Test Methods for Evaluating Aerial Drones Standard Test Methods for Small Unmanned Au NATIONAL INSTITUTE OF STANDARDS AND TECHNOLOGY Us. De Standarde Test Methodes vor Sarahi Wanga Rinter Alignatid Systemstee for Homeland Security Applic.

ASTM International Standar Robot Trest Methods mistage with Robbits (E5%: 09) Website: Robot Test Methods.nist.gov Response Robots (E54.09) Website: RobotTestMethods.nist.gov



Perform the designated flight paths to

Standard Test Methods for Small Unmanned Aircraft Systems

M International Standards Committee on Homeland Security Applications; Response Robots (E54.09) | Website: RobotTestMethods.nist.gov

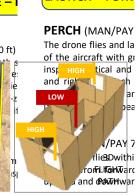
Version: 2020B2

Obstructed Te CI

The drone performs a series of maneuvers t the related scenarios. Each numbered buc recessed targets inside. Alignment with th designated position, orientation, and altitude bucket (5 points), or a partially inscribed ri work load to perform camera pointing, zoc many Concentric C gap directions as possik Proctor for scoring live trials. Video of the however scores may differ due to increasec The drone performs the related scenaric recessed targets in designated position bucket (5 points), o work load to perfor many Concentric C Proctor for scoring however scores may

PRO







The drone flies within 2-3 m (6-10 ft) proximity the aircraft (0 degrees) and behind the aircraft horizontal object features leftward and rightwar

The drone flies within the aircraft (0 degree horizontal object feat

rc

POST (MAN/PAY 10)

The drone flies within 2-3 m (6-10 ft) proximity while inspecting vertical object features up circumnavigating the post, the drone passes be obstacle placed 4 m (12 ft) apart.

POST (MAN/PAY 1

The drone flies within while inspecting ve circumnavigating the obstacle placed 4 m (2

Obstructed Test Lanes and Related Scenari

Standard Test Methods for 3

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Set Your Minimum T

Focus Training and Evaluate Confined Vehicle Inspection Scenarios Organizations can set their own threshold for pass/fa and/sectificencys Complete triads and gesenned LS DISTRIBUTED THROUGHOUT THE SCENARIO

Example proficiency data shown fr

