

# **Inertial Sensing Transducer**

**PROJECT LEADER:** Bahram Ghodsian (Lumedyne Technologies)

COLLABORATORS: Keith Easler (Lumedyne Technologies); Josh Schumacher (NIST)

## GOAL

To fabricate a proof-of-concept inertial motion sensor that uses an electron tunneling circuit to monitor the frequency of a microelectromechanical harmonic oscillator.

### **KEY ACCOMPLISHMENTS**

Fabricated a small low-power, low-cost mechanical oscillator with tunneling tips as a prototype timing trigger in a sensitive force and position detector.

Successfully created the 10 nm to 40 nm tunneling gaps required to allow electron tunneling.

#### **KEY NANOFAB PROCESS**

Precise focused ion beam ablation to define a nanoscale gap between tunneling tips on a microcantilever and on an adjacent rigid substrate.

> Left: Microscope image of the cantilever device with gold electrical connections. Right: Scanning electron micrograph shows conducting tips on the cantilever and on the rigid substrate. With each oscillation of the cantilever, a tunneling current flows between the tips as they pass each other, triggering timing circuitry.

Gold conductor on cantilever ← Cantilever adge → Cantilever tip Gap made by FIB

### **REFERENCE** http://www.lumedynetechnologies.com/