

Real-Time Video Analytics for Situation Awareness

Presenters: Salvador Medina, Junwei Liang PI: Alexander Hauptmann Carnegie Mellon University

DISCLAIMER

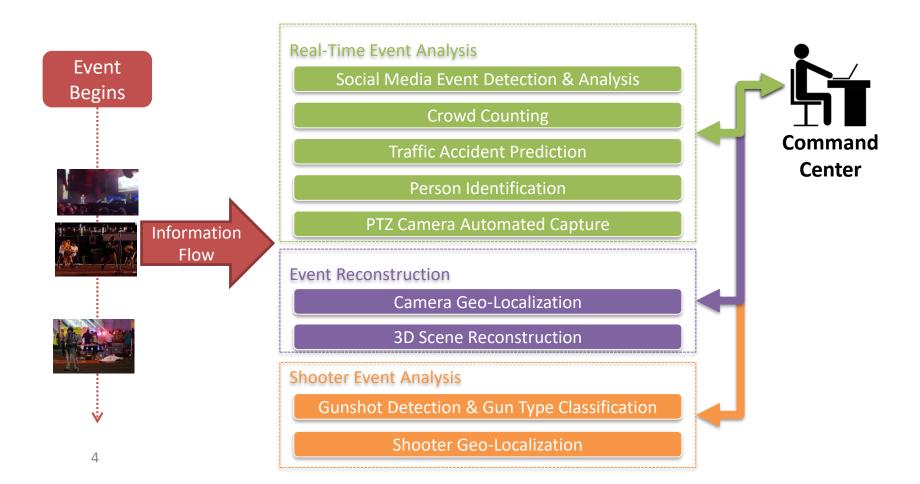
This presentation was produced by guest speaker(s) and presented at the National Institute of Standards and Technology's 2019 Public Safety Broadband Stakeholder Meeting. The contents of this presentation do not necessarily reflect the views or policies of the National Institute of Standards and Technology or the U.S. Government.

Posted with permission

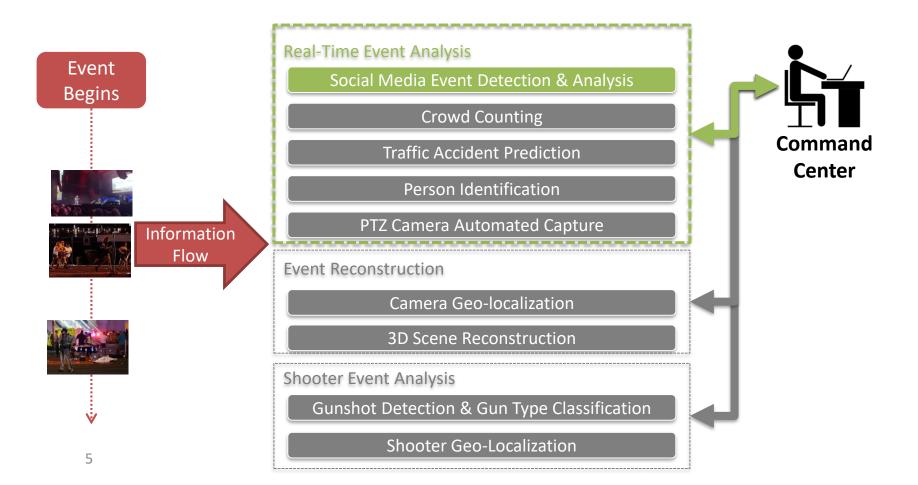
Introduction

- Ubiquitous camera phones capture public safety events and media is rapidly shared
- Goal: develop video analytics tools based on AI
 - Harness the information of event-based video recordings
 - Make video analysis for public safety less laborintensive and more manageable at a large scale
 - Enhance the decision making capability of analysts

Overview



Social Media Event Detection & Analysis



Social Media Event Detection & Analysis

- As a major public safety event unfolds, social media is an important source of information
- Problem:
 - Many social media entries are unrelated or uninformative
- Solution:
 - Filter "useful" entries with text, image, and/or video
 - Automatically identify useful social media posts in real-time



Useful Information

.....

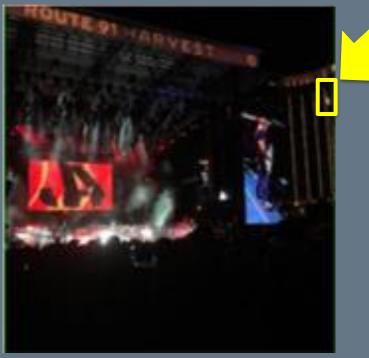
Useful Tweet Extraction – Natural Disaster Events

AnonUser @anonuser Apr 3, 2019 10:39:05 AM GMT-07:00 DST That's some of the damage caused by high winds and heavy rain in Goldsboro. Lights and some traffic signals are out, neighborhood streets are flooded. Avoid downed power lines! #abc11 https://t.co/D54qJIQMnl

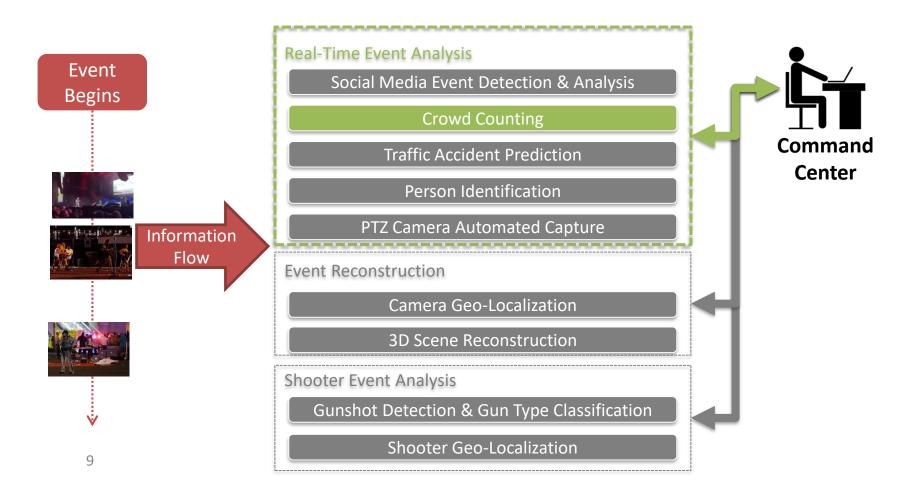


Useful Tweet Extraction – Shooting Event

AnonUser @anonuser Oct 3, 2017 10:51:19 PM GMT-07:00 D Look at the window the shooting is from. Real or fake?



Crowd Counting



Crowd Counting

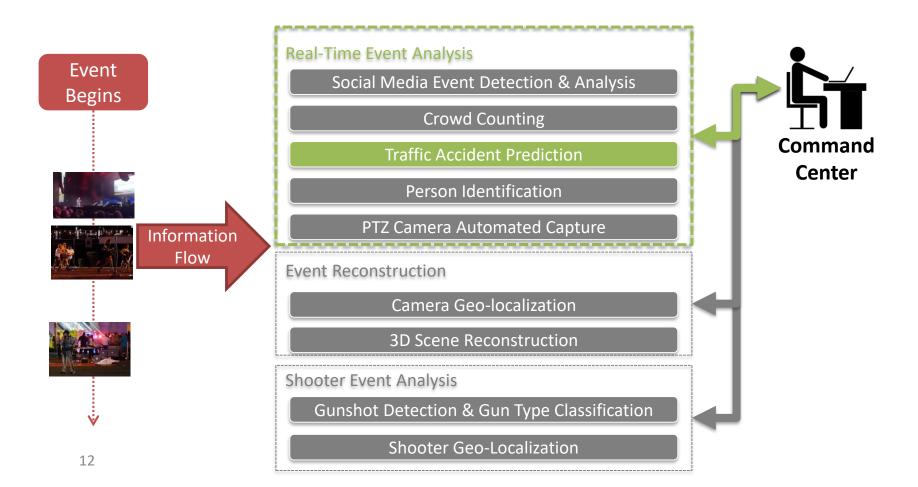


- Goal
 - Count number of persons in realtime in a given scene
- Possible applications:
 - Occupancy monitoring for safety
 - Situation assessment
 - Crowd management
 - Response coordination

Crowd Counting

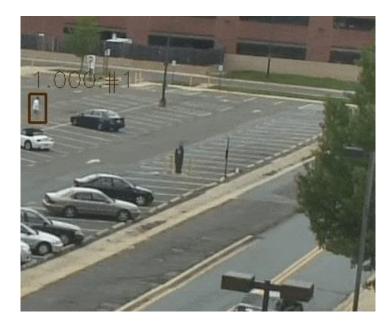


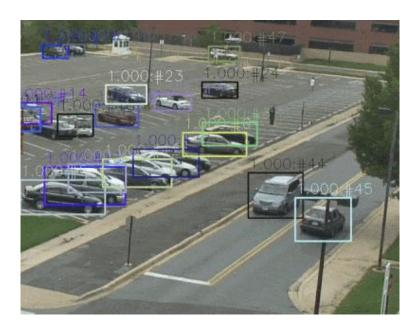
Traffic Accident Prediction



Object Detection & Tracking in Surveillance Videos

• Our tools are currently among the best in these scenarios





Person Tracking

Vehicle Tracking

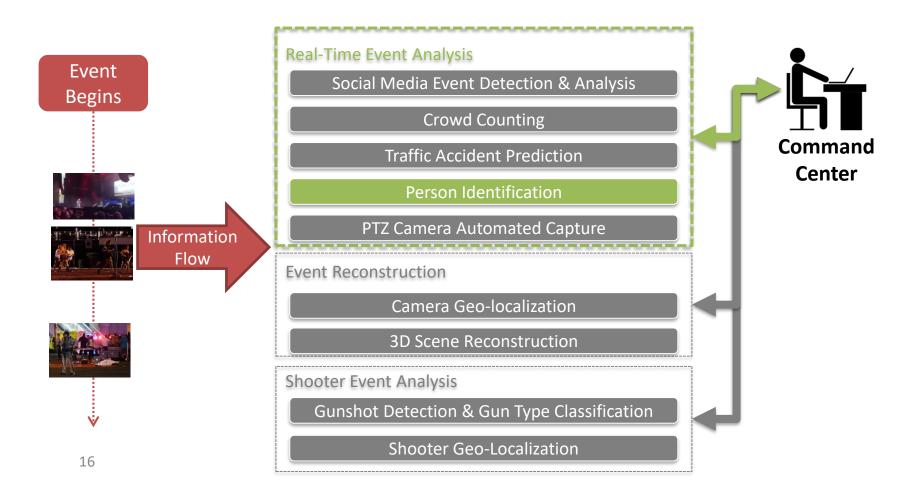
* Source Code and Model: https://github.com/JunweiLiang/Object_Detection_Tracking 13

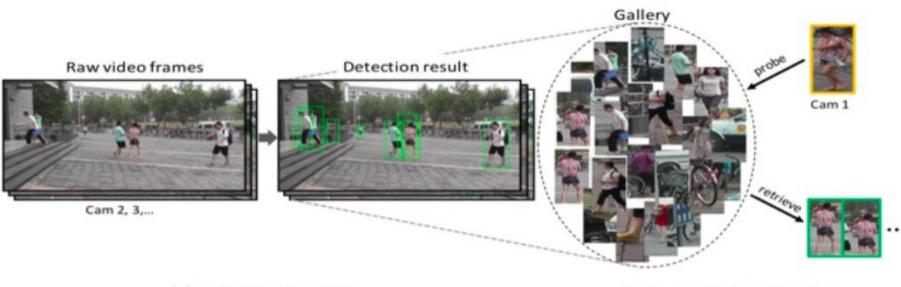
Traffic Accident Prediction

- Predict and detect crashes from surveillance cameras
 - Fast notifications to first responders
 - Ready to use on any camera stream
- Proactive safety check
 - Speed and distance check of normal traffic flow
 - Provide insight about high-risk intersections

Traffic Accident Detection - Video Example



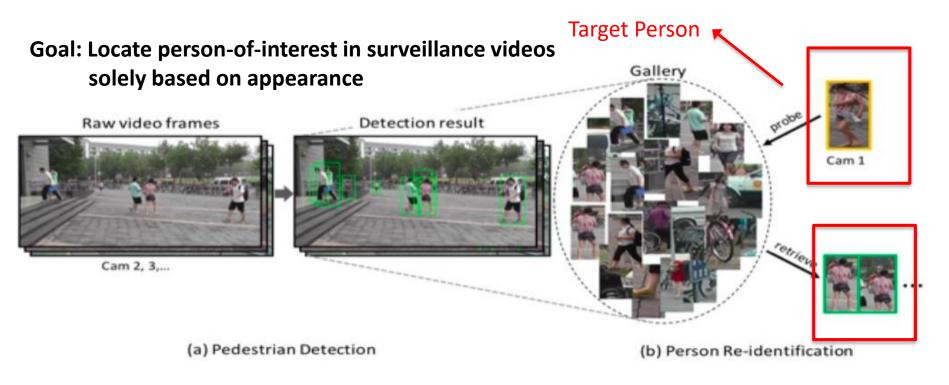




(a) Pedestrian Detection

(b) Person Re-identification

Chang, Xiaojun, Po-Yao Huang, Yi-Dong Shen, Xiaodan Liang, Yi Yang, and Alexander G. Hauptmann. "RCAA: Relational context-aware agents for person search." In *Proceedings of the European Conference on Computer Vision (ECCV)*, pp. 84-100. 2018.



Retrieved Person



Gait Recognition for Person identification



with bag, 54°, id:1



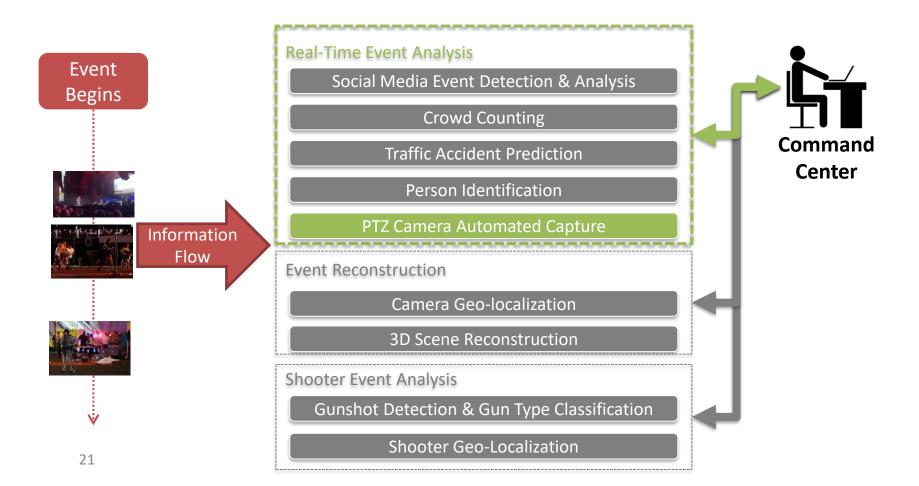
normal, 144°, id:1



with coat, 90°, id:1



PTZ Camera Automated Capture



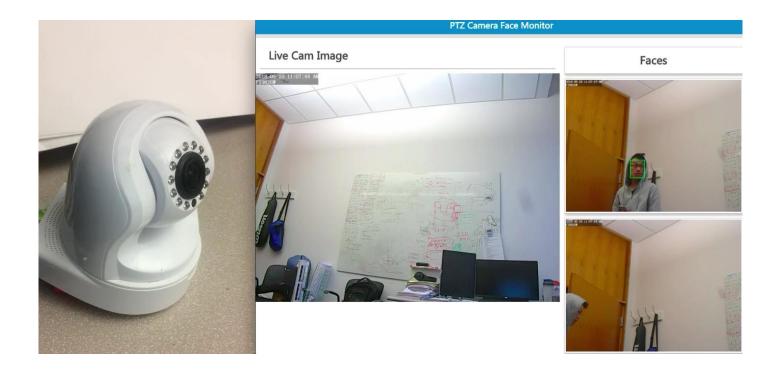
Last Year's Auto Person Capture

- Used Pan-Tilt-Zoom Camera
- PTZ camera system can take high-resolution pictures of people that are far away



Last Year's Auto Person Capture

• Problem: PTZ camera movement has a delay



Last Year's Auto Person Capture

- Pan-Tilt-Zoom Camera
 - We can see that the PTZ movement takes time
 - Therefore we need a system that:
 - predicts people's trajectories
 - filters out targets if the system can predict activities

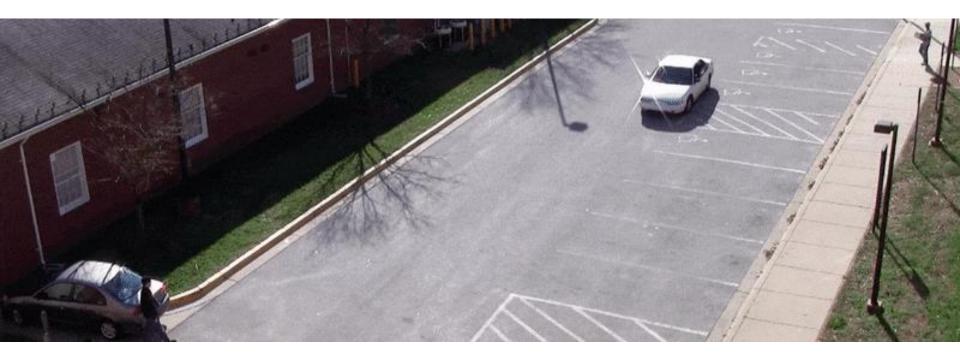
Can you predict what's next?

Where are they going to go?

What are they going to do?



How can a system predict a person's future?



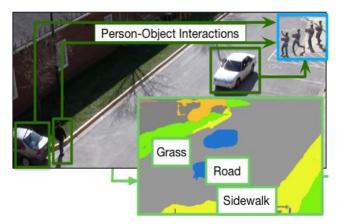
How can a system predict a person's future?

- People navigate in a scene with a specific purpose in mind
- People's purpose can be inferred from:
 - their appearance
 - body language
 - nearby environment



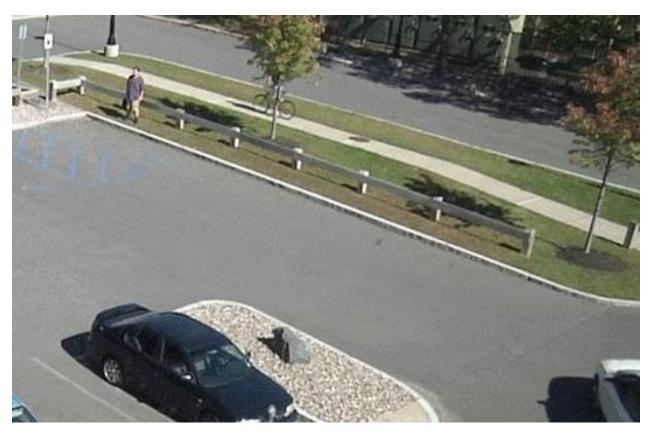
Our Model - NEXT

- We designed an AI model with a *Person Behavior Module* and *Person Interaction Module* which considers:
 - Target person
 - **Target person interactions** with the scene and other objects.



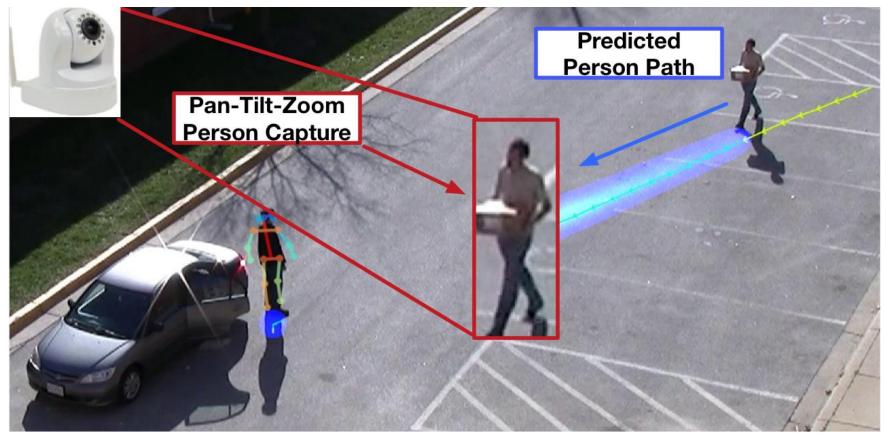
* Source Code and Model: https://github.com/google/next-prediction

Demonstration - Single Person Prediction



Yellow path: observable trajectory; Heatmap: trajectory prediction; Text: activity prediction

Automatic Person Picture Capturing Using Pan-Tilt-Zoom Cameras

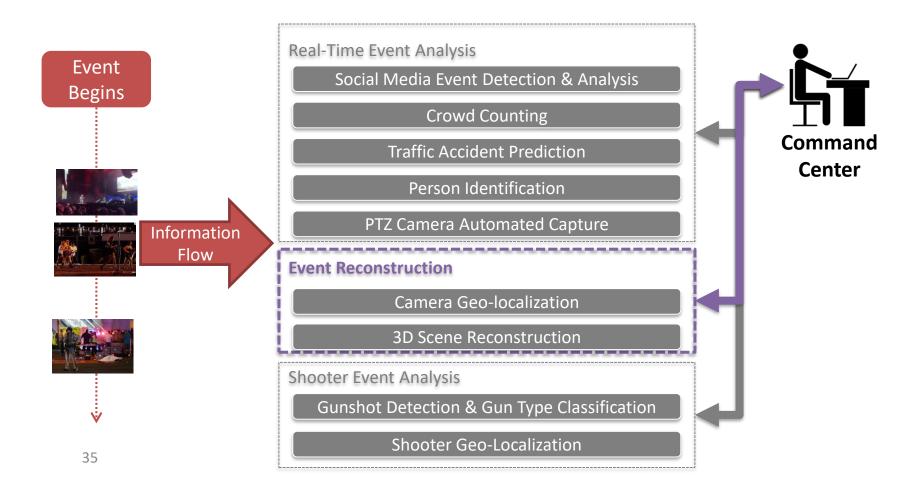


Automatic Person Picture Capturing Using Pan-Tilt-Zoom Cameras

Activity of Interest: Opening Trunk of a Car



Video Synchronization

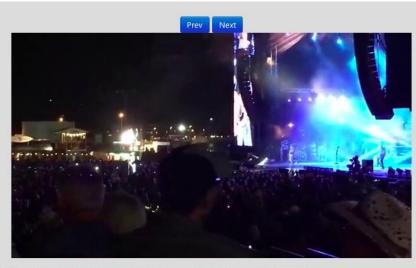


Video Synchronization

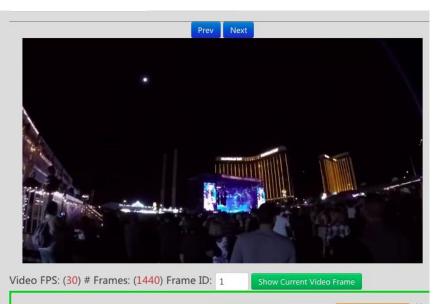
- Videos from social media usually do not have any meta-data like GPS and time.
- It is necessary to put all relevant videos in a global timeline first to understand an event.

Video Synchronization

• This year we added frame-accurate synchronization tool for video alignment

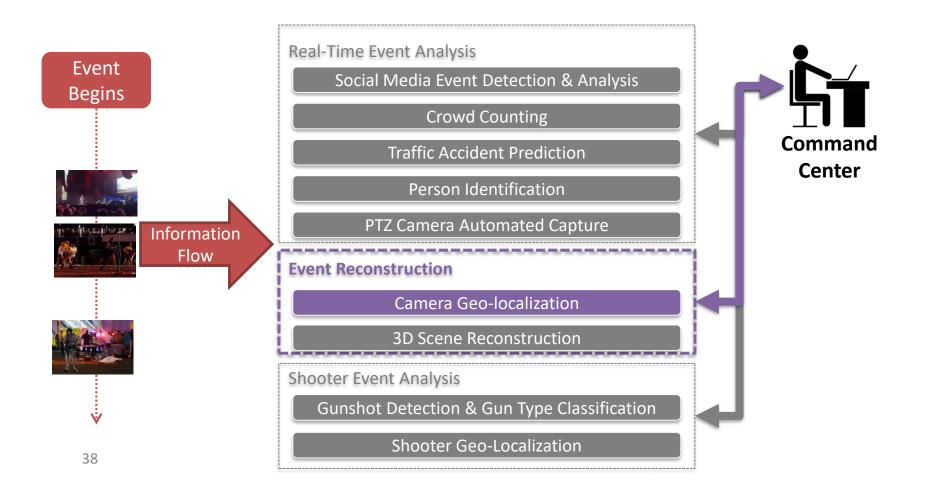


Video FPS: (29.97002997003) # Frames: (1310) Frame ID: 856 Show Current Video F ame by Frame Checking FrameView VideoView Current Video Time: (28.563415) struction



Current Video Time: (0) FrameView VideoView Destroy Vid

Camera Geo-Localization

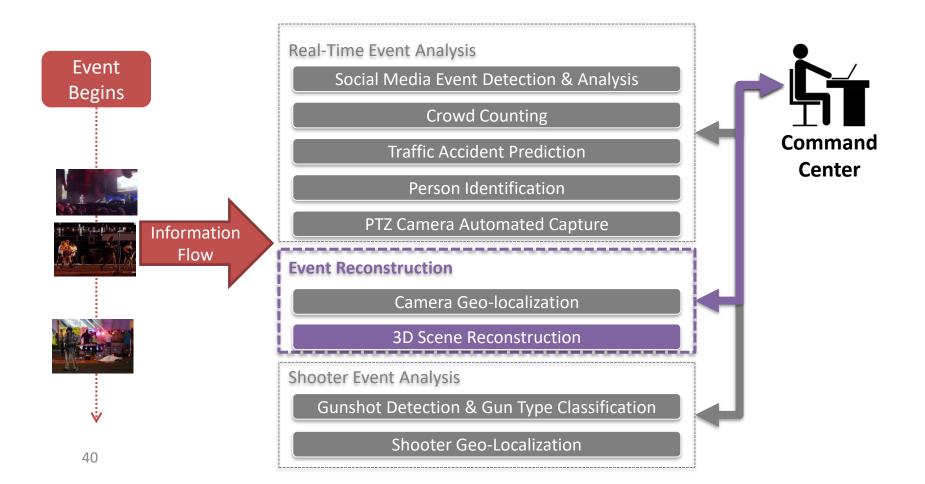


Camera Geo-Localization

- Usually social media videos have no GPS metadata
- To locate a video we match Google Street View images to video frames to infer its position



3D Scene Reconstruction



3D Reconstruction with Camera Localization

- Synchronizing multiple videos at a large scale makes it hard to understand the situation
- Our goal is:
 - To reconstruct the scene in 3D to project videos into augmented reality to understand the event
 - Pinpoint each camera location

Demonstration – Boston Dataset

• Sparse 3D reconstruction for Boylston Street in Boston



Demonstration – Boston Dataset

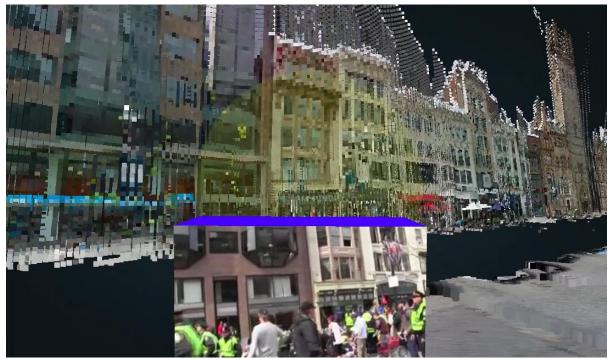
Dense 3D Reconstruction of Boylston Street from

Google Street View Data



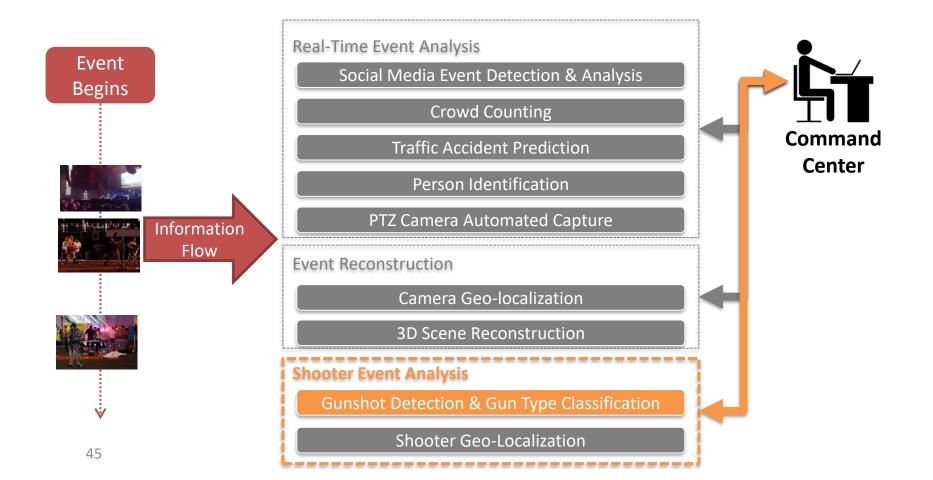
Demonstration – Boston Dataset

• Camera Localization in reconstructed 3D scene



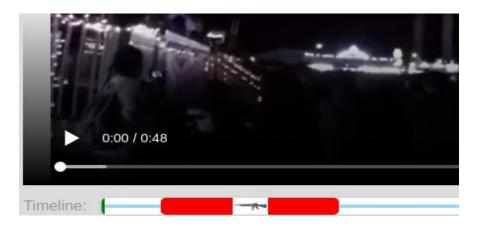
* Source Code and Model: https://github.com/JunweiLiang/VERA_3D_Reconstruction

Gunshot Detection



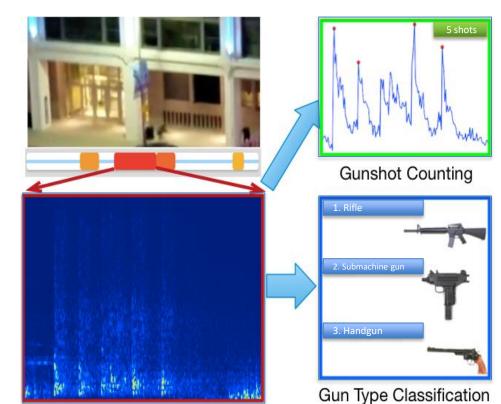
Gunshot Detection

- Our tools can detect video segments that contain one or more gunshots.
 - This significantly reduces the inspection time when dealing with many or very long videos.

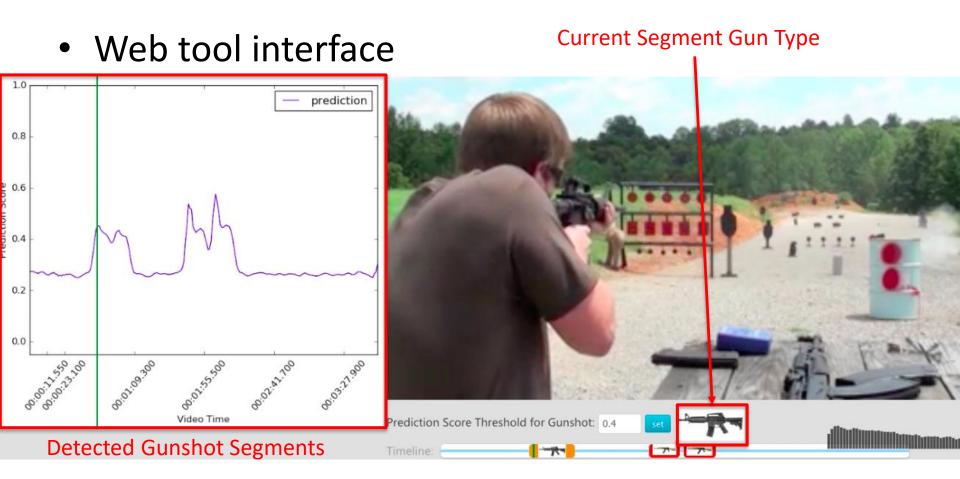


Gunshot Counting & Gun Type Classification

- After gunshot segments are identified,
 - our system can:
 - Count gunshots
 - Classify gun types



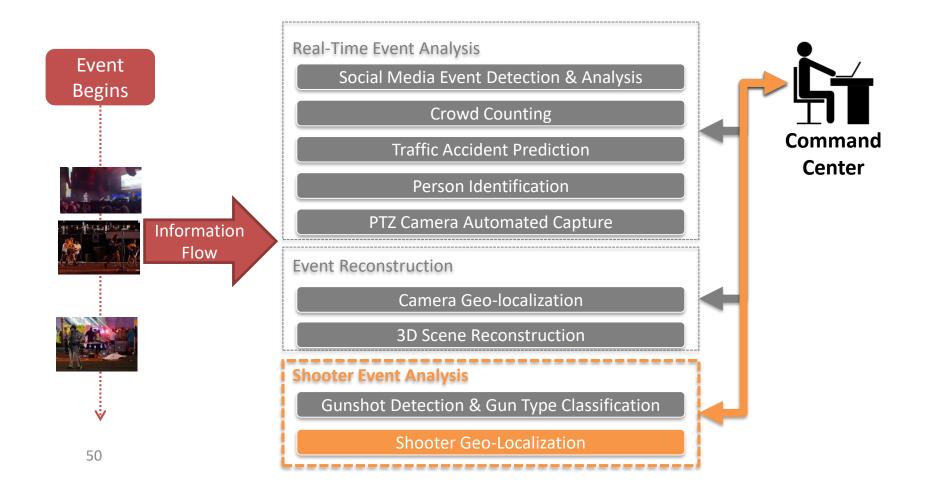
Gunshot Counting & Gun Type Classification



Gunshot Counting & Gun Type Classification



Shooter Geo-Localization



Shooter Geo-Localization

- Our system can determine the shooter's location from social-media videos where a gunshot was detected
- This localization is based on:
 - 1. Gunshot Detection
 - 2. Video Synchronization
 - 3. Camera Geo-Localization

Shooter Geo-Localization

- The system can estimate:
 - The shooter distance from the camera
 - The direction the shooter is shooting from given recordings from two cameras

Assuming:

- Videos are synchronized
- Cameras are geo-localized

- The system can estimate the distance of the shooter to the camera if:
 - 1. The bullet is super-sonic
 - 2. Bullet shockwave sound ("crack") is recorded
 - 3. Muzzle blast sound is recorded
 - Muzzle blast sound: the sound when the bullet leaves the barrel

See technical report at https://vera.cs.cmu.edu for more details

Bullet shockwave facts:

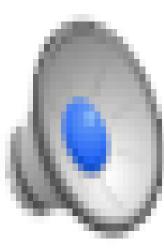
- Will arrive before the muzzle blast sound
- 2. Have a sharper angle if the bullet is faster
- Note: cannot be heard behind the rifle



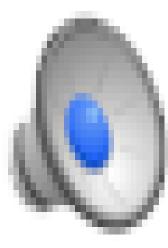
Rifle

See technical report at https://vera.cs.cmu.edu for more details

• Mark the shockwave sound and muzzle blast sound on the video segment that gunshot is detected



• Bullet shockwave sound

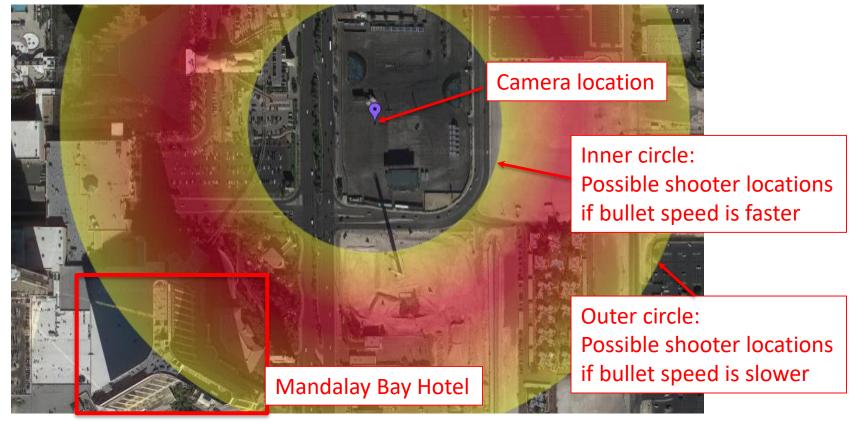


• Muzzle blast sound

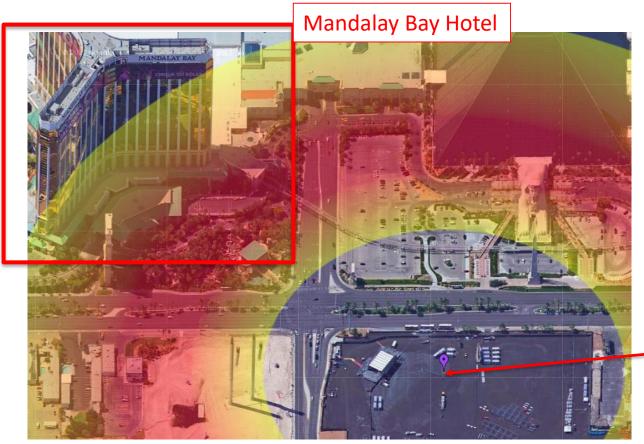


- Distance can be computed based on:
 - Time difference between the bullet shockwave and muzzle blast
 - Speed of the bullet
 - Speed of sound
- Since the bullet and speed of sound are estimated, there is a range of possible distances
- A probable minimum and maximum distances around the camera form a *donut* shape of possible locations

The *donut* is placed on the map around the camera



The *donut* is placed on the map around the camera



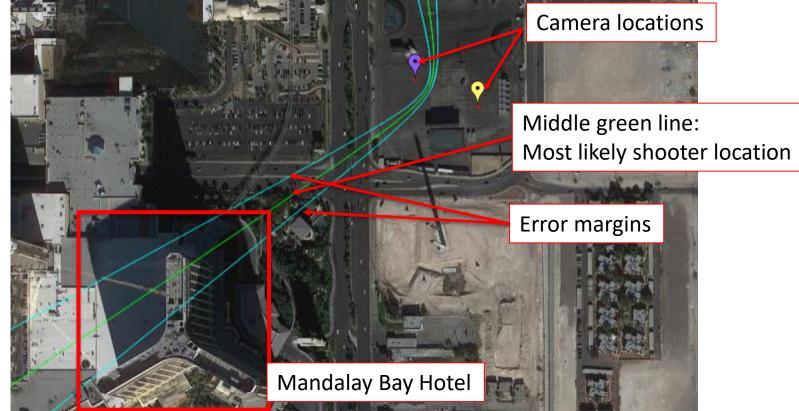
45 degree view from another angle

Camera location

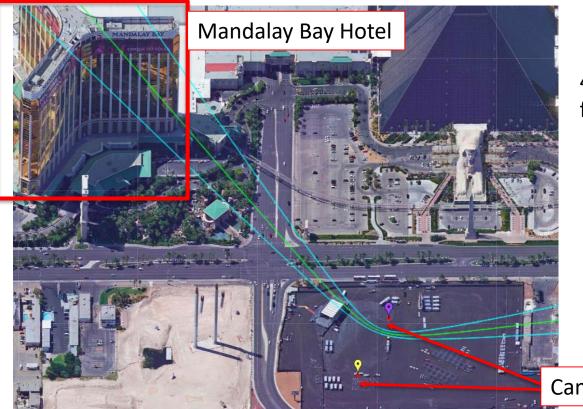
- To estimate the direction of the shooter, we need:
 - A pair of synchronized videos both recording the muzzle blast sound of the gunshot
 - Accurate camera locations

- We make use of the time difference of the arrival of the muzzle blast sound at the two cameras
 - Three bowl-shaped lines (hyperbolas) can be drawn to determine the likely location of the shooter

The shooter is located within the three lines, where the middle green one is most likely



The shooter is located within the three lines, where the middle green one is most likely



45 degree view from another angle

Camera locations

Gunshot Geo-Localization – Las Vegas Shooting

Satellite View Mandalay Bay Hotel DESCRIPTION OF A DESCRI **Pins: Camera locations** Possible shooter location: Donut area 1. 2. Between green line and blue line

Demonstration of the web interface

Summary

Real-Time Event Analysis

- Social Media Event Detection and Analysis
- Crowd Counting
- Object Detection and Tracking in Videos (https://github.com/JunweiLiang/Object_Detection_Tracking)
 - Traffic Accident Prediction
 - Person Re-identification using Gait Recognition
 - Automatic Person Picture Capturing Using Pan-Tilt-Zoom Cameras (https://github.com/google/next-prediction)
- Event Reconstruction
 - Video Synchronization (https://vera.cs.cmu.edu/)
 - Camera Geo-Localization
 - 3D Reconstruction (https://vera.cs.cmu.edu/VERA_3D_Reconstruction)
- Shooter Event Analysis
 - Gunshot Detection & Gun Type Classification (https://vera.cs.cmu.edu/)
 - Shooter Geo-Localization (https://vera.cs.cmu.edu/)

Thank you!

Any questions?



#PSCR2019

Come back for the

.....

Next Session 1:50 PM