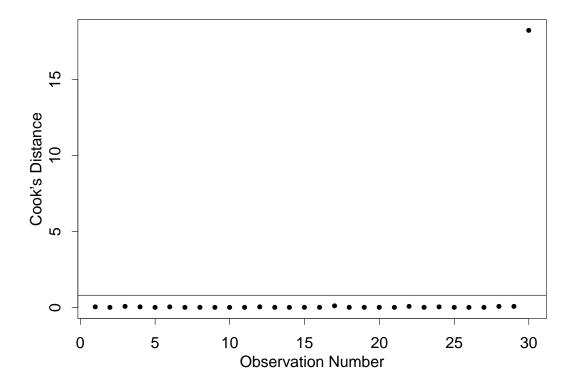
Leverages



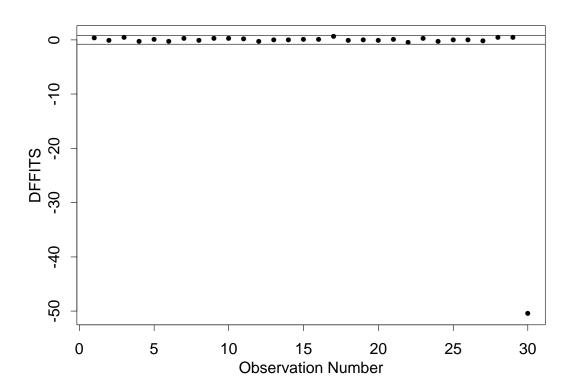
Studentized Deleted Residuals



Cook's Distances



DFFITS



Regression Output Using n Points

```
N = 30
```

Residual Standard Error = 1.2939

Multiple R-Square = 0.9994

F-statistic = 22959.24 on 2 and 27 df, p-value = 0

```
coef std.err t.stat p.value
Intercept 14.3252 1.4980 9.5630 0
x1 -13.5540 0.2401 -56.4605 0
x2 6.6670 0.4686 14.2261 0
```

Regression Output Using with the Influential Point Deleted

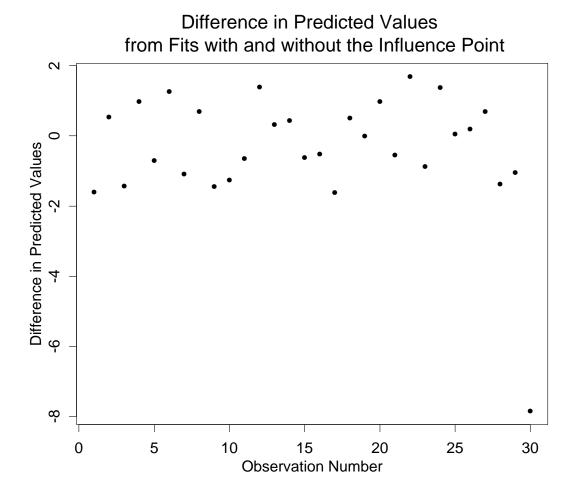
```
N = 29
```

Residual Standard Error = 0.1895

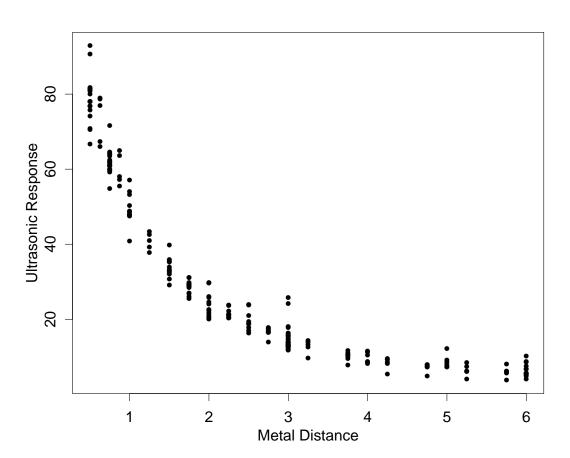
Multiple R-Square = 1

F-statistic = 1065271 on 2 and 26 df, p-value = 0

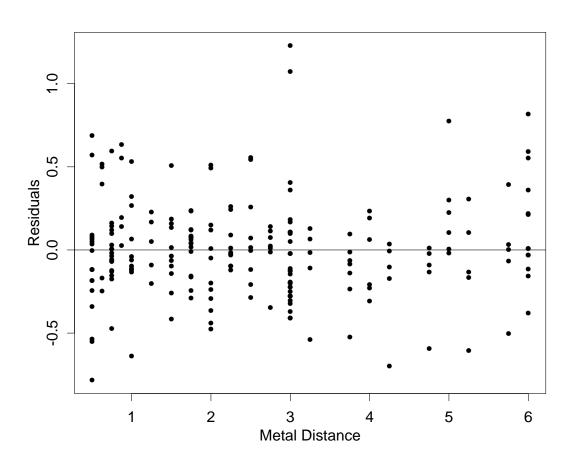
```
coef std.err t.stat p.value
Intercept 4.6989 0.3511 13.3843 0
x1 -11.9458 0.0577 -206.9284 0
x2 10.0405 0.1181 85.0499 0
```



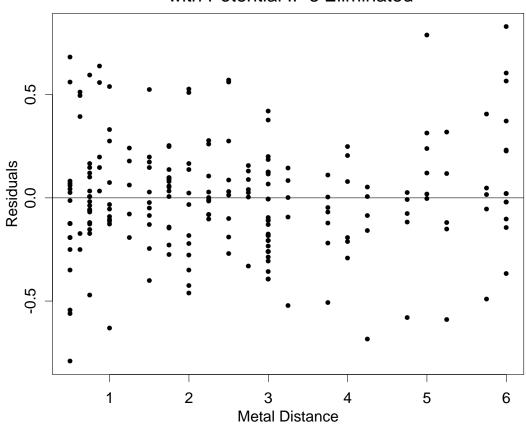
Ultrasonic Calibration Data



Residuals From Fit to Transformed Data



Residuals From Fit to Transformed Data with Potential IP's Eliminated



Ultrasonic Data Regression Output: n Points

Formula: $sqrt(ur) \sim exp(-b1 * md)/(b2 + b3 * md)$

Parameters:

```
Value Std. Error t value
b1 -0.0154274 0.00861101 -1.79159
b2 0.0806725 0.00150574 53.57670
b3 0.0638570 0.00288001 22.17250
```

Residual standard error: 0.29715 on 211 degrees of freedom

Ultrasonic Data Regression Output: n-2 Points

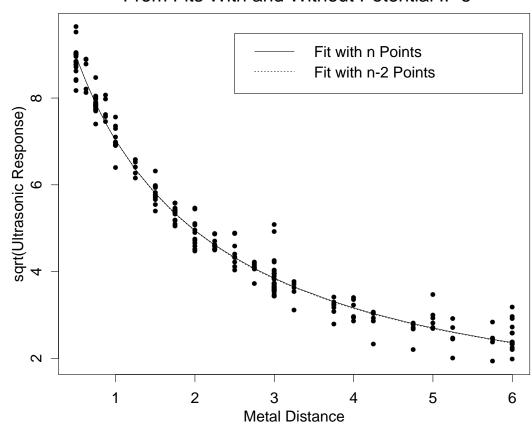
```
Formula: sqrt(ur) \sim exp(-b1 * md)/(b2 + b3 * md)
```

Parameters:

```
Value Std. Error t value
b1 -0.0155610 0.00799912 -1.94533
b2 0.0803004 0.00140502 57.15260
b3 0.0644030 0.00268723 23.96630
```

Residual standard error: 0.276145 on 209 degrees of freedom

Data with Predicted Values
From Fits With and Without Potential IP's



Section 2: Summary

Two problems that often occur when carrying out a regression analysis are:

- 1. finding non-constant standard deviations across different predictor variable values, and
- 2. finding outliers, high leverage points, and/or influential points in the data.

Outliers, leverage points and influential points can be identified using either graphical residual analysis or more specialized detection methods.

Non-constant standard deviation across the predictors can be corrected using either transformation of the data or weighted least squares.