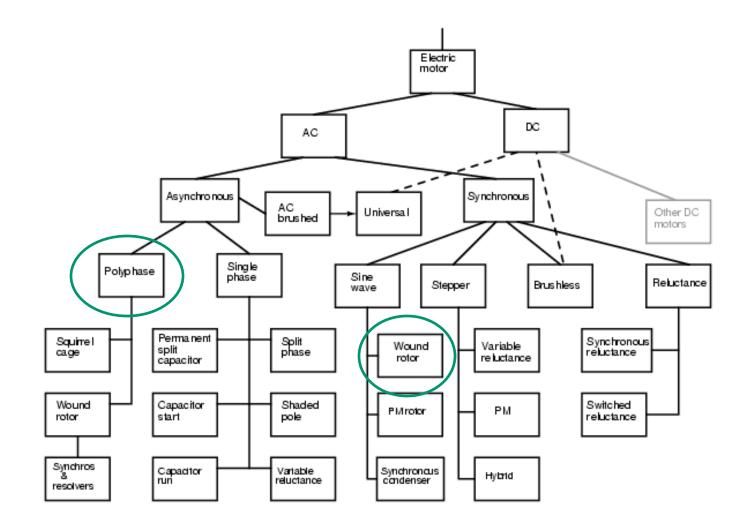
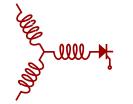
# Overview of Advanced HMW Motors

## T.A. Lipo

*WEMPEC* 

#### **Electric Motor Family Tree**



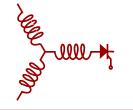


Constant Speed:

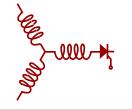
 Dominated by Induction Motors (90% in general) Synchronous Motors become Competitive beyond 3-5 MW

Variable Speed:

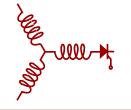
- Dominated by Induction Motors
- Significant Use of High MW Synchronous Motors
- PM Motor Use is Minimal (Using  $Nd_2Fe_{14}B$ )



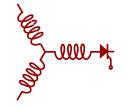
• Why Are Only Three Types of AC Motors Popular?

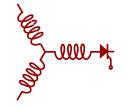


- Why Are Only Three Types of AC Motors Popular?
- What Are the Barriers to New Machine Topologies?

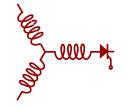


- Why Are Only Three Types of AC Motors Popular?
- What Are the Barriers to New Machine Topologies?
- How Can WBG Switching Devices Help?





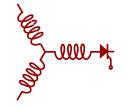
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(Magnets, Assembly, etc.)



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#2 Complexity

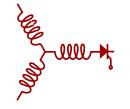




#1 COST!! Of Course!
(Magnets, Assembly, etc.)

#2 Complexity

#3 Inductance(?)

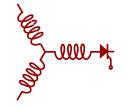


#### Electromechanical Energy Conversion Hinges Upon

 $P = i^*e$  (e = emf due to air gap flux)

Or

 $P = i(d\lambda/dt)$  ( $\lambda = air gap flux linkage$ )



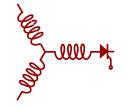
#### Electromechanical Energy Conversion Hinges Upon

Or

 $\mathsf{P}=\mathsf{i}(d\lambda/dt)$ 

But  $\lambda = Li + \lambda_{mag}$  and therefore

 $d\lambda/dt = i(dL/dt) + L(di/dt) + e_{mag}$ 



#### Electromechanical Energy Conversion Hinges Upon

Or

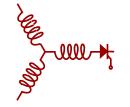
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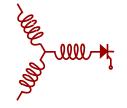
The friend! The enemy!

**WEMPEC** 

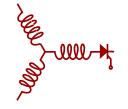


### i(dL/dt) The friend! Make dL/dt as large as possible! Implies: High speed Control of i (not v) is important.

L(di/dt) The enemy! Make L as small as possible! Air Gap Armature Winding Many Phases >3?

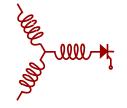


## How Can WBG Switching Devices Help?



#### WBG Device Attributes

- High Voltage
- High Efficiency
- High Temperature
- High Switching Frequency
- High Fundamental Frequency



Features of WBG Devices

#### WBG Device Attributes

- High Voltage
- High Efficiency
- High Temperature

High Switching Frequency

Benefit for Design of **Electrical Machines** 

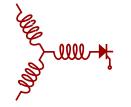
Questionable

Questionable

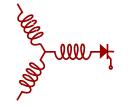
Questionable

Significant

 High Fundamental Frequency Significant



- A New Motor Side Filter Could Result in Nearly Zero THD Motor Voltage Waveforms
- Negligible Stator Copper and Iron Loss Due to Impressed Harmonics
- Possibility of Reduced Magnetics
  Line Side Filter, Line Side Transformer



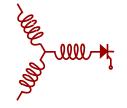
- Increased Differential and Common Mode EMI
- Bearing Current Issues
- Insulation Degradation

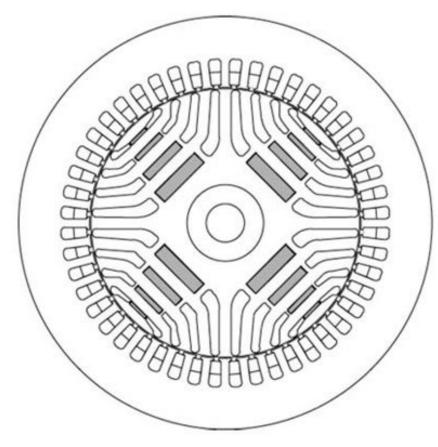


Other Machines Capable of Megawatt Ratings

- Switched (Variable) Reluctance Motor
- Synchronous Reluctance Motor
- PM Assisted Synchronous Reluctance Motor
- Spoke Type PM Motor
- Switched Flux Motor
- Transverse Flux Motor
- Vernier Motor

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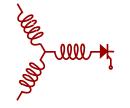


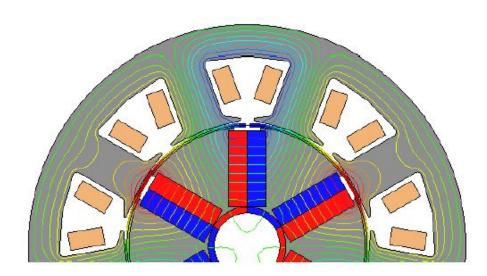
Characterized by:

- Good dL/dt
- High L
- Small  $d\lambda_{mag}/dt$
- Good Power Factor
- Expensive Rotor

Benefits from high switching frequency of WBG devices

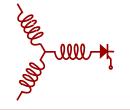
 Reduced torque ripple by current control



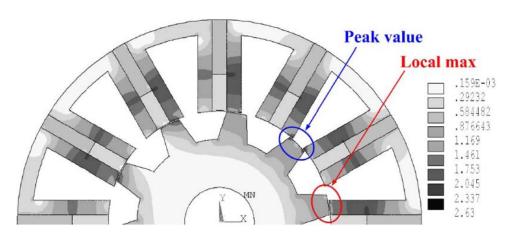


Characterized by:

- Low dL/dt
- Moderate L
- High  $d\lambda_{mag}/dt$
- Good Power Factor
- Expensive Rotor



Switched Flux Motors



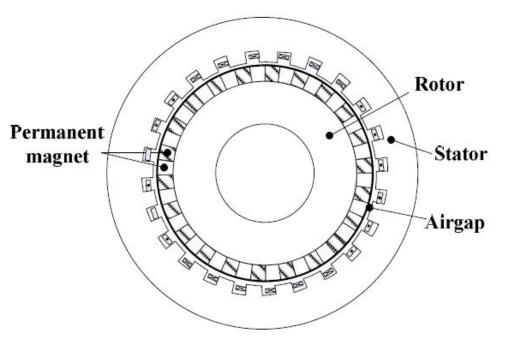
#### Characterized by:

- Low dL/dt
- High  $d\lambda_{mag}/dt$
- High L
- Expensive Stator Many magnets

Benefit from high switching frequency of WBG devices

- Improved torque precision
- Higher speed (frequency)





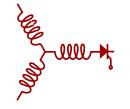
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J-IIII-¥



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- Spoke Type PM Motor
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- Transverse Flux Motor
- Vernier Motor

Where will the boundaries of machines be extended?

### High Speed Machines

- Compact Turbine Driven Power Source
- Energy Storage Systems

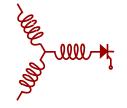
Low Speed Machines

- Directly Driven Wind Turbines
- Ocean and Tidal Wave Machines

High Temperature Machines (and Drives)

- Compact Mechanical Power Sources
- Switching Devices in the Motor Frame

HT Superconducting Machines



## Time for questions?