



Pocket Guide for Aerial Drones



CONFINED

Tests and Scenarios



SHED VEHICLE SEARCE



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Sponsor:

Systems Engineering & Standards Div Science and Technology Directora U.S. Department of Homeland Sect

 $\label{eq:website} Website \\ Robot Test Methods. nist. gov$



Email RobotTe

Version 2023C

Confined Tests and Scorable Scenarios

Indoors/Outdoors, Lighted/Dark, GPS/No GPS

Standard Test Methods for Small Unmanned Aircraft Systems
ASTM International Standards Committee on Homeland Security Applications;
Response Robots (FSA 09) | Websites Robots TestMethods nist row

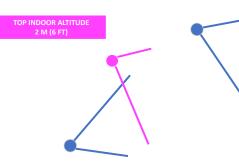
Confined Scenario: Structure Interior Rooms (Safety | Capabilities | Proficiency

OPEN

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MIDDLE INDOOR ALTITUDE 1 M (3 FT)

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Confined Tests and Scorable Scenarios

Evaluate safety, capabilities, and proficiency

Standard Test Methods for Small Unmanned Aircraft Systems ASTM International Standards Committee on Homeland Security Applications: Response Robots (E54.09) | Website: RobotTestMethods.nist.gov

Confined Scenario: Structure Interior Rooms (South) Safety | Capabilities | Proficiency





MIDDLE INDOOR ALTITUDE 1 M (3 FT)





















Bucket Alignments Define Flight Paths

Designated altitudes, positions, and orientations



Confine

Standard Test Methods for Sma ASTM International Standards Committee

Response Robots (E54.09) | Web

Confined Scenario: Structu Safety | Capabilit







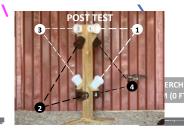




MIDDLE INDOOR ALTITUDE 1 M (3 FT)

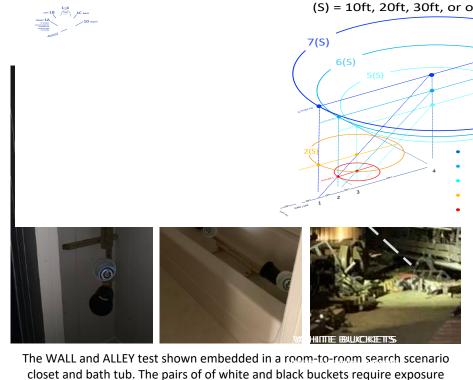


MIDDLE INDOOR ALTITUDE 1 M (3 FT)



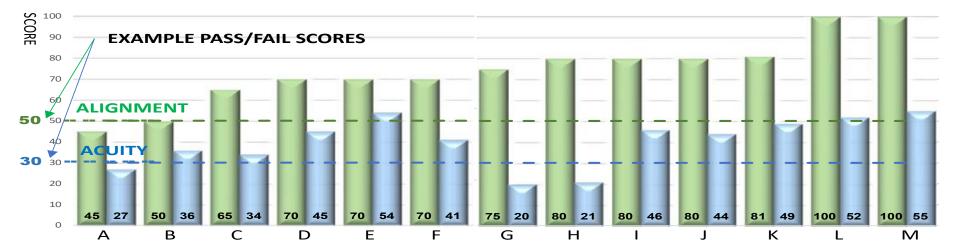
Separate Scores: ALIGNMENT and ACUITY

Track and Compare Scores Using the Same Drone



5 Different Orbits in Every Lan

closet and bath tub. The pairs of of white and black buckets require exposure control to discern details. Also shown is a more complex overturned subway rail car disaster. All such scenarios get embedded with scoring tasks totaling 100 points.





CAPTURE IMAGES OF THE INSCRIBED RINGS AND PE increasingly small Concentric Cs gaps to correct (1 of 8) orientations.

- First align with each PERPENDICULAR BUCKET to capture a SINGLE ALIGNMENT IMAGE of the inscribed ring.
- Score captured images with
 - UNBROKEN RINGS (5 points)
 - BROKEN RINGS (1 point)
 - NO RINGS (0 points, strike through line)
- Accurate landings are not scored.
- during the trial when obvious or after the trial to eliminate discussions during the trial. Images can also be stored for documentation.



Teams Rotate Through Each Role

Each Pilot flies a 5-minute trial with help from others. A 3-4 person team completes all 5 tests in 2 hours.





8

17

Four person teams always have one person getting their aircraft ready to launch right after the previous lands.

Three person teams work too, but require some time between each rotation to prepare the next aircraft.

PILOT

- Maintain control of the aircraft.
- Call out each intention of movement be
 —
 ing
- Call out each bucket alignment and acu square

PROCTOR

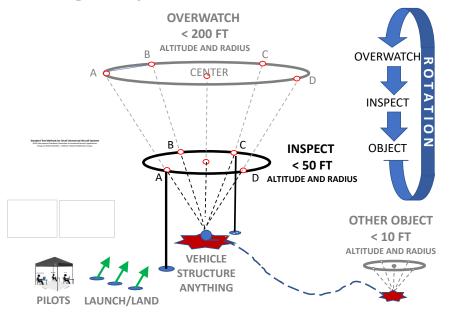
- Fill in the form header.
- Read the test procedures to the Pilot.
- Confirm, record, and attest to scoring after the trial.

VISUAL OBSERVER (VO)

- Maintain sight with the aircraft and surroundings.
- Repeat the Pilot's intention of movement to confirm.
- Call out corrections and warnings as necessary.

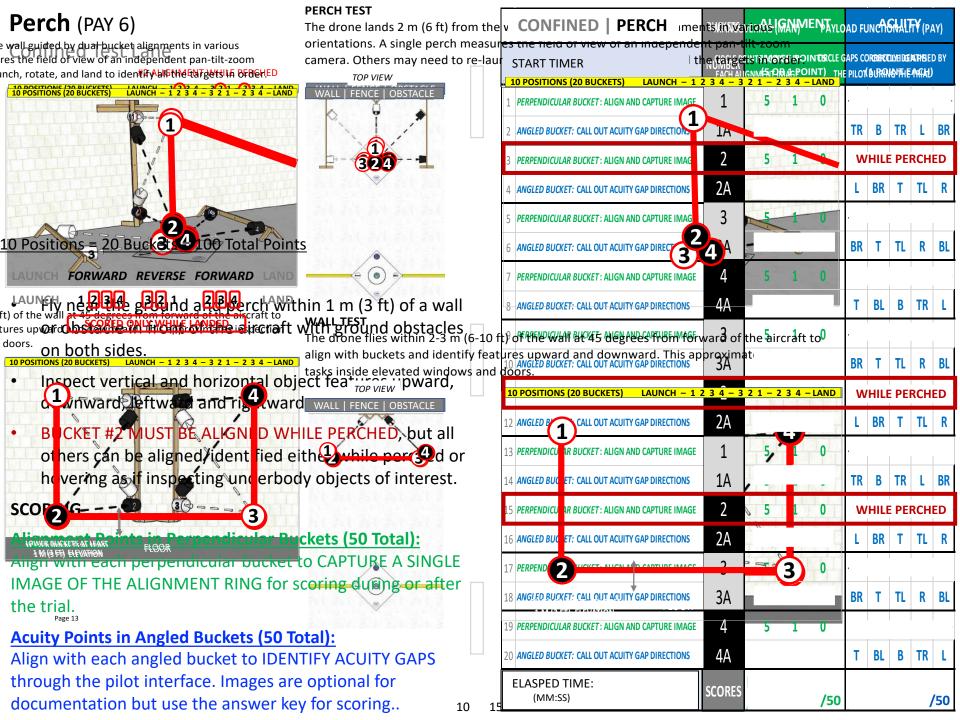
Teams Sequence Through Scenarios

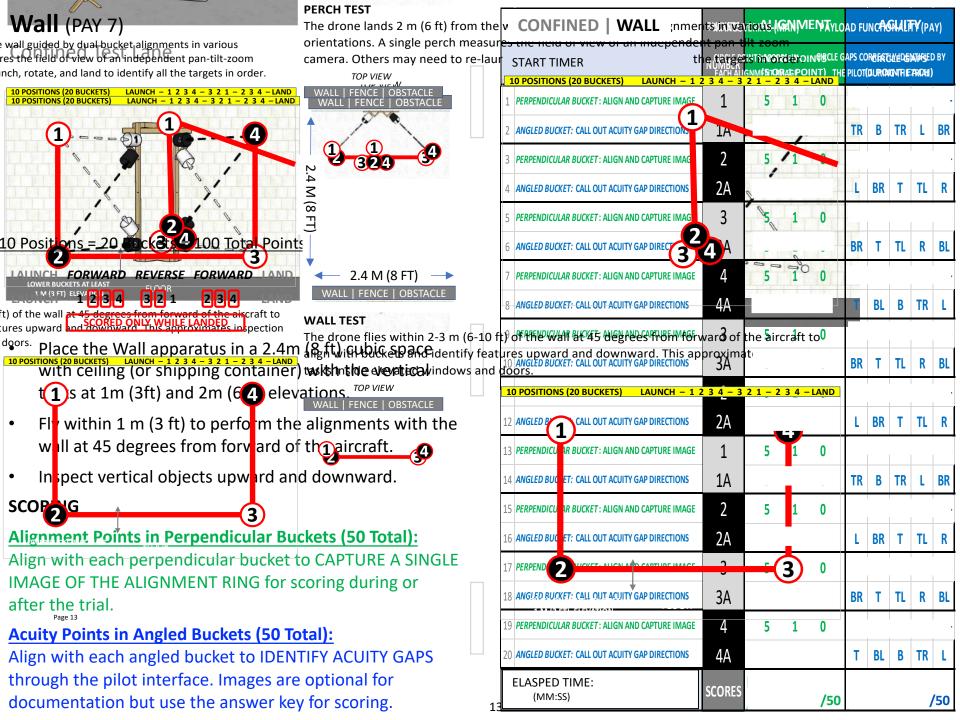
Each Pilot flies a 15-minute scenario, sequencing through 3 objectives for 5 minutes each.

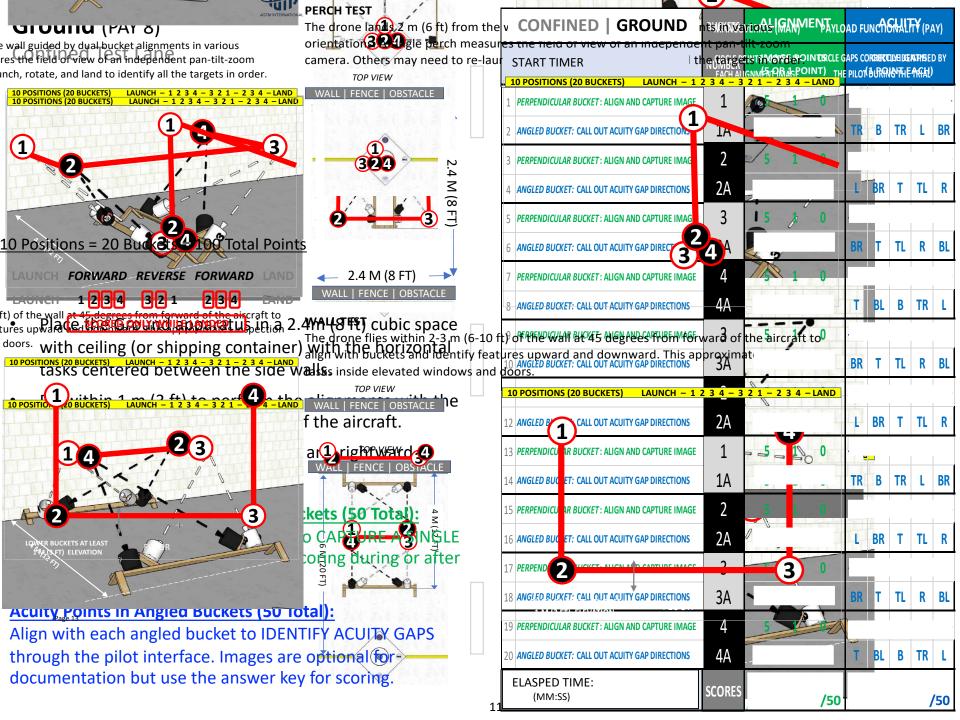


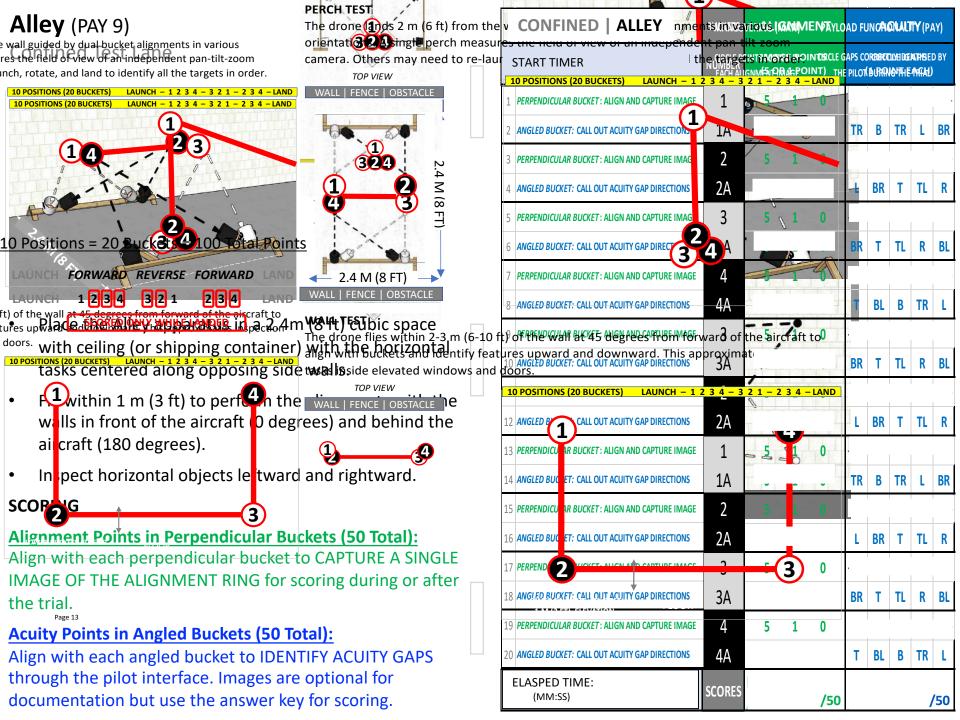
- This scenario mechanization enables embedded bucket scoring tasks to be performed similarly by all participating Pilots. So the results are comparable within the same scenario layout. Additional tactics can be overlayed onto these scenarios at your facility.
- Up to 3 teams concurrently fly different scenario objectives from safe distances and altitudes apart.
- Teams move as necessary to maintain sight lines with their aircraft and communications with other teams.

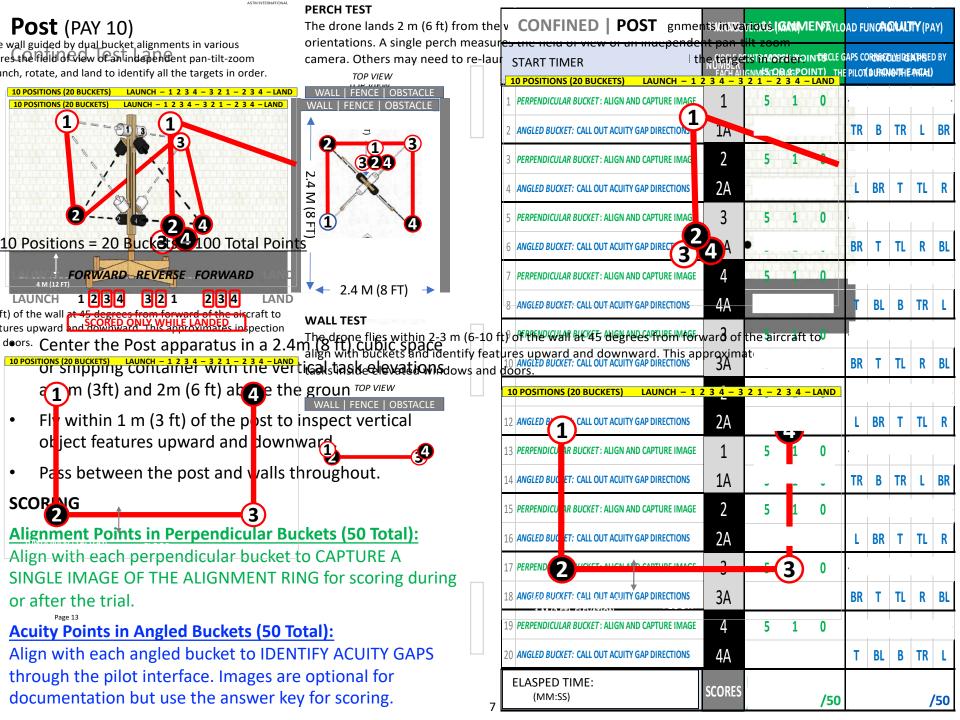
 The overwatch team leads communications.
- Scenarios restart every 20 minutes with a different rotation of Pilot, Proctor, and VO.











Standard Test Methods for Small Unmanned Aircraft Systems Confined Vehicles in Spection The Central Spection Spection The Central Spection Specti n the wall guided by dual-bucket alignments in various leasures the field of view of an independent pan-tilt-zoom orientations. A single perch measures the he tatigetstyrografer oincircle gaps correcting liberstaties by camera. Others may need to re-laun START TIMER NAMBER I ANMÉRTORA ÉPOINT) THE PILOT É BRACH I LAUNCH - 1 2 3 4 - 3 2 1 - 2 3 4 - LAND BUCKI TOP VIEW II S 10 POSITIONS (20 BUCKETS) PERPENDICULAR BUCKET: ALIGN AND CAPTURE IMAGE DISTRIBUTED THROUGHOUT THE SCENARIO TR B TR L BR ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTION: ĺΑ PERPENDICULAR BUCKET: ALIGN AND CAPTURE IMAG BR T TL R ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS PERPENDICULAR BUCKET: ALIGN AND CAPTURE IMAG 0 4Et 4. Total Points 10 Positi ANGLED BUCKET: CALL OUT ACUITY GAP DIRECT BR T TL R BL LAUNCH FORWARD REVERSE FORWARD LAND 0 PERPENDICULAR BUCKET: ALIGN AND CAPTURE IMAGE 1234 2 3 4 BL B TR L **ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS** y features upward and downward. This approximates in spection rone flies within 2-3 m (6-10 ft) of the Wall at 45 degrees Trem forward of the aircraft to 0 vith buckets and dentify features upward and downward. This approximate 10 POSITIONS (20 BUCKETS) LAUNCH - 1 2 3 4 - 3 2 1 - 2 3 4 - LAND BL l TL e elevated windows and doors. TOP VIEW LAUNCH - 1 2 3 4 - 3 2 1 - 2 3 4 - LAND WALL | FENCE | OBSTACLE 6A TR B TR L BR 12 ANGLED B CALL OUT ACUITY GAP DIRECTIONS R BUCKET: ALIGN AND CAPTURE IMAGE 13 PERPENDICU 7A 14 ANGLED BUC ET: CALL OUT ACUITY GAP DIRECTIONS BR T TL 8 15 **PERPENDICU** AR BUCKET: ALIGN AND CAPTURE IMAGE **VEHICLES** 8A TL WER BUCKETS AT LEAST 1 M (3 FT) ELEVATION 16 ANGLED BUC ET: CALL OUT ACUITY GAP DIRECTIONS ٥ 9A BL В TR 18 ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS 10 19 PERPENDICULAR BUCKET: ALIGN AND CAPTURE IMAGE 10A BL R TL L BL 20 ANGLED BUCKET: CALL OUT ACUITY GAP DIRECTIONS **ELASPED TIME: SCORES** (MM:SS) /50 /50 20

