



Pocket Guide for Aerial Drones



CONFINED

Tests and Scenarios





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Version 2023D

Confined Tests and Scorable Scenarios

Indoors/Outdoors, Lighted/Dark, GPS/No GPS

Standard Test Methods for Small Unmanned Aircraft Systems ASTM International Standards Committee on Homeland Security Applications;

Confined Scenario: Structure Interior Rooms (Safety | Capabilities | Proficiency

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MIDDLE INDOOR ALTITUDE







LINDER VEHICLE SEARCH





Confined Tests and Scorable Scenarios PROCEDURES FOR ALL JESTS AND THE SOME OF LAUNCH - FORWARD - REVERSE - FORWARD - LAND PROCEDURES FOR ALL TESTS ARE THE SAME (10 POSITIONS = 20 BUCKET ALIGN | LAUNCH - 1 2 3 4 - 3

Evaluate safety, capabilities, and proficiency

MIDDLE INDOOR ALTITUDE 1 M (3 FT)

Standard Test Methods for Small Unmanned Aircraft Systems ASTM International Standards Committee on Homeland Security Applications: Response Robots (E54.09) | Website: RobotTestMethods.nist.gov



MIDDLE INDOOR ALTITUDE

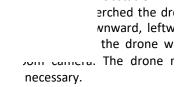
1 M (3 FT)

Confined Scenario: Structure Interior Rooms (South) Safety | Capabilities | Proficiency

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Standard Test Methods for Small Unmanned Aircra

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Standard Test Methods for Si ASTM International Standards Comm

Response Robots (E54.09) | W

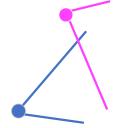
Confined Scenario: Struct Safety | Capabil







TOP INDOOR ALTITUDE





MIDDLE INDOOR ALTITUDE 1 M (3 FT)



MIDDLE INDOOR ALTITUDE 1 M (3 FT)









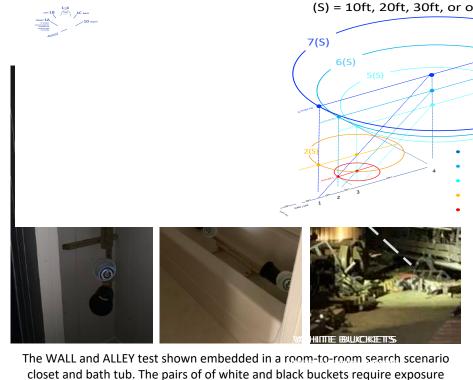




ALLET (IVIAI

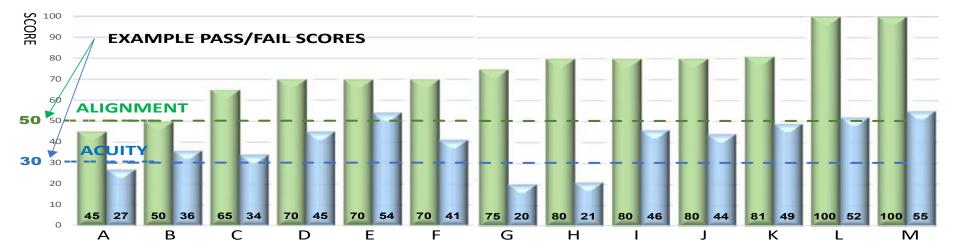
Separate Scores: ALIGNMENT and ACUITY

Track and Compare Scores Using the Same Drone



5 Different Orbits in Every Lan

closet and bath tub. The pairs of of white and black buckets require exposure control to discern details. Also shown is a more complex overturned subway rail car disaster. All such scenarios get embedded with scoring tasks totaling 100 points.





increasingly small Concentric Cs gaps to correct (1 of 8) orientations.

- First align with each PERPENDICULAR BUCKET to capture a SINGLE ALIGNMENT IMAGE of the inscribed ring.
- Score captured images with
 - UNBROKEN RINGS (5 points)
 - BROKEN RINGS (1 point)
 - NO RINGS (0 points, strike through line)
- Accurate landings are not scored.
- during the trial when obvious or after the trial to eliminate discussions during the trial. Images can also be stored for documentation.



Teams Rotate Through Each Role

Each Pilot flies a 5-minute trial with help from others. A 3-4 person team completes all 5 tests in 2 hours.





Four person teams always have one person getting their aircraft ready to launch right after the previous lands.

Three person teams work too, but require some time between each rotation to prepare the next aircraft

PILOT

- Maintain control of the aircraft.
- Call out each intention of movement be
- Call out each bucket alignment and acu tigap.

PROCTOR

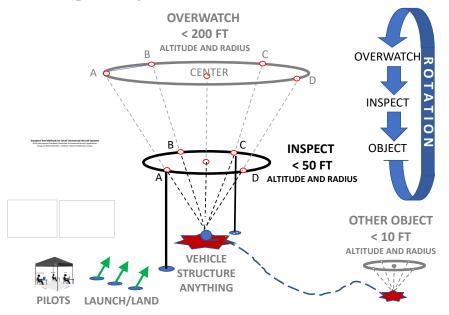
- Fill in the form header.
- Read the test procedures to the Pilot.
- Confirm, record, and attest to scoring after the trial.

VISUAL OBSERVER (VO)

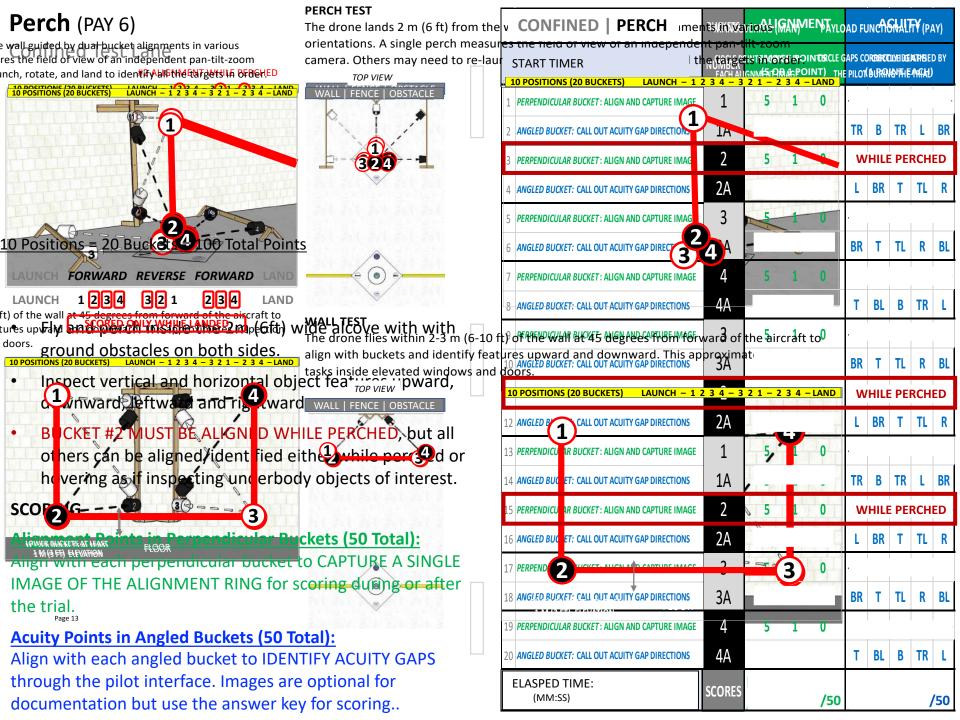
- Maintain sight with the aircraft and surroundings.
- Repeat the Pilot's intention of movement to confirm.
- Call out corrections and warnings as necessary.

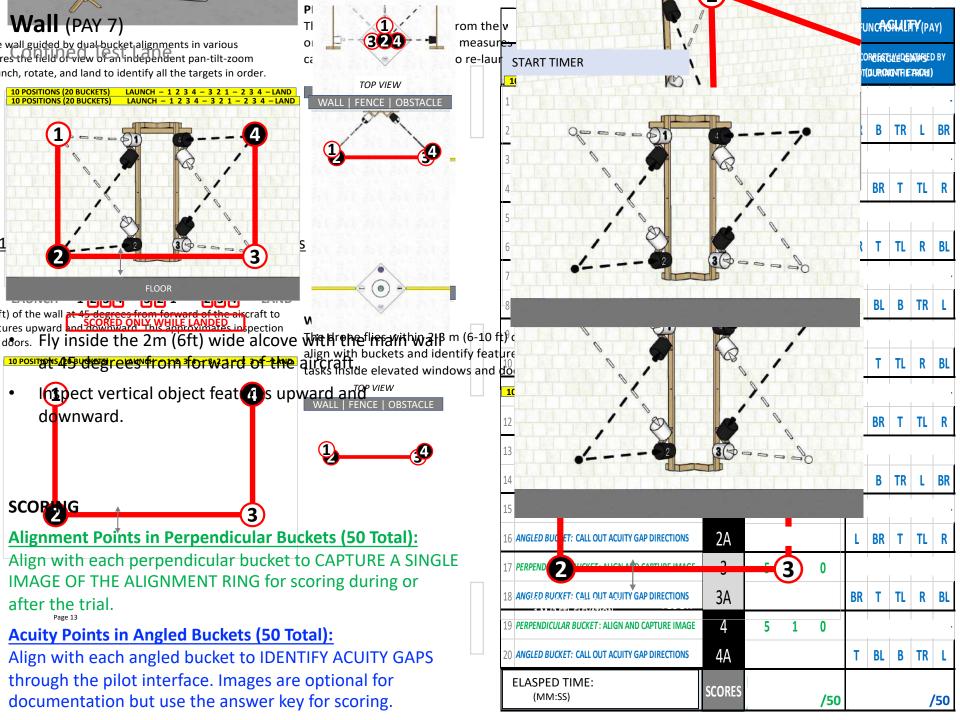
Teams Sequence Through Scenarios

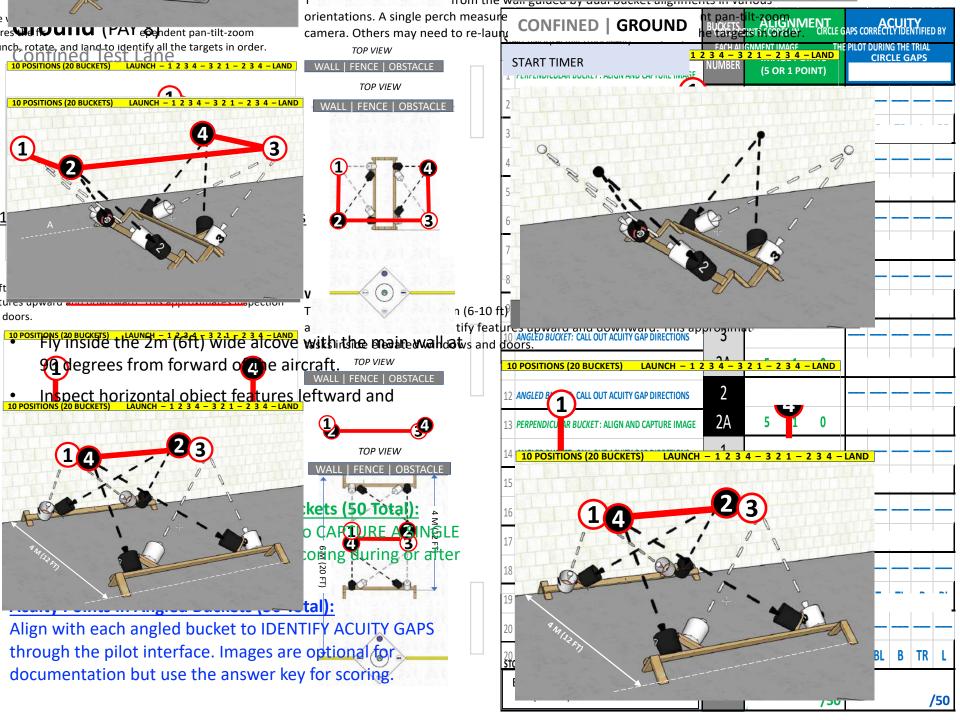
Each Pilot flies a 15-minute scenario, sequencing through 3 objectives for 5 minutes each.

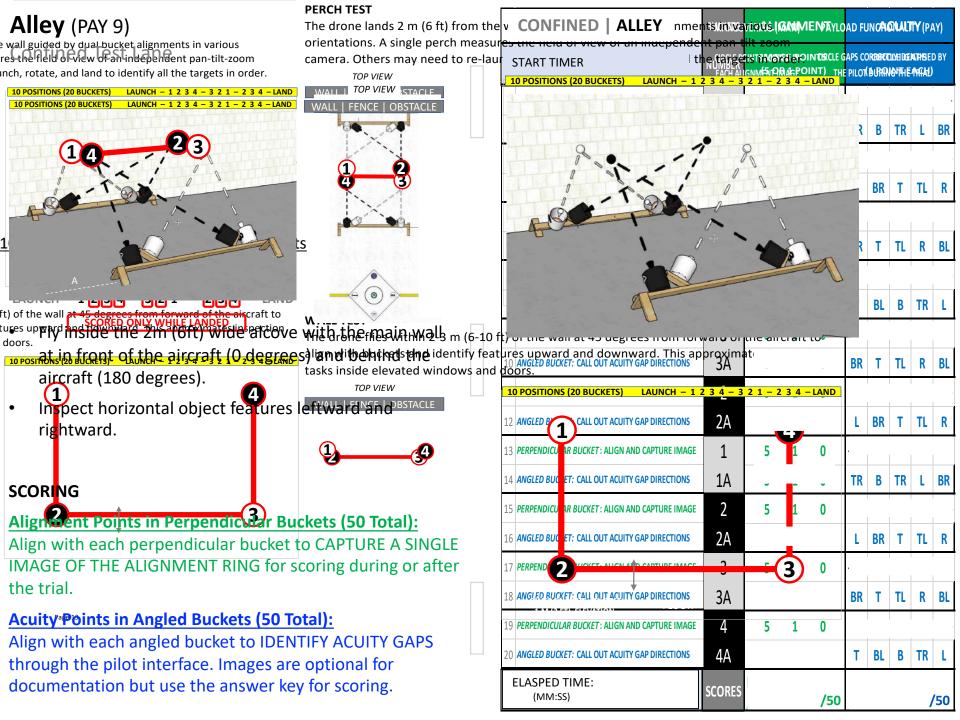


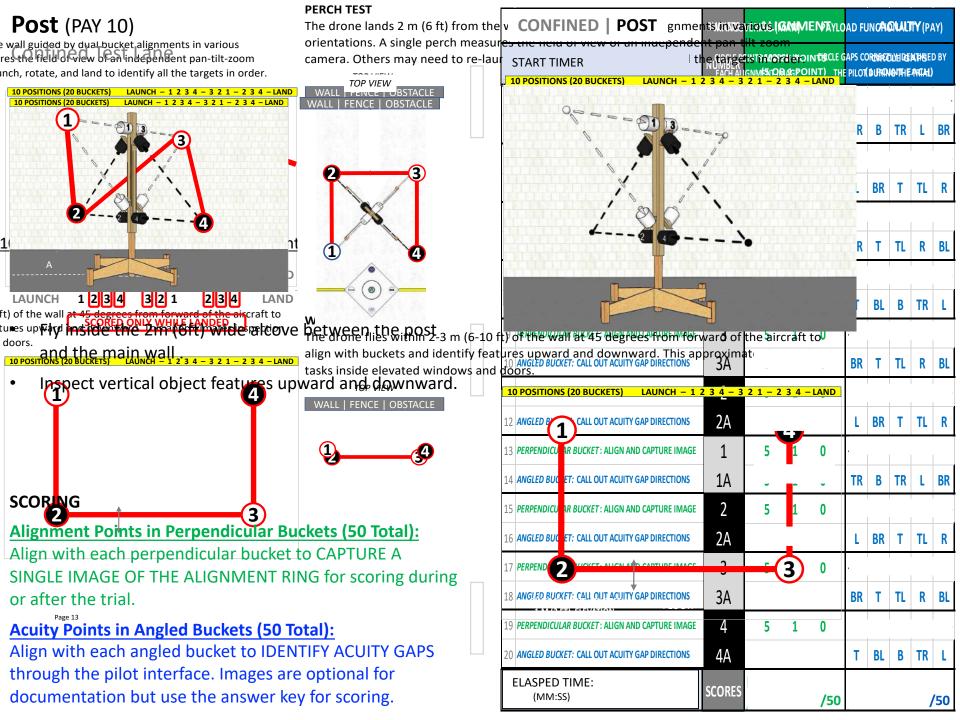
- This scenario mechanization enables embedded bucket scoring tasks to be performed similarly by all participating Pilots. So the results are comparable within the same scenario layout. Additional tactics can be overlayed onto these scenarios at your facility.
- Up to 3 teams concurrently fly different scenario objectives from safe distances and altitudes apart.
- Teams move as necessary to maintain sight lines with their aircraft and communications with other teams.
 The overwatch team leads communications.
- Scenarios restart every 20 minutes with a different rotation of Pilot, Proctor, and VO.











Standard Test Methods for Small Unmanned Aircraft Systems Confined Vehicles in spection the Confined (6 ft) from the CONFINED | VEHICLE IN THE CONFINED | n the wall guided by dual-bucket alignments in various leasures the field of view of an independent pan-tilt-zoom orientations. A single perch measures the he tatigetistiavorater oincircle gaps correctriciperstaties by camera. Others may need to re-laun START TIMER NAMBER I ANMÉRTORA ÉPOINT) THE PILOT É BRACH I LAUNCH - 1 2 3 4 - 3 2 1 - 2 3 4 - LAND BUCKL TOP VIEW II S 10 POSITIONS (20 BUCKETS) PERPENDICULAR BUCKET: ALIGN AND CAPTURE IMAGE DISTRIBUTED THROUGHOUT THE SCENARIO TR B TR L BR ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTION: ĺΑ PERPENDICULAR BUCKET: ALIGN AND CAPTURE IMAG BR T TL R ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS PERPENDICULAR BUCKET: ALIGN AND CAPTURE IMAG 0 4Et 4. Total Points 10 Positi BR T TL R BL ANGLED BUCKET: CALL OUT ACUITY GAP DIRECT LAUNCH FORWARD REVERSE FORWARD LAND 0 PERPENDICULAR BUCKET: ALIGN AND CAPTURE IMAGE 1234 234 BL B TR L ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS y features upward and downward. This approximates in spection rone flies within 2-3 m (6-10 ft) of the Wall at 45 degrees Trem forward of the aircraft to 0 vith buckets and dentify features upward and downward. This approximate 10 POSITIONS (20 BUCKETS) LAUNCH - 1 2 3 4 - 3 2 1 - 2 3 4 - LAND BL l TL e elevated windows and doors. TOP VIEW LAUNCH - 1 2 3 4 - 3 2 1 - 2 3 4 - LAND WALL | FENCE | OBSTACLE 6A TR B TR L BR 12 ANGLED B CALL OUT ACUITY GAP DIRECTIONS R BUCKET: ALIGN AND CAPTURE IMAGE 13 PERPENDICU 7A 14 ANGLED BUC ET: CALL OUT ACUITY GAP DIRECTIONS BR T TL 8 15 **PERPENDICU** AR BUCKET: ALIGN AND CAPTURE IMAGE **VEHICLES** 8A TL WER BUCKETS AT LEAST 1 M (3 FT) ELEVATION 16 ANGLED BUC ET: CALL OUT ACUITY GAP DIRECTIONS ٥ 9A BL В TR 18 ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS 10 19 PERPENDICULAR BUCKET: ALIGN AND CAPTURE IMAGE 10A BL R TL L BL 20 ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS **ELASPED TIME: SCORES** (MM:SS) /50 /50

Confined Room-to-Room Labyrint CONFINED | SEARCH ents // (NOT a right shift LOAD FUNCTION SHIFT MAY) ands 2 m (6 ft) from the orientations. A single perch measur camera. Others may need to re-lau mothe wall glided by dual bycket alignments In Pailious Innimur neasures the field of view of an independent pan-tilt-zoom START TIMER re-launch, rotate, and land to identify all the targets in order. USE SETS OF 5 "INLINE" DUAL BUCKET RANGE. HORIZONTALS FOR LEFTWARD/RIGHTWARD INSPECTIONS TR B TR L BR NGLED BUCKET: CALL OUT ACUITY GAP DIRECTION ĺΑ HIGH/LOW ACCESS HOLES PERPENDICULAR BUCKET: ALIGN AND CAPTURE IMAG 1 m (3 ft) 2A **SQUARE** BR T TL R ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS 0 'bil 3D BR T TL **FLIGHT** AND **PATH** LAUNCH 1 234 32 1 234 LAND -WERTIGALS FOR JOWARD/DOWNWARD INSPECTIONS BL B TR L Angled Bucket: Call out acuity gap directions 2-3 m (6-10 ft) of the Wall & 45 deglees fibrill forward of the aircraft to 0 UPWARD l identify features upward and downward. This approximate 10 ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS 5A ELEVATION LEFT/RIGHT **ELEVATIO** BL l TL 6A TR B TR L BR 12 ANGLED B CALL OUT ACUITY GAP DIRECTIONS 13 **Perpendicu** *R BUCKET* : ALIGN AND CAPTURE IMAGE 1 M (3 FT) DOWNWARD 7A 14 ANGLED BUCET: CALL OUT ACUITY GAP DIRECTIONS BR T TL **ELEVATION** LEFT/RIGHT 8 Plywood panels attached together form tall self standing "L" walls as test lane alcoves, switchback hallways, and 8A ET: CALL OUT ACUITY GAP DIRECTIONS rooms with tasks to identify. A blackout tarp over top makes a ceiling at 2.4m (8ft), or set it up inside a 6m 9A BL TR 18 ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS (20ft) shipping container. 10 Square access "windows" measuring 1m (3ft) square 10A BL R TL L BL 20 ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS provide entry/exit and interior high/low pass throughs. **ELASPED TIME: SCORES** (MM:SS) /50 /50 Split cylinder concrete forms evaluate 2D/3D maps.