

Scoring

[5] Acuity targets A-B-C-D inside bottom of all[2] Perch acuity targets inside and bottom of A

Capture in

ALIGN WITH BUCKETS AND LAND ACURATELY

20 ALIGNMENTS TOTAL UP TO 100 POINTS



to guide alignment and a visual acuity target with

- Align with each bucket to capture at SINGLE IMAGE of the inscribed alignment ring. Only the first image is scored.
- Score captured images as:
 - UNBROKEN RINGS (5 points)
 - BROKEN RINGS (1 point)
 - NO RINGS (0 points, strike through line)
- Score accurate landings as:
 - CENTERED (5 pts) with the aircraft center point inside the 60 cm (24 in) diameter circle.
 - OFFSETT (12 pts): withdatrleasts one propellering the slotted leg extensions so the angled buckets are at 45 degrees. motor inside the circle.

4

• Verification of captured alignment images can be during the trial when obvious or after the trial to eliminate discussions during the trial. Images can also be stored for documentation.





Y ACUITY re controls.

ric C gap Proctor.

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Completen Wisual On Deck Twittle every bucket in the sequence and land accurately according to the procedure. The Four person treams alloways have one person getting their objective score for the previous lands.

Withoute poking mistakes work too, but require some time between each rotation to prepare the next aircraft.

Score: POr complete trials, track your scores over time.

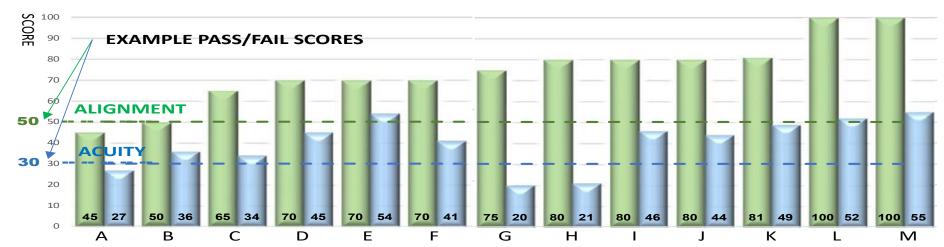
The average of your last five aircraft Call out each interntion of movement before doing so. of your proficiency on the aircraft and interface used. Call out each bucket alignment and acuity target gap.

PROCTOR

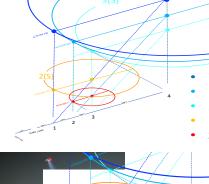
Efficiency (Optional): For complete trials with maximum scores for a particula pair control of particular partity partition particul

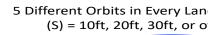
Separate Scores: ALIGNMENT and ACUITY

Track and Compare Scores Using the Same Drone









7(S)

6(S)

Teams Rotate Through Each Role

Each Pilot flies a 5-minute trial with help from others. A 3-4 person team completes all 5 tests in 2 hours.



Four person teams always have one person getting their aircraft ready to launch right after the previous lands.

Three person teams work too, but require some time between each rotation to prepare the next aircraft.

PILOT

- Maintain control of the aircraft.
- Call out each intention of movement be
- Call out each bucket alignment and acu kt gap.

ng so.

6

PROCTOR

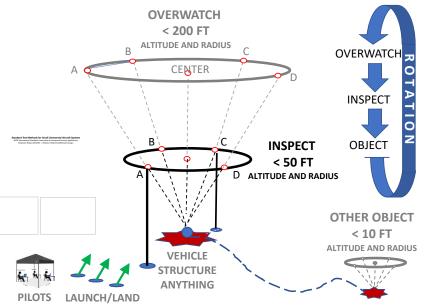
- Fill in the form header.
- Read the test procedures to the Pilot.
- Confirm, record, and attest to scoring after the trial.

VISUAL OBSERVER (VO)

- Maintain sight with the aircraft and surroundings.
- Repeat the Pilot's intention of movement to confirm.
- Call out corrections and warnings as necessary.

Teams Sequence Through Scenarios

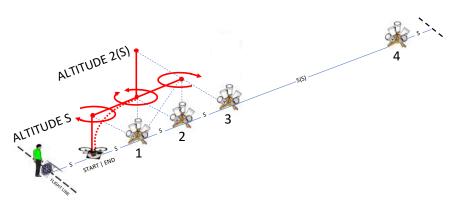
Each Pilot flies a 15-minute scenario, sequencing through 3 objectives for 5 minutes each.



- This scenario mechanization enables embedded bucket scoring tasks to be performed similarly by all participating Pilots. So the results are comparable within the same scenario layout. Additional tactics can be overlayed onto these scenarios at your facility.
- Up to 3 teams concurrently fly different scenario objectives from safe distances and altitudes apart.
- Teams move as necessary to maintain sight lines with their aircraft and communications with other teams. The overwatch team leads communications.
- Scenarios restart every 20 minutes with a different rotation of Pilot, Proctor, and VO.

Position (MAN/PAY 1)

Open Test Lane

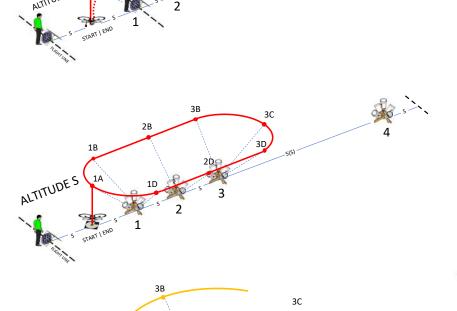


- Demonstrate positive aircraft control using basic flight MAN maneuvers between designated hover positions, orientations, and altitudes along the lane centerline.
- Perform a series of maneuvers including climb, wescend, vaw, pitch, and roll to simultaneously align with down waxd and forward buckets in each position.
- band accurately on the platform with the chassis CENTERED (5 pts) within the 60 cm (24 in) diameter circle, or OFFSET (1 pt) at least one motor in the circle.

• ORBIAlignment Points: Gapture a SINGLE IMAGE of each MANalignment ing throughout 1 ap through 10 positions with 20 buckets and accurate and ings to score up to 100 alignment points

Acuity Points: While aligned with each bucket, identify as many acuity target gaps as possible to Core up to 100 acuity points.

| OPEN TEST LANE POSITION | ALIGNMENT | | | | ACUITY | | | | |
|--|-----------------------------|--------------|--------|------------|--------------------------------|---------------|-----------------|--------------|---------------|
| START TIMER | | lign Cket | | AGE NTS | CORRECT GAPS (1 POINT EACH) | | | | |
| LAUNCH AND HOVER OVER STAND #1 ALIGN WITH BOTH BUCKETS 2 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD | HOVER | 1 2A | 5 5 | 1 | T | BL BR | R T | BR TL | L R |
| 3 YAW LEFT 360° OVER STAND #1 ALIGN WITH BOTH BUCKETS 4 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD | YAW L-360 | 1 2A | 5 5 | 1 | T | BL BR | R T | BR TL | L |
| 5 YAW <u>RIGHT</u> 360° OVER STAND #1 ALIGN WITH BOTH BUCKETS 6 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD |) YAW R-360 | 1 2A | 5 | 1 | T | BL | R | BR | L |
| 7 CLIMB VERTICALLY OVER STAND #1 ALIGN WITH BOTH BUCKETS 8 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD | CLIMB | 1 3A | 5 5 | 1 | T BR | BL T | R TL | BR R | L BI |
| 9 PERCEND VERTICALLY OVER STAND #1 ALIGN WITH BOTH BUCKETS C CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD | DESCEND | 1 2A | 5 | 1 | T | BL | R | BR | L |
| PITCH FORWARD TO STAND #2 ALIGN WITH BOTH BUCKETS 12 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD | FWD | 2 3A | 5 | 1 | BL | T | BR | R | TI |
| 13 ALIGN WITH BOTH BUCKETS 14 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD | BKWD | 1 2A | 5 5 | 1 | T | BL BR | R T | BR TL | L |
| 15 ALIGN WITH BOTH BUCKETS 16 CAPTURE ONE IMAGE DOWNWARD THEN ONE IMAGE FORWARD | FWD-L180 | 7 10 | 5 5 | 1 | <u>TR</u> BR | <u>B</u> R | <u>11</u> 11 | <u>L</u> | <u>B</u> |
| 17 ALIGN WITH BOTH BUCKETS CANTURE ONE MAGE FORMANIA BD THEN ONE MAGE FORMARD |) FWD-R18 | L 1A | 5 | 1 | В | TR | L | BL | Т |
| Image of the image downward then one image forward 19 LAND IN CIRCLE CENTERED (5 PTS) OR OFFSET (1 PT) COUNT SINGLE LANDING TWICE FOR ALIGNMENT SCORE 20 CAPTURE ONE IMAGE OF P1 AND P2 ACUITY TARGETS | 30 LAND | P1 P2 | 5 | 1 | TR BL L | B R BR | TR TL T | L L TL | BI BI B |
| STOP TIMER | | | | /100 | | | | | /10 |
| ELAPSED TIME (MM : SS) | PASS FAIL (CIRCLE ONE) | | | | | PAS: | | | |



- Fly sideways parallel to objects while looking forward to videntify features as if along a road, truck, bus, while looking features as if along as road, truck, bus
- Maintain altitude (5) throughout to complete two laps in both directions around the first three omni stands.
- Land accurately on the platform with the chassis
 GENTERED (5 pts) within the 60 cm (24 in) diameter circle, or OFFSET (1 pt) at least one motor in the circle.
- Alignment Points: Capture a SINGLE IMAGE of each alignment ring throughout 2 laps with 20 buckets and accurate landings to score up to 100 alignment points.
 MANIPAY A
 Manual Points: While aligned with each bucket, identify
- Acuity Points: White stighted with each bucket, identify as many acuity target gaps as possible to score up to 100 ອະບັນັ້ນ points.

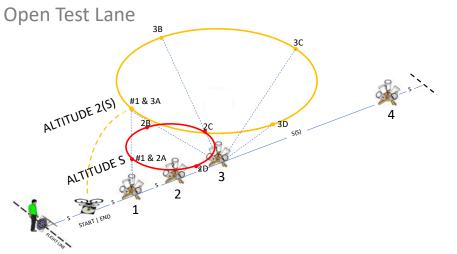
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| OPEN TEST LANE TRAVERSE | | ALIGN | | ACUITY | | | | |
|---|-------------|--------------|-----------------|--------------|-----------------------|----|----|------|
| START TIMER | | lign Cket | IMAGE POINTS | | CORRECT (1 POINT E | | | |
| 1 HOVER OVER THE LAUNCH AT ALTITUDE S | | 1A | 51 | TR | В | TR | L | BR |
| 2 ORBIT 90° LEFTWARD AROUND STAND #1 | | 1B | 51 | R | TL | т | BL | В |
| 3 ROLL LEFTWARD TO STAND #2 | | 2B | 51 | TL | R | TR | L | BR |
| 4 ROLL LEFTWARD TO STAND #3 | ALT S | 3B | 51 | в | TR | R | BL | т |
| 5 ORBIT 90° LEFTWARD AROUND STAND #3 | 1 | 3C | 51 | BL | R | BL | т | BR |
| 6 ORBIT 90° LEFTWARD AROUND STAND #3 | LEFTWARD | 3D | 51 | L | TL | R | BR | т |
| 7 ROLL LEFTWARD TO STAND #2 | Ő | 2D | 51 | TR | В | TL | В | BL |
| 8 ROLL LEFTWARD TO STAND #1 | | 1D | 51 | в | TL | R | BL | т |
| 9 ORBIT 90° LEFTWARD AROUND STAND #1 | | 1A | 51 | TR | В | TR | L | BR |
| 0 LAND IN CIRCLE (5 PTS CENTERED, 1 PT OFFSET) | | P1 | 51 | BL | R | TL | L | BL |
| | | 1A | 5 1 | TR | В | TR | L | BR |
| 2 ORBIT 90° RIGHTWARD AROUND STAND #1 | | 1D | 51 | В | TL | R | BL | Н |
| 3 ROLL RIGHTWARD TO STAND #2 | | 2D | 5 1 | TR | В | TL | В | BL |
| 4 ROLL RIGHTWARD TO STAND #3 | ALT S | 3D | 5 1 | L | TL | R | BR | т |
| 15 ORBIT 90° RIGHTWARD AROUND STAND #3 | - RIGI | 3C | 5 1 | BL | R | BL | т | BR |
| 6 ORBIT 90° RIGHTWARD AROUND STAND #3 | - RIGHTWARD | 3B | 51 | В | TR | R | BL | Т |
| 7 ROLL RIGHTWARD TO STAND #2 | RD | 2B | 5 1 | TL | R | TR | L | BR |
| 8 ROLL RIGHTWARD TO STAND #1 | | 1B | 5 1 | R | TL | т | BL | В |
| I9 ORBIT 90° RIGHTWARD AROUND STAND #1 | | 1A | 5 1 | TR | В | TR | L | BR |
| 20 LAND IN CIRCLE (5 PTS CENTERED, 1 PT OFFSET) | | P2 | 51 | L | BR | T | TL | В |
| STOP TIMER | | | | | | | | |
| | | | /10 | 0 | | | | /100 |
| ELAPSED TIME | F | PASS | P | PASS FAIL | | | | |
| (MM : SS) | | (CIRCL | E ONE) | (CIRCLE ONE) | | | | |

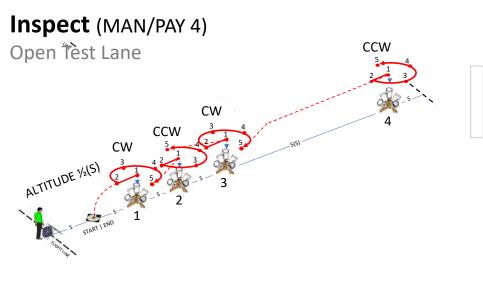
Orbit (MAN/PAY 3)



- Orbit an object at an equal altitude and radius while looking inward to identify features on four sides.
- Each orbit includes 5 bucket alignments: 1 downward radius check plus 4 angled buckets all around.
- Start aligned over omni stand #1 at altitude 2(S) to set the orbit radius around omni stand #3. Orbit both directions ending at the start point.
- Descend over omni stand #1 to altitude S to set the orbit radius around omni stand #2. Orbit both directions. Accurate landings are not included.
- Alignment Points: Capture a SINGLE IMAGE of each alignment ring throughout 4 orbits (leftward and rightward at each altitude) with 20 buckets to score up to 100 alignment points.
- Acuity Points: While aligned with each bucket, identify as many acuity target gaps as possible to score up to 100 acuity points.

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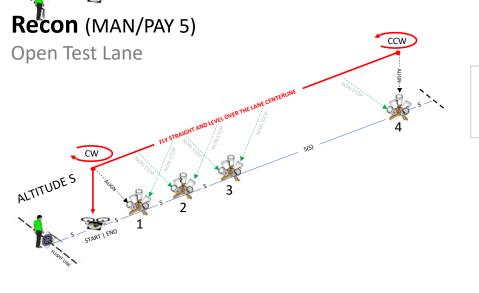
| OPEN TEST LANE ORBIT | | ALIGN | IMENT | ACUITY | | | | |
|--|--------------------------|--------------|-----------------|--------------------------------|--|--|--|--|
| START TIMER | | lign Cket | IMAGE POINTS | CORRECT GAPS (1 POINT EACH) | | | | |
| 1 ALIGN OVER STAND #1 AT ALT 2(S) CHECK RADIUS | A | 1 | 51 | T BL R BR L | | | | |
| 2 ALIGN WITH BUCKET 3A CHECK ALTITUDE | ALT 2(S) - | 3A | 51 | BR T TL R BL | | | | |
| 3 ORBIT LEFTWARD 90° | | 3B | 51 | B TR R BL T | | | | |
| 4 ORBIT LEFTWARD 90° | LEFTWARD | 3C | 51 | BL R BL T BR | | | | |
| 5 ORBIT LEFTWARD 90° | | 3D | 51 | L TL R BR T | | | | |
| 6 ALIGN OVER STAND #1 AT ALT 2(S) CHECK RADIUS | AL | 1 | 51 | T BL R BR L | | | | |
| 7 ALIGN WITH BUCKET 3A CHECK ALTITUDE | ALT 2(S) | 3A | 51 | BR T TL R BL | | | | |
| 8 ORBIT RIGHTWARD 90° | – RIGHTWARD | 3D | 51 | L TL R BR T | | | | |
| 9 ORBIT RIGHTWARD 90° | HTWA | 3C | 5 1 | BL R BL T BR | | | | |
| 10 ORBIT RIGHTWARD 90° | RD | 3B | 51 | B TR R BL T | | | | |
| 11 ALIGN OVER STAND #1 AT ALT S CHECK RADIUS | | 1 | 5 1 | T BL R BR L | | | | |
| 12 ALIGN WITH BUCKET 2A CHECKALTITUDE | ALT S | 2A | 5 1 | L BR T TL R | | | | |
| 13 ORBIT LEFTWARD 90° | | 2B | 5 1 | TL R TR L BR | | | | |
| 14 ORBIT LEFTWARD 90° | LEFTWARD | 2C | 5 1 | T BL R TL B | | | | |
| 15 ORBIT LEFTWARD 90° | | 2D | 51 | TR B TL B BL | | | | |
| 16 ALIGN OVER STAND #1 AT ALT S CHECK RADIUS | 1 | 1 | 5 1 | T BL R BR L | | | | |
| 17 ALIGN WITH BUCKET 2A CHECKALTITUDE | ALT S - | 2A | 5 1 | L BR T TL R | | | | |
| 18 ORBIT RIGHTWARD 90° | - RIGH | 2D | 5 1 | TR B TL B BL | | | | |
| 19 ORBIT RIGHTWARD 90° | RIGHTWARD | 2C | 51 | T BL R TL B | | | | |
| 20 ORBIT RIGHTWARD 90° | | 2B | 51 | TL R TR L BR | | | | |
| STOP TIMER | | | | | | | | |
| STOT HIMEN | | | /100 | /100 | | | | |
| ELAPSED TIME | PASS FAIL PASS FA | | | | | | | |
| (MM : SS) | (CIRCLE ONE) (CIRCLE ONE | | | | | | | |



- Fly around objects in close proximity to inspect detailed features on the top and all four sides.
- Maintain altitude 1/2(S) throughout starting on top of each omni stand then rotate around all four omni bucket stands in alternating clockwise (A-B-C-D) and counter clockwise (A-D-C-B) directions.
- Accurate landings are not included.
- Alignment Points: Capture a SINGLE IMAGE of each alignment ring throughout 4 omni stands with 20 buckets to score up to 100 alignment points.
- Acuity Points: While aligned with each bucket, identify as many acuity target gaps as possible to score up to 100 acuity points.

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| OPEN TEST LANE INSPECT | ALI | GNMENT | ACUITY | | | | |
|---|----------------------|--------------|--------------------------------|--|--|--|--|
| START TIMER | ALIGN BUCKE | | CORRECT GAPS (1 POINT EACH) | | | | |
| 1 HOVER OVER STAND #1 AT ALTITUDE 1/2(S) | A | 5 1 | T BL R BR L | | | | |
| 2 PITCH BACKWARD | т %(S) | A 5 1 | TR B TR L BR | | | | |
| 3 ORBIT LEFTWARD 90° | ́ <mark></mark> 1 | B 5 1 | R TL T BL B | | | | |
| 4 ORBIT LEFTWARD 90° | ALT ½(S) – LEFTWARD | C <u>5</u> 1 | BR R TL L BR | | | | |
| 5 ORBIT LEFTWARD 90° | 1 | D 51 | B TL R BL T | | | | |
| 6 HOVER OVER STAND #2 AT ALTITUDE 1/2(S) | ALT | 5 1 | BL T BR R TL | | | | |
| 7 PITCH BACKWARD | ALT ½(S) – | A 51 | L BR T TL R | | | | |
| 8 ORBIT RIGHTWARD 90° | -RIGH 2 | 5 1 | TR B TL B BL | | | | |
| 9 ORBIT RIGHTWARD 90° | RIGHTWARD | C 5 1 | T BL R TL B | | | | |
| 10 ORBIT RIGHTWARD 90° | ଁ 2 | B 51 | TL R TR L BR | | | | |
| 11 HOVER OVER STAND #3 AT ALTITUDE 1/2(S) | _ ≥ 3 | 5 1 | R TL B BL R | | | | |
| 12 PITCH BACKWARD | ALT ½(S) – LEFTWARD | A 51 | BR T TL R BL | | | | |
| 13 ORBIT LEFTWARD 90° | 3 | B 5 1 | B TR R BL T | | | | |
| 14 ORBIT LEFTWARD 90° | TWAR 3 | C <u>5</u> 1 | BL R BL T BR | | | | |
| 15 ORBIT LEFTWARD 90° | 3 | D 51 | L TL R BR T | | | | |
| 16 HOVER OVER STAND #4 AT ALTITUDE 1/2(S) | ALT | 5 1 | TL B TR R BR | | | | |
| 17 PITCH BACKWARD | 4/ | A 51 | T BL B TR L | | | | |
| 18 ORBIT RIGHTWARD 90° | - RIGH | D 5 1 | BR B TL B TR | | | | |
| 19 ORBIT RIGHTWARD 90° | ALT ½(S) – RIGHTWARD | C 5 1 | R BL T TR B | | | | |
| 20 ORBIT RIGHTWARD 90° | 8 4 | B 51 | TR L BL R TL | | | | |
| STOP TIMER | | | | | | | |
| | _ | /100 | /100 | | | | |
| ELAPSED TIME | PAS | S FAIL | PASS FAIL | | | | |
| (MM : SS) | (CIF | CLE ONE) | (CIRCLE ONE) | | | | |



- Fly straight and level at a sustainable speed directly over the lane centerline to establish a stable hover over an object and perform quick reconnaissance tasks.
- Maintain altitude (S) throughout starting over the launch/land platform to align with the designated targets at both ends of the lane.
- A complete trial totals a distance of 80(S).
- Accurate landings are not included.
- Alignment Points: Capture a SINGLE IMAGE of each alignment ring throughout 5 laps with 20 buckets to score up to 100 alignment points.
- Acuity Points: While aligned with each bucket, identify as many acuity target gaps as possible to score up to 100 acuity points.

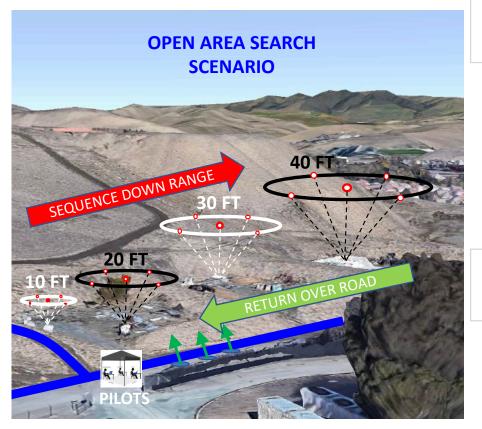
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| OPEN TEST LANE RECON | ALIGNMENT | | | | ACUITY | | | | |
|---|-------------------------|----|-----------------|------|-------------|-----|-----------|----|-----------|
| START TIMER | ALIGN BUCKET | | IMAGE POINTS | | CORRECT GAP | | | | |
| 1 FLY AT ALTITUDE S TO STAND #4 | | 4 | 5 | 1 | TL | В | TR | R | BR |
| 2 YAW LEFT 180° | LAP | 7 | 5 | 1 | <u>BR</u> | I | BL | Ŀ | <u>TL</u> |
| 3 FLY TO THE LAUNCH AND YAW RIGHT 180° | 1 | L | 5 | 1 | в | TR | L | BL | т |
| 4 HOVER IN PLACE CHECK ALTITUDE S | | 1A | 5 | 1 | TR | в | TR | L | BR |
| 5 FLY AT ALTITUDE S TO STAND #4 | LAP | 4 | 5 | 1 | TL | в | TR | R | BR |
| 6 YAW LEFT 180° | | 7 | 5 | 1 | <u>BR</u> | I | <u>BL</u> | L | ΤL |
| 7 FLY TO THE LAUNCH AND YAW RIGHT 180° | 2 | L | 5 | 1 | в | TR | L | BL | т |
| 8 HOVER IN PLACE CHECK ALTITUDE S | | 1A | 5 | 1 | TR | в | TR | L | BR |
| 9 FLY AT ALTITUDE S TO STAND #4 | LAP 3 | 4 | 5 | 1 | TL | в | TR | R | BR |
| 10 YAW LEFT 180° | | 7 | 5 | 1 | BR | I | BL | Ŀ | TL |
| 11 FLY TO THE LAUNCH AND YAW RIGHT 180° | | L | 5 | 1 | в | TR | L | BL | т |
| 12 HOVER IN PLACE CHECKALTITUDE S | | 1A | 5 | 1 | TR | в | TR | L | BR |
| 13 FLY AT ALTITUDE S TO STAND #4 | | 4 | 5 | 1 | TL | в | TR | R | BR |
| 14 YAW LEFT 180° | LAP | 7 | 5 | 1 | <u>BR</u> | I | <u>BL</u> | L | TL |
| 15 FLY TO THE LAUNCH AND YAW RIGHT 180° | 4 | L | 5 | 1 | в | TR | L | BL | т |
| 16 HOVER IN PLACE CHECKALTITUDE S | | 1A | 5 | 1 | TR | в | TR | L | BR |
| 17 FLY AT ALTITUDE S TO STAND #4 | | 4 | 5 | 1 | TL | в | TR | R | BR |
| 18 YAW LEFT 180° | LAP | 7 | 5 | 1 | <u>BR</u> | I | <u>BL</u> | Ŀ | TL |
| 19 FLY TO THE LAUNCH AND YAW RIGHT 180° | 5 | L | 5 | 1 | В | TR | L | BL | Т |
| 20 HOVER IN PLACE CHECK ALTITUDE S | | 1A | 5 | 1 | TR | В | TR | L | BR |
| STOP TIMER | | | | /100 | | | | | /100 |
| ELAPSED TIME | PASS FAIL | | | | PASS FAIL | | | | IL |
| (MM : SS) | (CIRCLE ONE) (CIRCLE ON | | | | | ONE |) | | |

Open Area Search Scenarios

Day and Night Trials



- Teams concurrently fly separate objectives set up at safe distances and/or altitudes apart (with a clearly designated and safe return path).
- Each pilot flies for 15 minutes across 3 different objectives for 5 minutes each. Teams move as necessary to maintain sight lines and communication.
- Scenarios restart with a different rotation of Pilot, Proctor, and VO.

| OPEN SCENARIO SEARCH | 1 | ALIGN | IMENT | ACUITY |
|---|-----------|--------------|-----------------|--------------------------------|
| START TIMER | | lign Cket | IMAGE POINTS | CORRECT GAPS (1 POINT EACH) |
| 1 HOVER OVER STAND #1 AT CHOSEN ALTITUDE | | 1 | 51 | T BL R BR L |
| 2 PITCH BACKWARD | LEFT | 1A | 51 | TR B TR L BR |
| 3 ORBIT LEFTWARD 90° | LEFTWARD | 1B | 51 | R TL T BL B |
| 4 ORBIT LEFTWARD 90° | | 1C | 51 | BR R TL L BR |
| 5 ORBIT LEFTWARD 90° | | 1D | 51 | B TL R BL T |
| 6 HOVER OVER STAND #2 AT CHOSEN ALTITUDE | RIG | 2 | 51 | BL T BR R TL |
| 7 PITCH BACKWARD | | 2A | 51 | LBRTTLR |
| 8 ORBIT RIGHTWARD 90° | RIGHTWARD | 2D | 51 | TR B TL B BL |
| 9 ORBIT RIGHTWARD 90° | 05 | 2C | 51 | T BL R TL B |
| 10 ORBIT RIGHTWARD 90° | | 2B | 51 | TL R TR L BR |
| 11 HOVER OVER STAND #3 AT CHOSEN ALTITUDE | | 3 | 51 | R TL B BL R |
| 12 PITCH BACKWARD | Ē | 3A | 51 | BR T TL R BL |
| 13 ORBIT LEFTWARD 90° | LEFTWARD | 3B | 51 | B TR R BL T |
| 14 ORBIT LEFTWARD 90° | RD | 3C | 5 1 | BL R BL T BR |
| 15 ORBIT LEFTWARD 90° | | 3D | 5 1 | L TL R BR T |
| 16 HOVER OVER STAND #4 AT CHOSEN ALTITUDE | | 4 | 51 | TL B TR R BR |
| 17 PITCH BACKWARD | RIC | 4A | 51 | T BL B TR L |
| 18 ORBIT RIGHTWARD 90° | RIGHTWARD | 4D | 5 1 | BR B TL B TR |
| 19 ORBIT RIGHTWARD 90° | ARD | 4C | 51 | R BL T TR B |
| 20 ORBIT RIGHTWARD 90° | | 4B | 51 | TR L BL R TL |
| STOP TIMER | | | | |
| | | | /100 | /100 |
| ELAPSED TIME | P | ASS | FAIL | PASS FAIL |
| (MM : SS) | (| CIRCLE | E ONE) | (CIRCLE ONE) |

AN POLICE COLLEGE, ONTARIO, CANADA

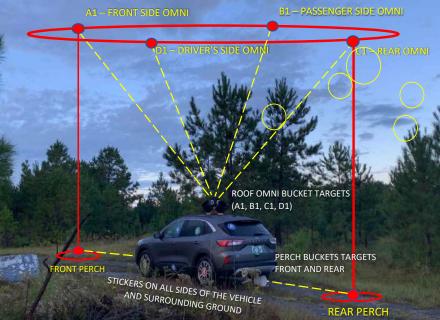
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A1 -

A2 -

C4 – F

CONCURRENT OBJECTIVES FOR 3 TEAMS TO FLY 20 FORWARD SPECTION BUILDING EXTRESHOR SEARCHercise ALTITUDE AND RADIUS OTHER OBJECT < 10 FT ALTITUDE AND RADIUS /FHICLF STRUCTURE ANYTHING LAUNCH/LAND 5 TARGETS TO IDENTIFY ON EACH SIDE = 20 TARGETS = 100 POINTS



A STATE OF THE AREA OF THE ALTITUDE 1/2(S) TURE PRE LAUNCH MAGE OF THE CLE THE PRE LAUNCH MAGE OF THE CLE THE PRE LAUNCH MAGE OF THE OF THE ALTITUDE 1/2(S) The R BL BUCKEGNMENTS HOVER OVER STAND #1 AT ALTITUDE 1/2(S) ALION BUCKE MAGE CORRECT GAPS FOIN' S (* POIN : EA 이상) DEBERLEVEN ARABABE®®® AEAL STURF 1/AGA #4 TOP TARGET: ORBIT LEFTWARD 90° GRINT BICHTWARD 90° GRINT BICHTWARD 90° GRINT BICHTWARD 90° GRINT LEFTWARD 90° GRINT LEFTWARD 90° GRINT BICHTWARD 90° Α ARATER WHISHER WAS SHELLOT CENET FIE (S) OR BIT LEFTWARD 90 INCLESSION WARD 90 INCLESSION 1D 3 FRONT HOVER OVER STAND #2 AT ALTITUDE 1/2(S) ORBIT RUGH OVER STAND #2 AT ALTITUDE 1/2(S) ORBIT RUGH OVER STAND #2 PITCH BACKWARD ORBIT RUGHTMEDE PERCH UNDERBODY BUCKET 34 40 ORBIT CHENNARD APSED TIME. В R TR BL TL 100 ORBIT RIGHTWARD 90° 322 TL PASSENGER ORBIT RIGHTWARD 90° T. Syekasteristeristing findet findetsom2(S) TR E3 TR R TO/TAb SCORE 34 HOVER OVER STAND #3 AT ALTITUDE 1/2(S) PECHTBASE MARDSIDE - EXTERIOR FEATURE 3A ITCH BACKWARD ReitPARSHTMARE FIRE - SURROUNDING GROUND EFT WARD OF OMNI BUCKET С R BL Ť TR B FTOP OMNEBUCKET 3G SERIE STANDER WINDOW CENTER 殆 5 REA TORBET LEENSEARD PE BR R h l C4 RECIPON BROPHER NET END SEATIMETITUDE 1/2(S) R BR ĸ /100 100 舫 PC5CHERGAWABERBODY BUCKET PL R BR D MOFTOP, OMNI, BUCKET В TL TR TOTAL 82 ₿⊦ ŦŔ В FRONTW 43 匙 R Æ D3" DRIVER SIDE D4 5 R BL T TR B 1 C3 – RI EGOSD SCRIESUNDING BEDUND OBJECT D5 5 100 BR B TL B /100 C5 – RI STOP TIMER D1 - DF TO/TAPISCORE /100 D2 – DF ELAPSED TIME (MM:SS) 3 D3 – D PASS | FAIL ELAPSED TIME PASS | FAIL D4 - DR (MM:SS) (CIRCLE ONE) (CIRCLE ONE) DE - DF