

# Greenhouse Gas Emissions A Case Study On The Calibration Of An L-pitot Static Tube

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## RATA Tests are often based on “S” Pitot Tubes

### Advantages:

- Cheap
- Simple design
- Doesn't plug



### Disadvantages:

- Questionable accuracy
- Problems with swirl

## 3-D Pitot Tubes

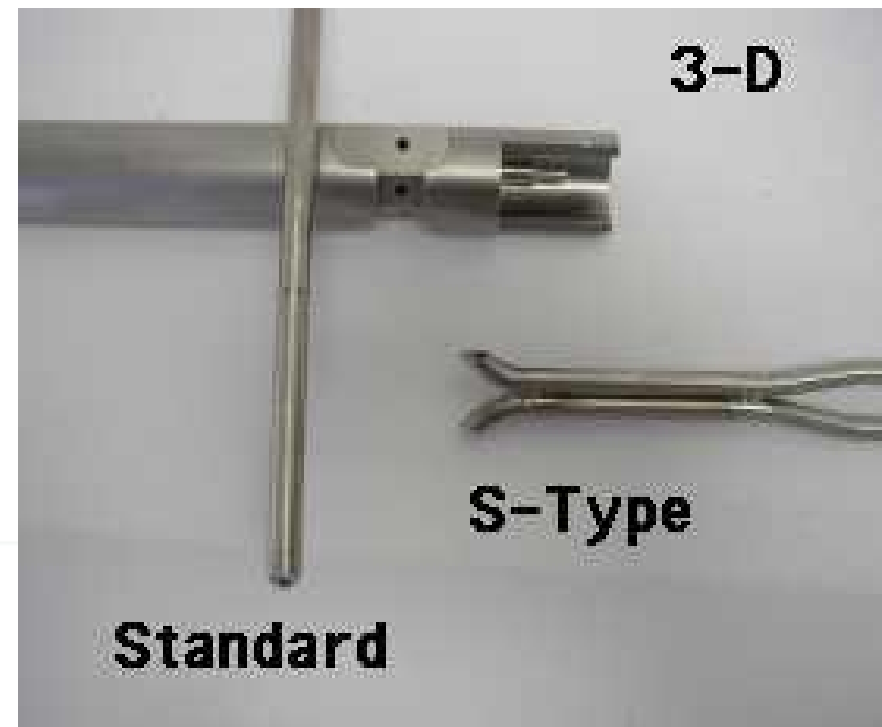
### Advantages:

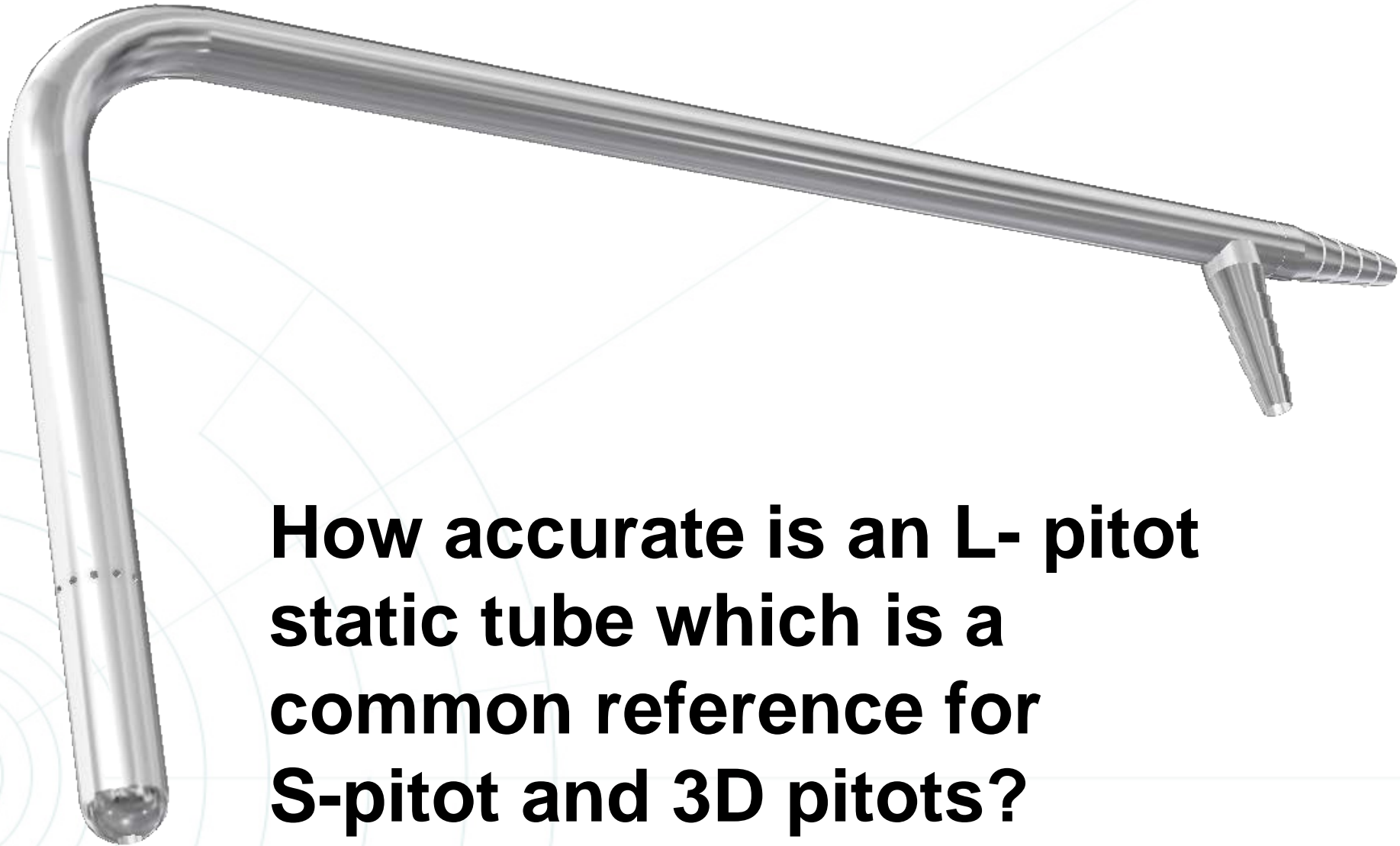
- Can measure swirl vectors (yaw)
- Can measure radial vectors (pitch)

### Problems:

- Requires calibration

EPA adds wind tunnel calibration requirements which are often based on L-pitot static tubes



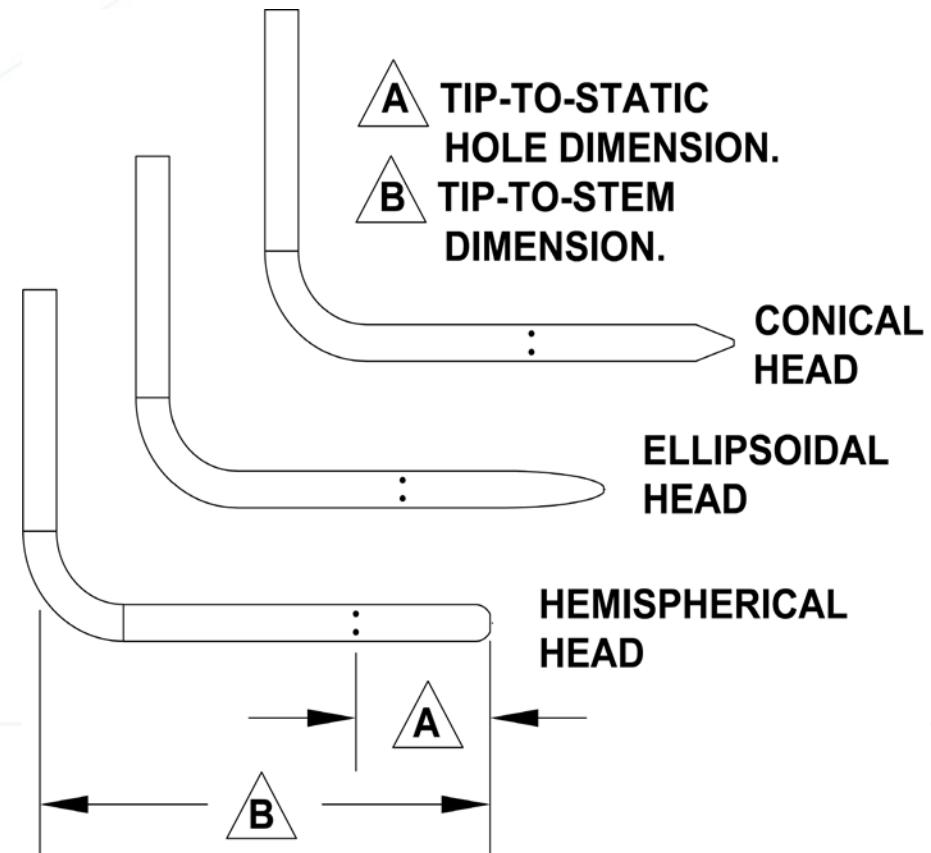
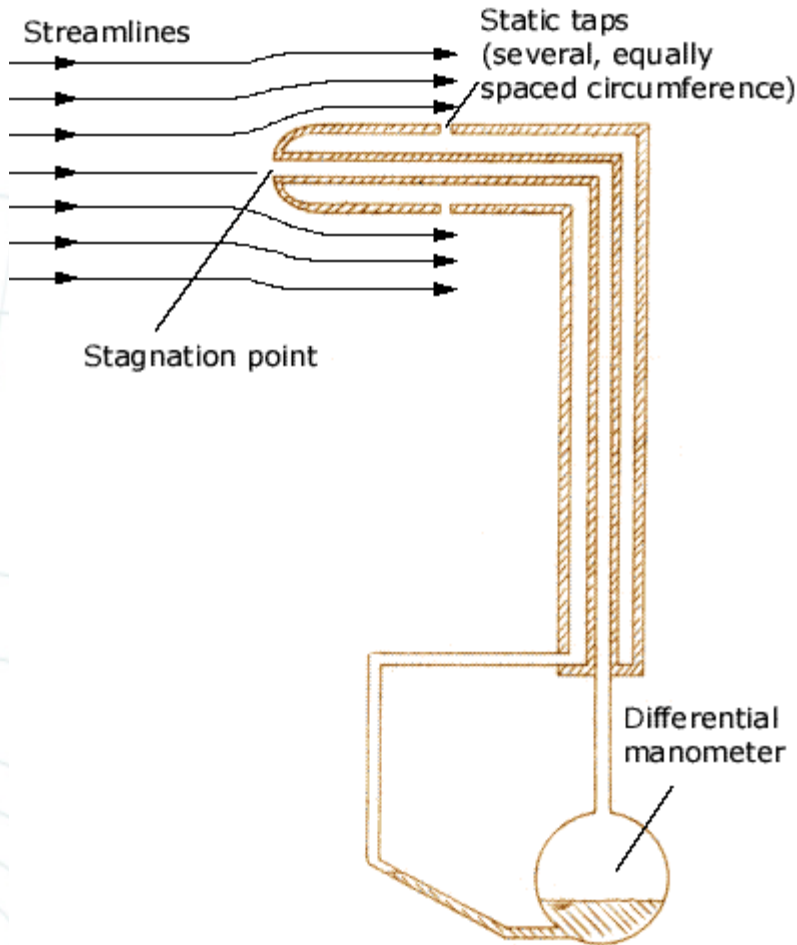


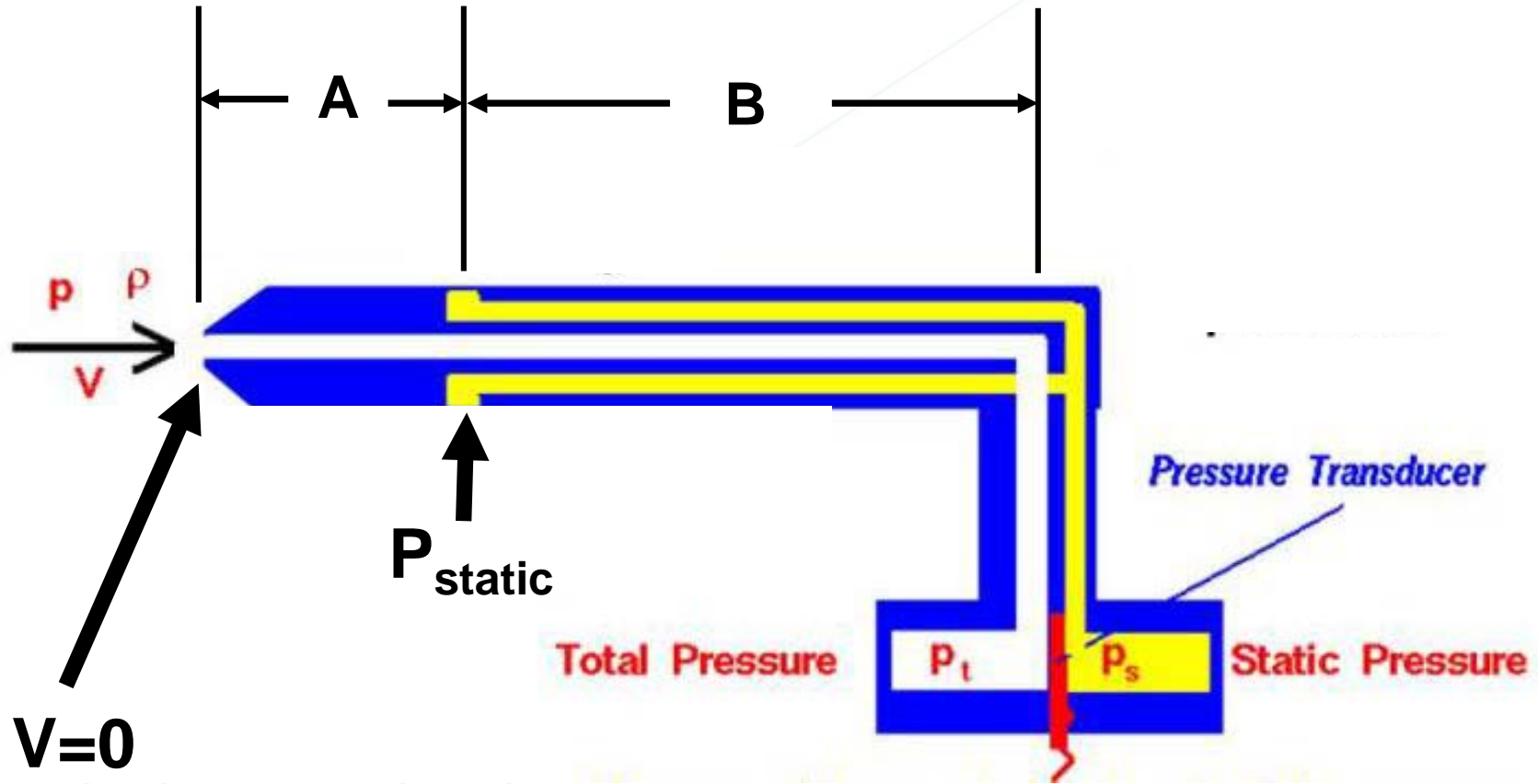
**How accurate is an L- pitot static tube which is a common reference for S-pitot and 3D pitots?**

**Alternate Calibration Methodology  
For Point-Velocity Devices  
(Pitot-Tubes, Anemometers, Hot-Wire Devices)  
Using NIST Traceable Mass Flow Measurement  
Standards**



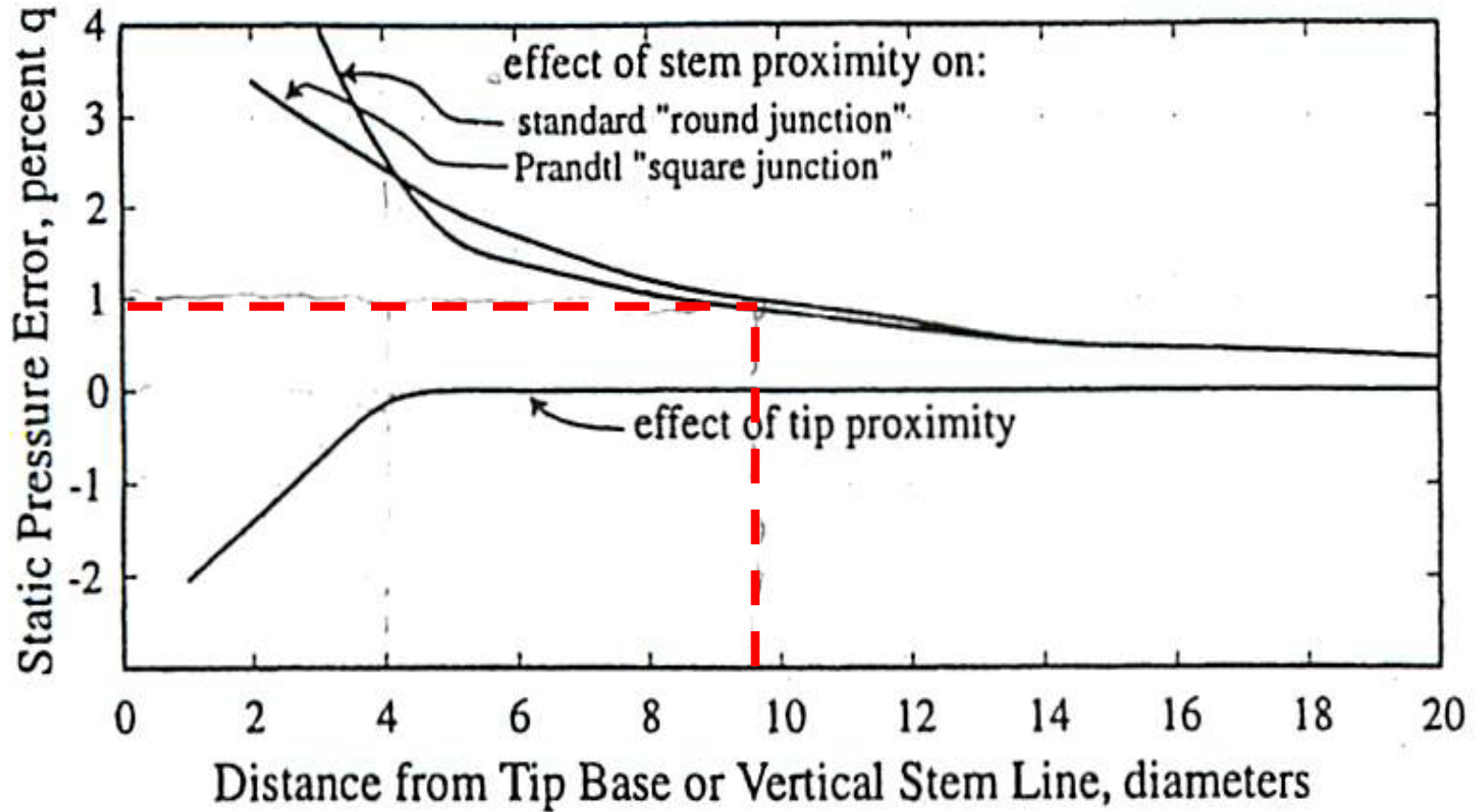
# Pitot-static In A Flow Stream





$V=0$

**Isentropic  
Compression**



**FIGURE 4.9** Effect of static orifice distance from tip or from stem: see Example 4.1.





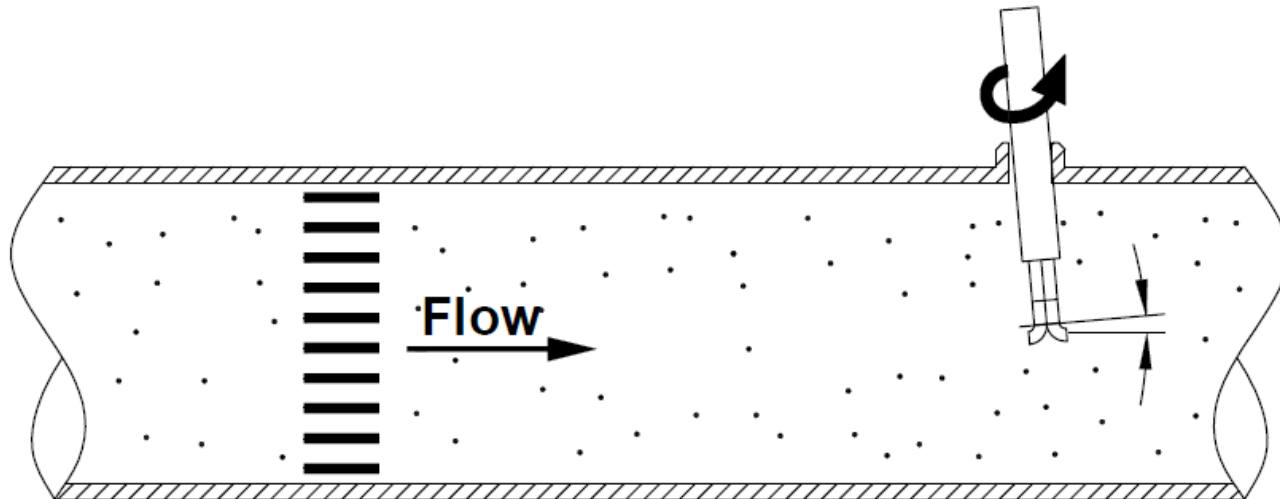
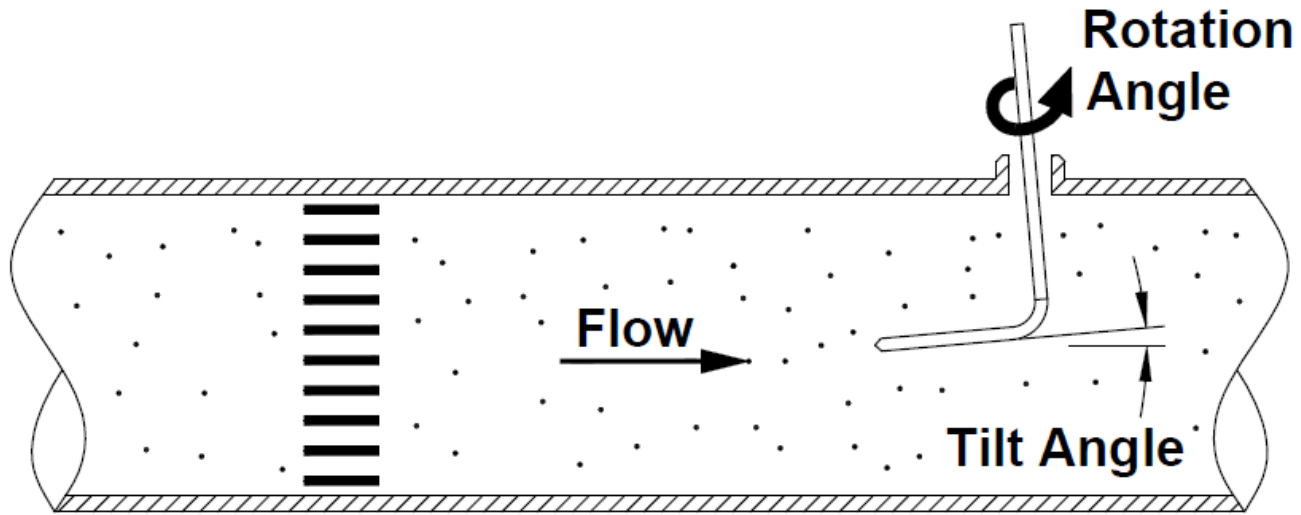
THE ROBINSON ANEMOMETER.

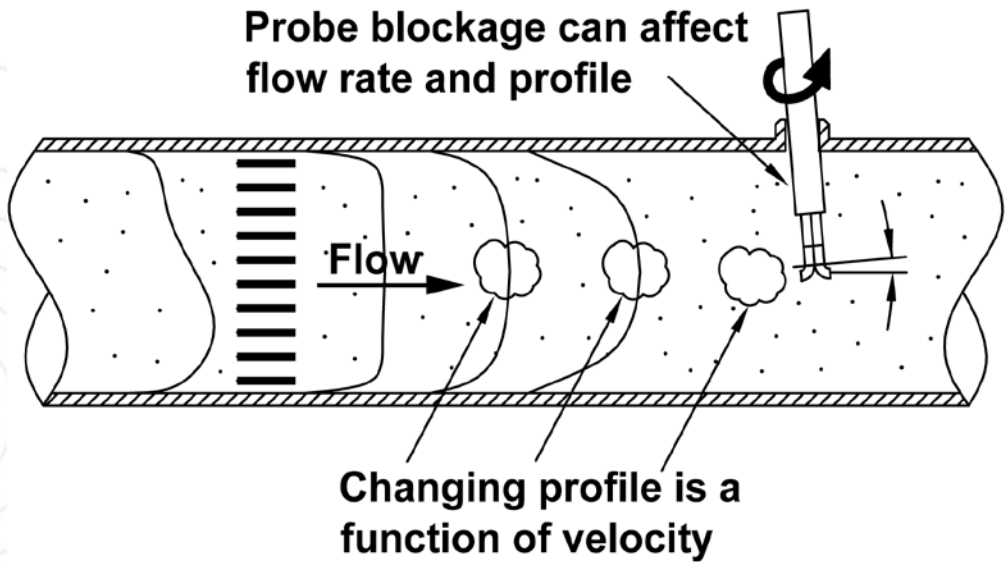
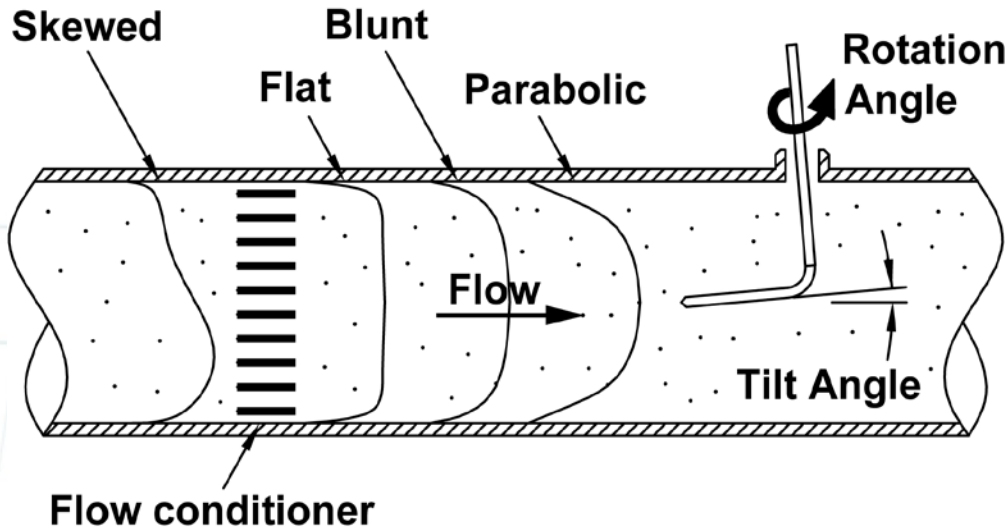


$$V = K_{factor} (output)$$

From Lab  $\nearrow$   $V$   $\nwarrow$  Measured

$\uparrow$   $K_{factor}$





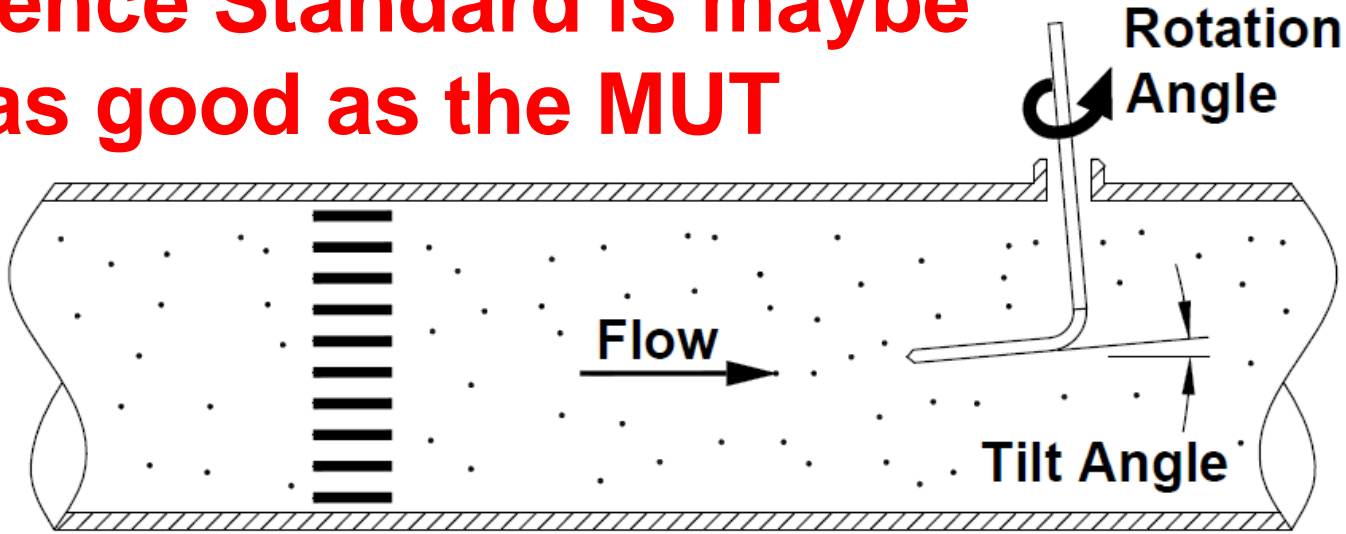
## STEP 1.

- A. Set flow and record velocity with Pitot-Static Tube that has a known Pressure Coefficient ( $C_p$ ).
- B. Avoid Tilt & Rotation Errors.

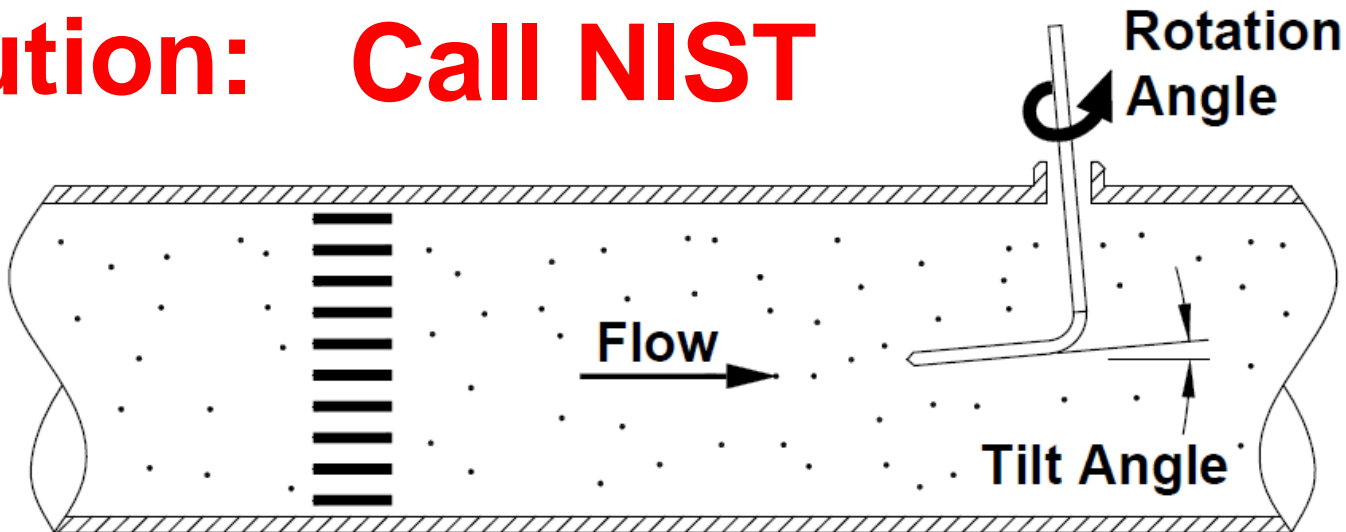
## STEP 2.

- A. Maintain identical flow rate.
- B. Remove the Pitot-Static Tube.
- C. Position the Point Velocity Device in the exact same location.
- D. Make sure the blockage of Point Velocity Device does not alter the fluid velocity by reducing the flow area or increasing the pressure drop causing a lower fan output.
- E. Make sure velocity range does not cause an adverse localized velocity gradient.
- F. Avoid Tilt & Rotation Errors.

**Reference Standard is maybe only as good as the MUT**



**Solution: Call NIST**



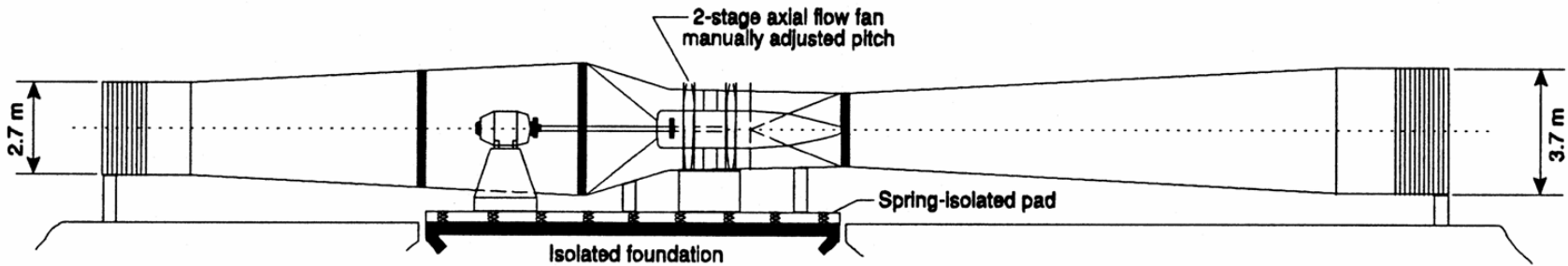
## NIST Fluid Metrology Group

Iosif I. Shinder, Aaron Johnson

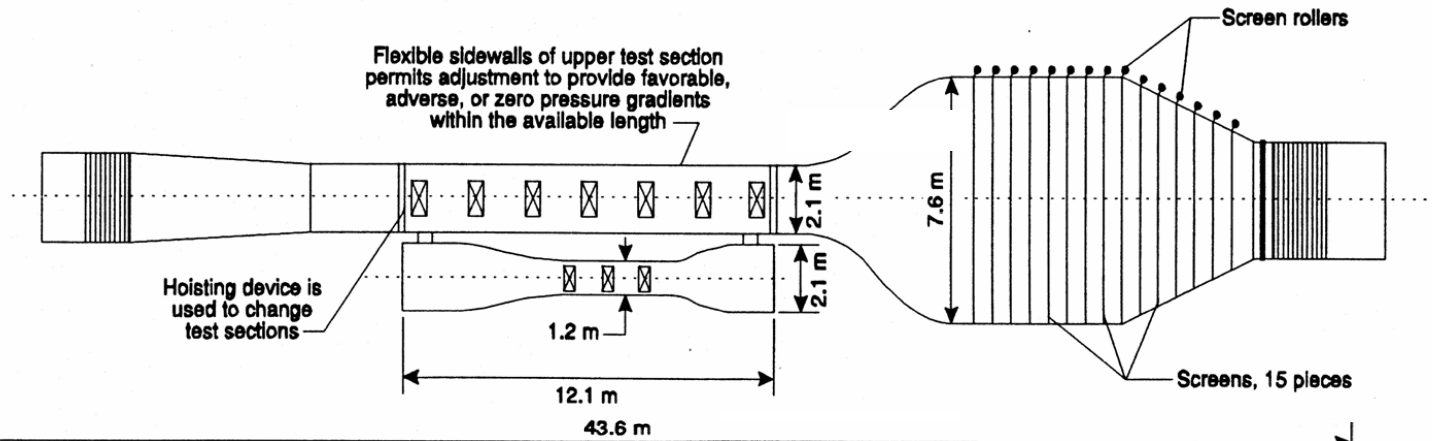


# NIST Dual Test-Section Wind Tunnel

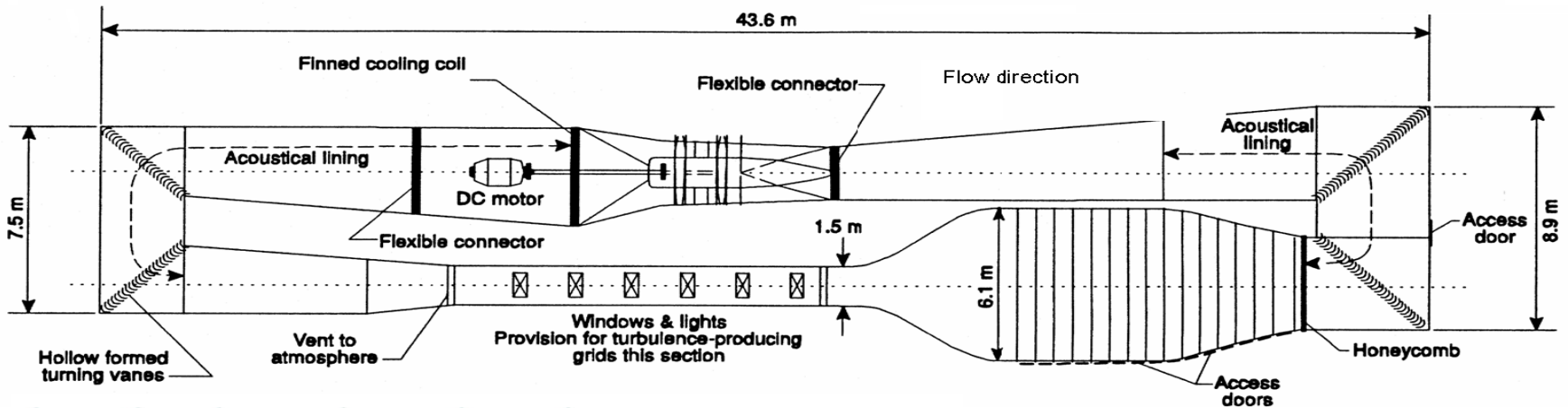
Return Section Side View



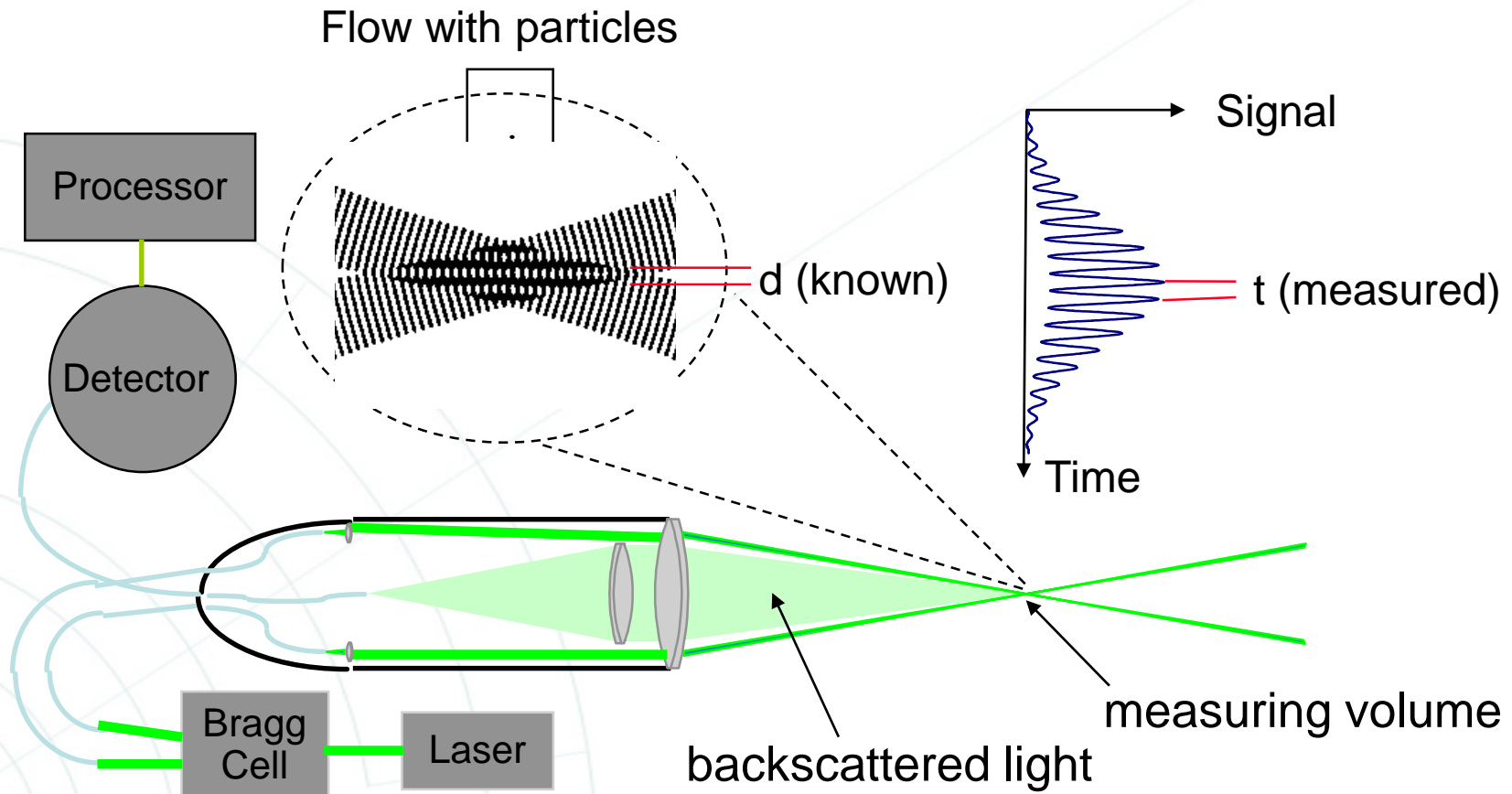
Test Section Side View



Top View



# Primary Standard. Differential LDV



# Oil Seeding





# Lasers & Seeding

Oil Seeding

vs

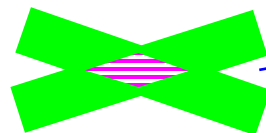
Water Seeding

3 gm/hr

10000 gm/hr

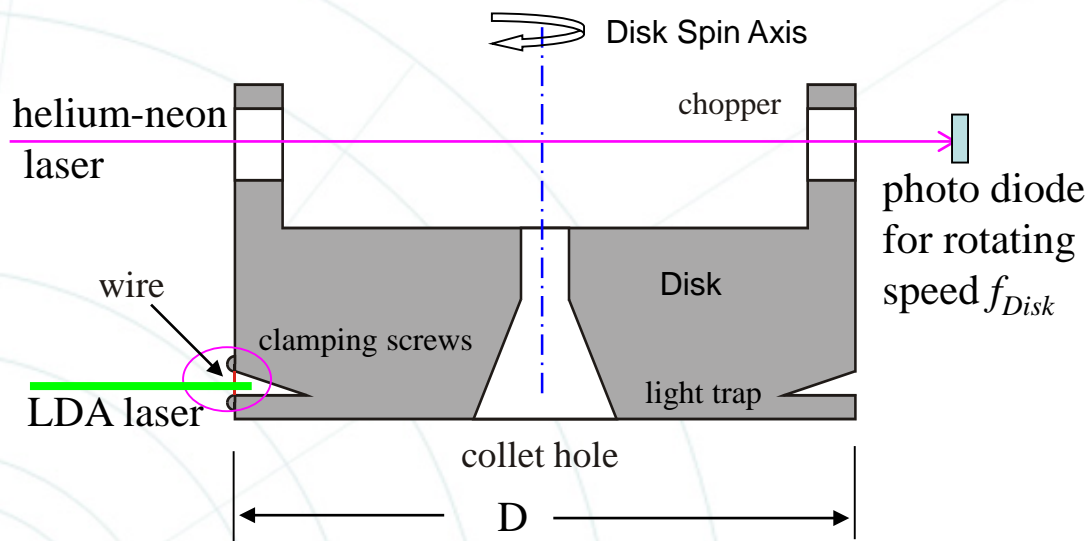


# Spinning disk



$$V_{LDA} = d f_D$$

$$V_{Disk} = f_{Disk} D / 2$$



$$C_{LDA} = \frac{V_{Disk}}{V_{LDA}} = \frac{D}{2} \frac{f_{Disk}}{f_D^C d}$$

$$V_{NIST} = C_{LDA} V_{LDA} = \frac{D}{2} f_{Disk} \frac{f_D}{f_D^C}$$

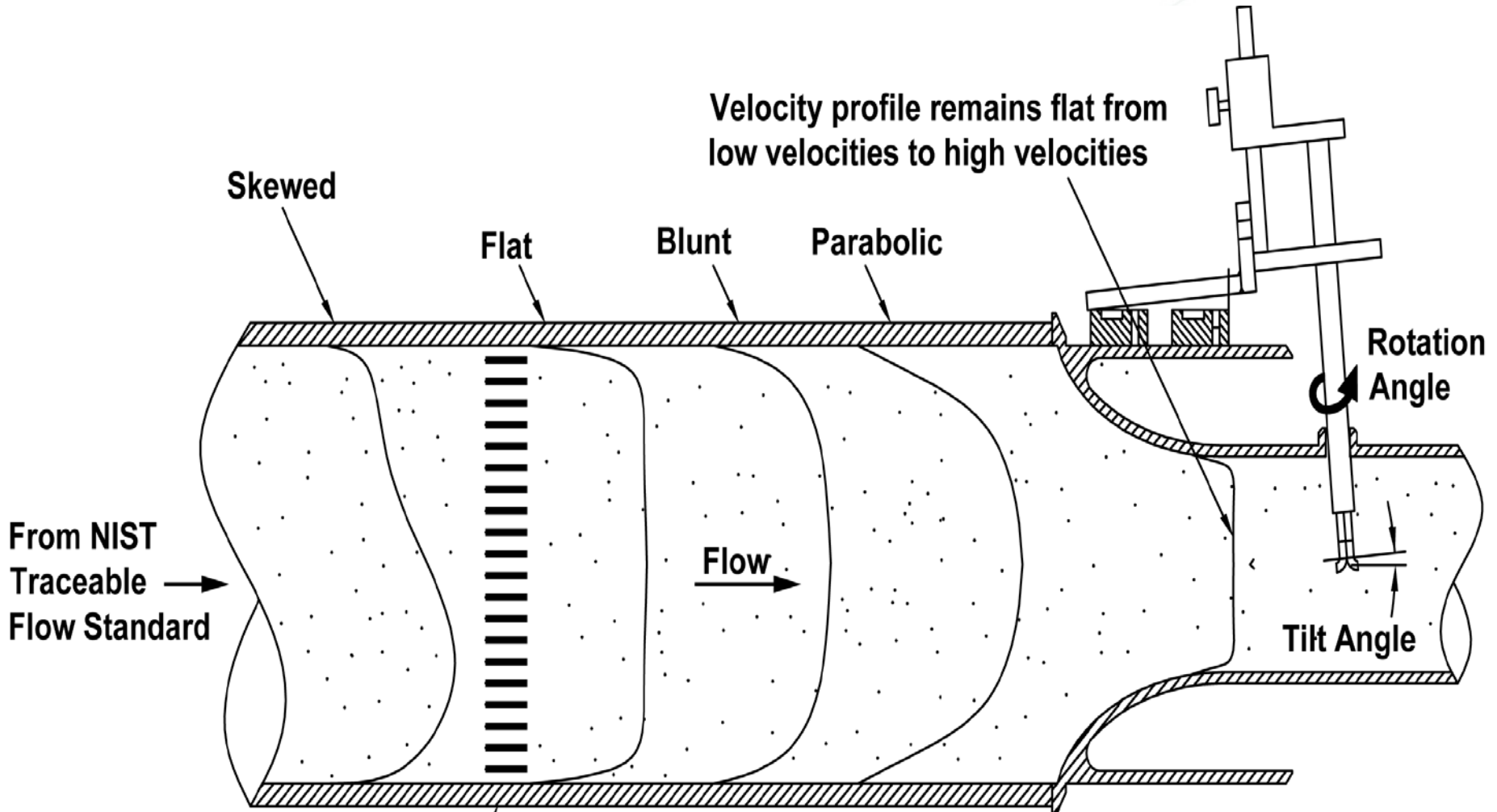
Length  $D$  and Time  $f_{Disk}$

- **Two test sections:**
- **High speed: to 75 m/s (246 ft/sec) 1.2 m high**
- **Low speed: to 45 m/s (147 ft/sec) 2.1 m high**
- **Uncertainties – 0.25% increasing to 2% at low speeds**

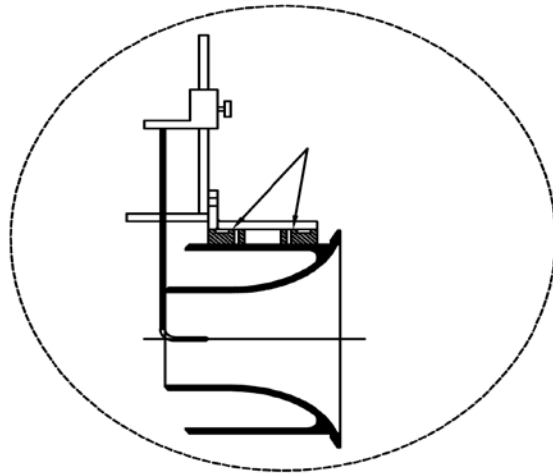
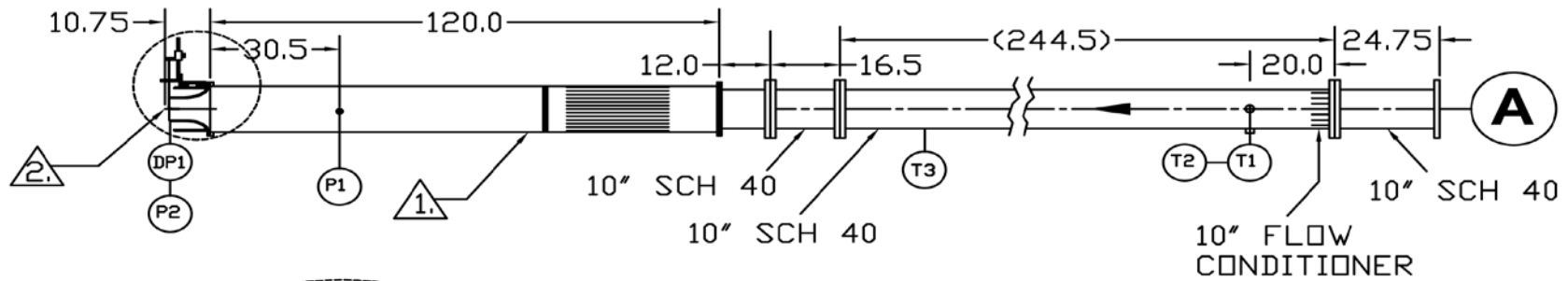
**NASA's Requirements:**

**7.6 to 122 m/sec (25 to 400 FPS)**

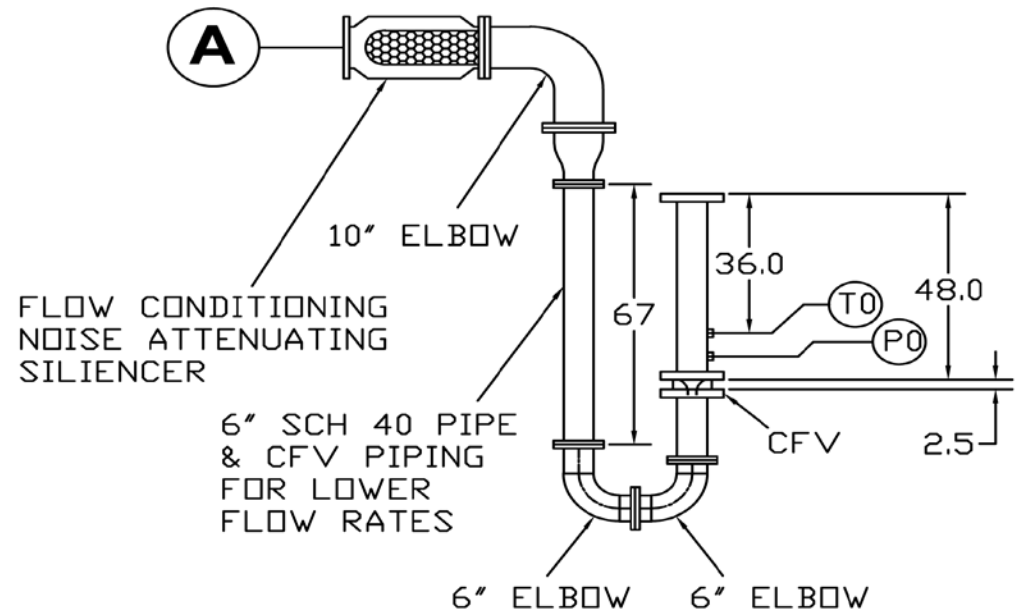
# Alternate Point-Velocity Calibration Methodology



# Test Configuration



4X MAGNIFICATION BUBBLE



**NOTES:**

1. 12" SCH 10S CONDITIONING SPOOL WITH TUBE BUNDLE & HONEYCOMB
2. FLOW CONDITIONING SUB-SONIC VENTURI
3. T3 INSERTED AT 0.5D FROM TOP, T2 INSERTED AT 0.25D FROM BOTTOM, T1 INSERTED AT 0.25D, P2 MEASURING STAGNATION PRESSURE, ON HIGH SIDE OF PITOT TUBE.

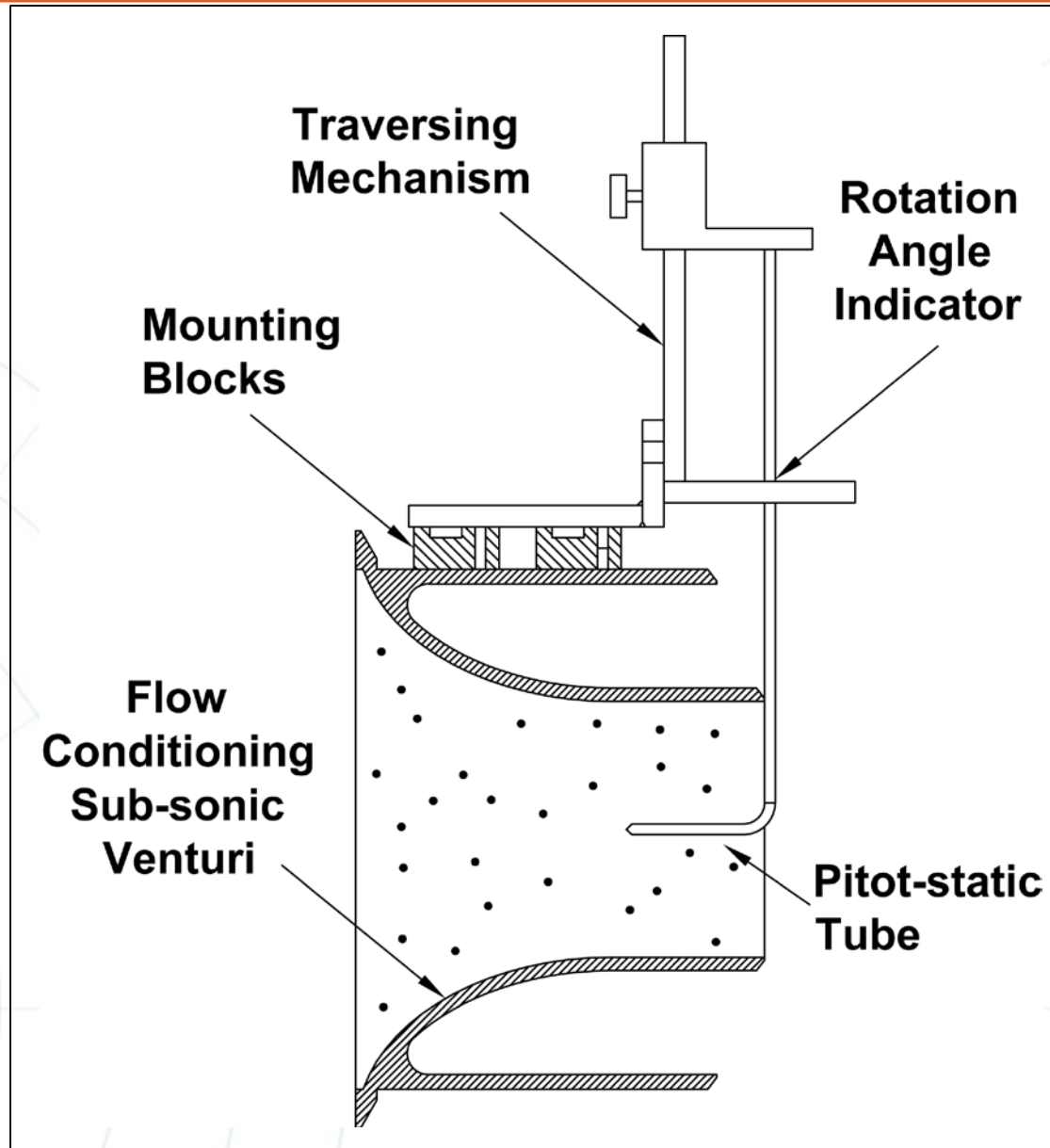
UNLESS OTHERWISE SPECIFIED:
DIMENSIONS IN INCHES
TOLERANCES:
FRACTIONAL: $\pm 1/32"$
ANGULAR: $\pm 1^\circ$
1-PLACE DECIMAL: $\pm 0.03$
2-PLACE DECIMAL: $\pm 0.01$
3-PLACE DECIMAL: $\pm 0.005$

Drawn By: EJH	Prod Appr: EJH	ECR No:
Eng Appr: EJH	QA Appr:	ECR Appr:

<b>Piping Configuration for Point-Velocity Calibration</b>	
DATE: 03-15-2015	DWG. NO: <b>CEESI-1503</b>
SCALE: N.T.S.	REV: A
	PAGE: 1 OF 1

# The Hardware





1. Determine the mass flowrate ( $\dot{m}$ ) from an upstream NIST traceable flow standard.
2. Determine the gas density ( $\rho$ ) at the calibration location from temperature and pressure measurements.
3. Divide the mass flowrate by the gas density and the throat area ( $A_{throat}$ ) of the sub-sonic venturi to determine the bulk (average) velocity in the calibration location.

$$V_{Average} = \frac{\dot{m}}{\rho \cdot A_{throat}}$$

4. Correct the average velocity by the projected area of the Pitot-static tube. Note, this does not include the Pitot-static's stem area.

$$V_{Ave-corrected} = V_{Average} \cdot \frac{A_{throat}}{(A_{throat} - A_{Pitot})}$$



5. Using an uncalibrated Pitot-static tube, perform a pitot traverse at the calibrating velocity ranges, while monitoring the flow standard. Apply the equation below to determine individual velocities at each traverse location. If slight variations occur in the flowrate during the pitot traverse, the velocities can be normalized by multiplying by the average mass flow rate during the testing, and by dividing the mass flowrate during the individual traverse point as shown below.

$$V_i = N \cdot K_{initial} \sqrt{\frac{h_{w-i}}{\rho_i} \left( \frac{\dot{m}_{average}}{\dot{m}_i} \right)}$$

6. Determine a Profile Factor (PF) that relates the average velocity in the throat of the sub-sonic venturi to the velocity in the center. Notice how the initial Pitot-static flow coefficient ( $K_{initial}$ ) drops out of the equation.

$$PF = \frac{N \cdot K_{initial} \sqrt{\frac{h_{w-center}}{\rho_{center}} \left( \frac{\dot{m}_{average}}{\dot{m}_{center}} \right)}}{N \cdot K_{initial} \frac{\sum \left[ \sqrt{\frac{h_{w-i}}{\rho_i} \left( \frac{\dot{m}_{average}}{\dot{m}_i} \right)} \right]}{n}} = \frac{\sqrt{\frac{h_{w-center}}{\rho_{center}} \left( \frac{\dot{m}_{average}}{\dot{m}_{center}} \right)}}{\frac{\sum \left[ \sqrt{\frac{h_{w-i}}{\rho_i} \left( \frac{\dot{m}_{average}}{\dot{m}_i} \right)} \right]}{n}}$$

7. Profile Factors (PF) can be calculated for different velocities, and curve fit to different Throat Reynolds Numbers.

$$PF = f(Re_{throat})$$

8. The Point Velocity Device can be inserted into the center of the sub-sonic venturi, and its flow coefficient can be determined by the following equation.

$$K = \frac{PF}{N \cdot (A_{throat} - A_{Pitot})} \cdot \frac{\dot{m}}{\sqrt{\rho \cdot h_w}}$$

- Three Pitot-static tubes were tested using the Alternative Methodology.
- The Pitot-static tubes were positioned in the center of the nozzle, and tested from 10 to 115 m/sec.
- The percent deviation between the experimentally determined flow coefficients (K) and theory was determined where:

$$K_{theory} = \left\{ \left( \frac{\gamma}{\gamma - 1} \right) \left( \frac{P_1}{P_t - P_1} \right) \left[ \left( \frac{P_t}{P_1} \right)^{\frac{\gamma-1}{\gamma}} - 1 \right] \right\}^{\frac{1}{2}}$$

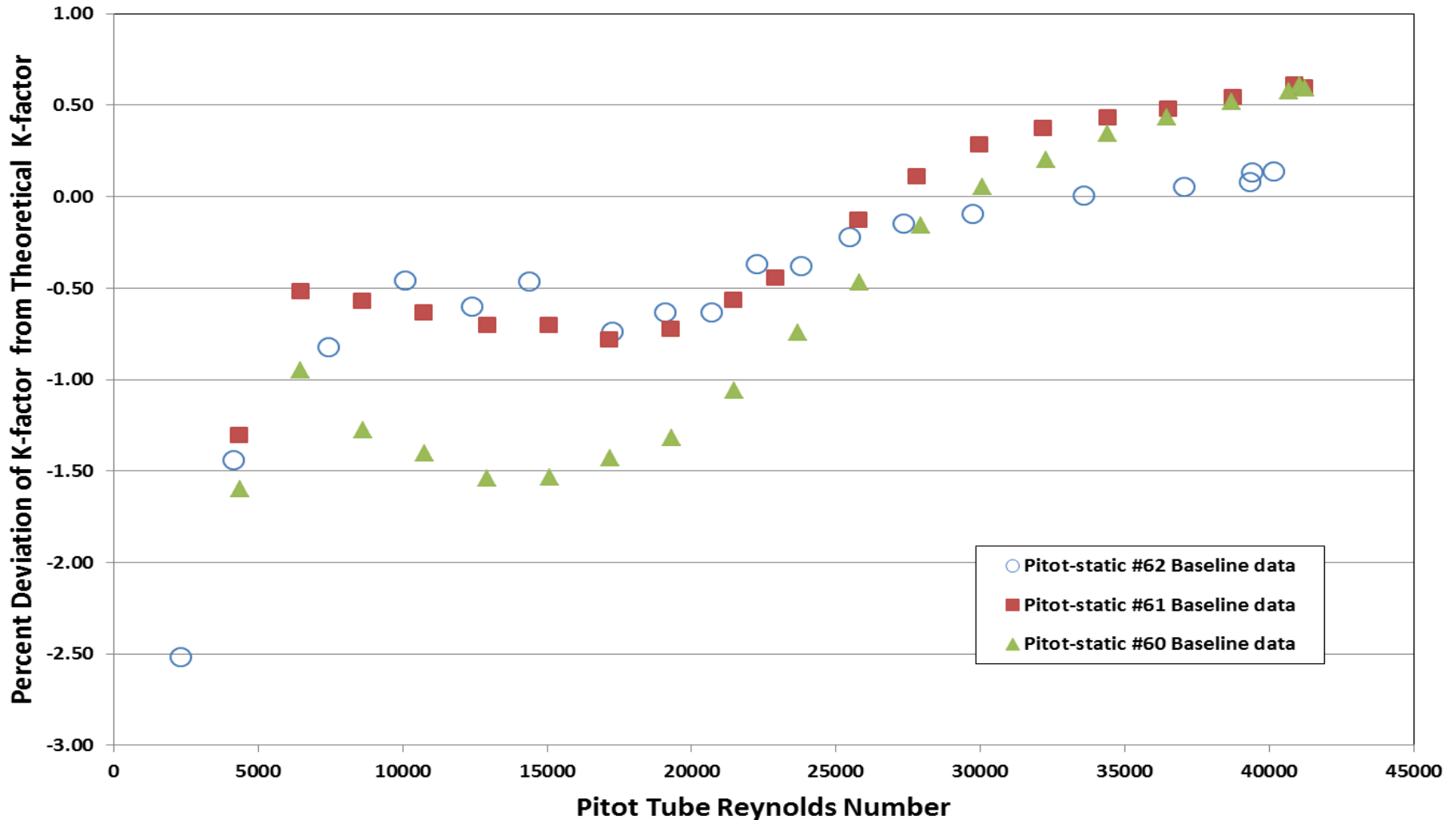
**Summary of the Percent Deviation  
between Experimentally determined  
Flow Coefficients and Theroetical Flow  
Coefficients**

<b>Pitot-static Tube No.</b>	<b>Perent Average Deviation*</b>	<b>Percent Standard Deviation*</b>
<b>#60</b>	<b>-0.5</b>	<b>0.84</b>
<b>#61</b>	<b>-0.2</b>	<b>0.58</b>
<b>#62</b>	<b>-0.5</b>	<b>0.62</b>
<b>Averages:</b>	<b>-0.4</b>	<b>0.7</b>

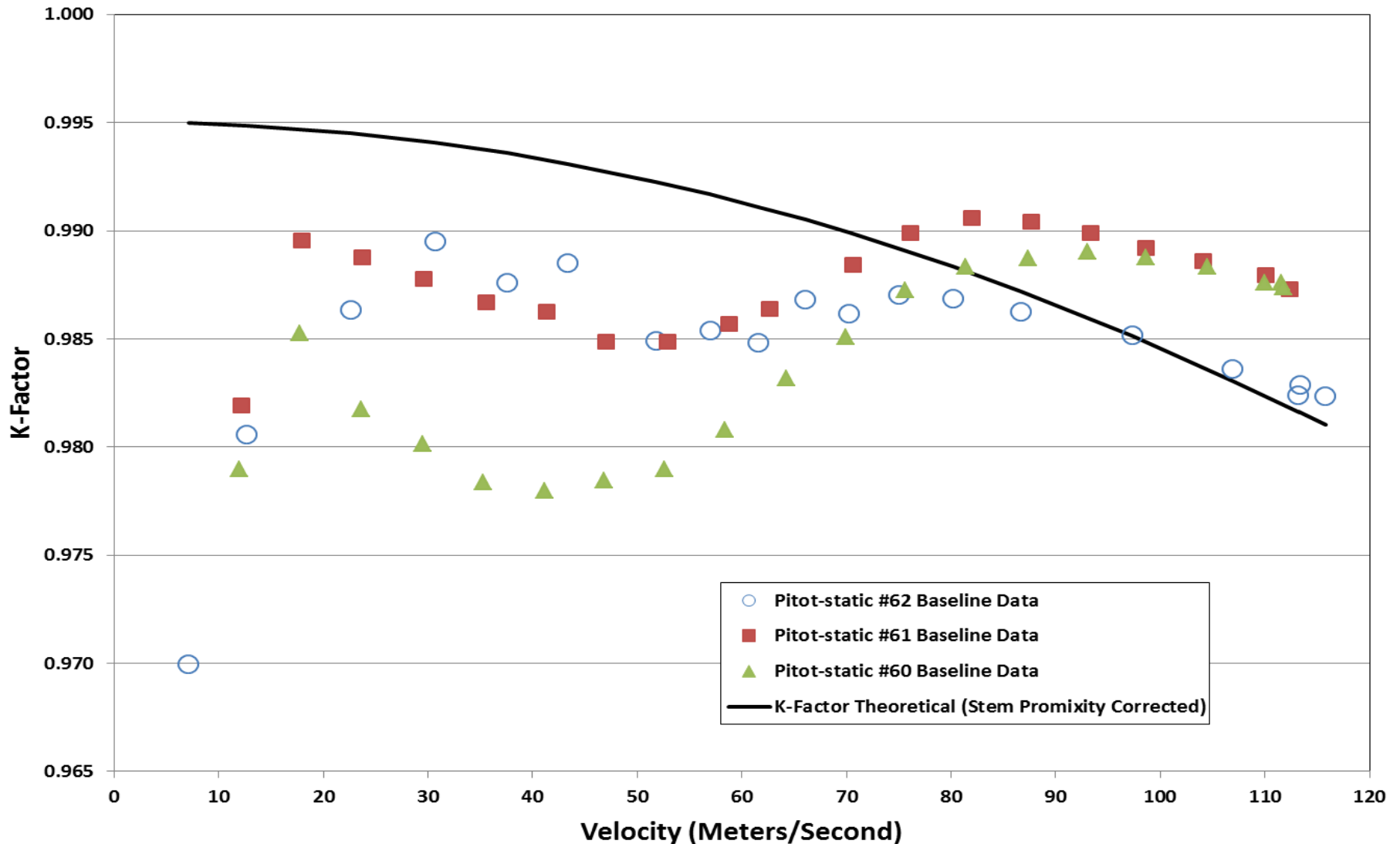
**\* Over the entire velocity range tested**

# K-factor vs. Pitot Tube Reynolds Number

**Three Hemispherical Pitot Tubes  
Percent Deviation From Theoretical K-Factor (Stem Proximity Corrected)  
vs. Pitot Tube Reynolds Number**



## Three Hemispherical Pitot Tubes K-Factor vs. Centerline Velocity



The following equation was used to determine the Pitot-static Tube's flow coefficient (K) uncertainty.

$$\frac{U_e(K)}{K} = \sqrt{\left[\left(\frac{\partial K}{\partial \dot{m}}\right) \frac{U(\dot{m})}{\dot{m}}\right]^2 + \left[\left(\frac{\partial K}{\partial V_{pf}}\right) \frac{U(V_{pf})}{V_{pf}}\right]^2 + \left[\left(\frac{\partial K}{\partial P_1}\right) \frac{U(P_1)}{P_1}\right]^2 + \left[\left(\frac{\partial K}{\partial T_1}\right) \frac{U(T_1)}{T_1}\right]^2 + \left[\left(\frac{\partial K}{\partial h_w}\right) \frac{U(h_w)}{h_w}\right]^2}$$

Where:

$\dot{m}$  = mass flow rate from the Critical Flow Venturi, pounds-mass/sec

$V_{pf}$  = Velocity profile factor in the sub-sonic venturi

$P_1$  = Static pressure in the sub-sonic venturi, psia

$T_1$  = Absolute sub-sonic venturi temperature, °R

$h_w$  = Differential pressure produced by the Pitot-static tube, "H<sub>2</sub>O



Applying the appropriate sensitivity coefficients the equation above yields.

$$\frac{U_e(K)}{K} = \sqrt{\left[\frac{U(\dot{m})}{\dot{m}}\right]^2 + \left[\frac{U(V_{pf})}{V_{pf}}\right]^2 + \left[\frac{1}{2} \frac{U(P_1)}{P_1}\right]^2 + \left[\frac{1}{2} \frac{U(T_1)}{T_1}\right]^2 + \left[\frac{1}{2} \frac{U(h_w)}{h_w}\right]^2}$$

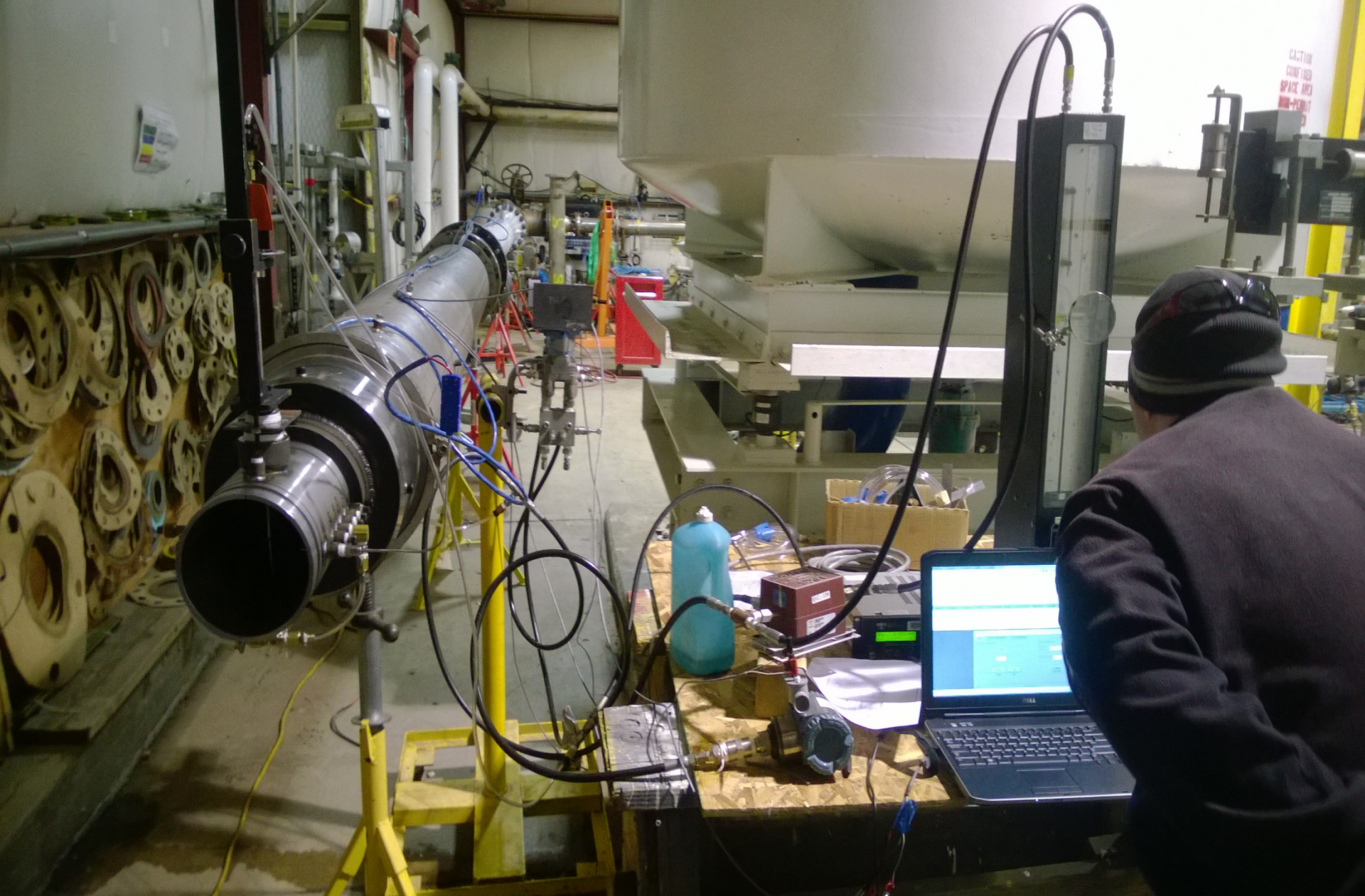
Applying the test uncertainties the equation above yields.

$$\frac{U_e(K)}{K} = \sqrt{[0.35]^2 + [0.1]^2 + \left[\frac{1}{2} \cdot 0.1\right]^2 + \left[\frac{1}{2} \cdot 0.1\right]^2 + \left[\frac{1}{2} \cdot 1.0\right]^2} = 0.62\%$$

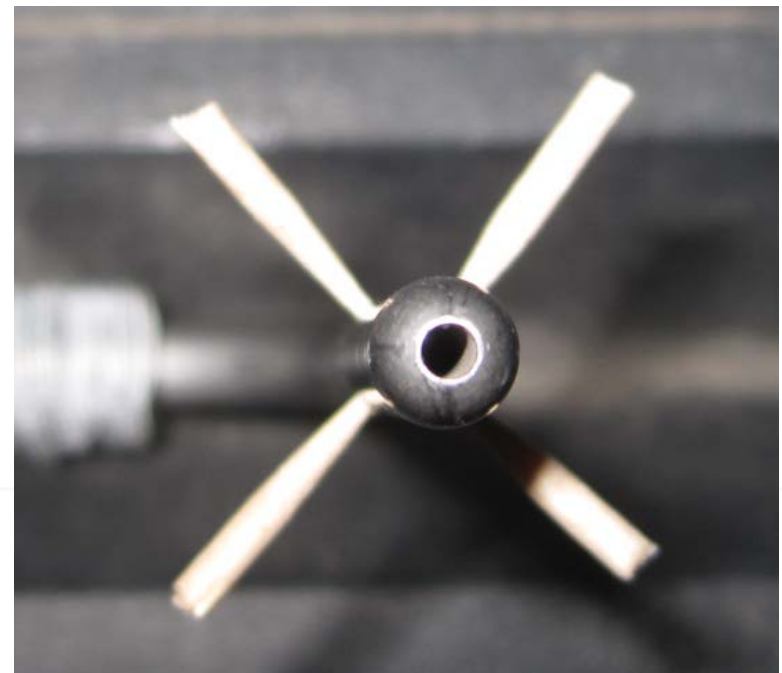
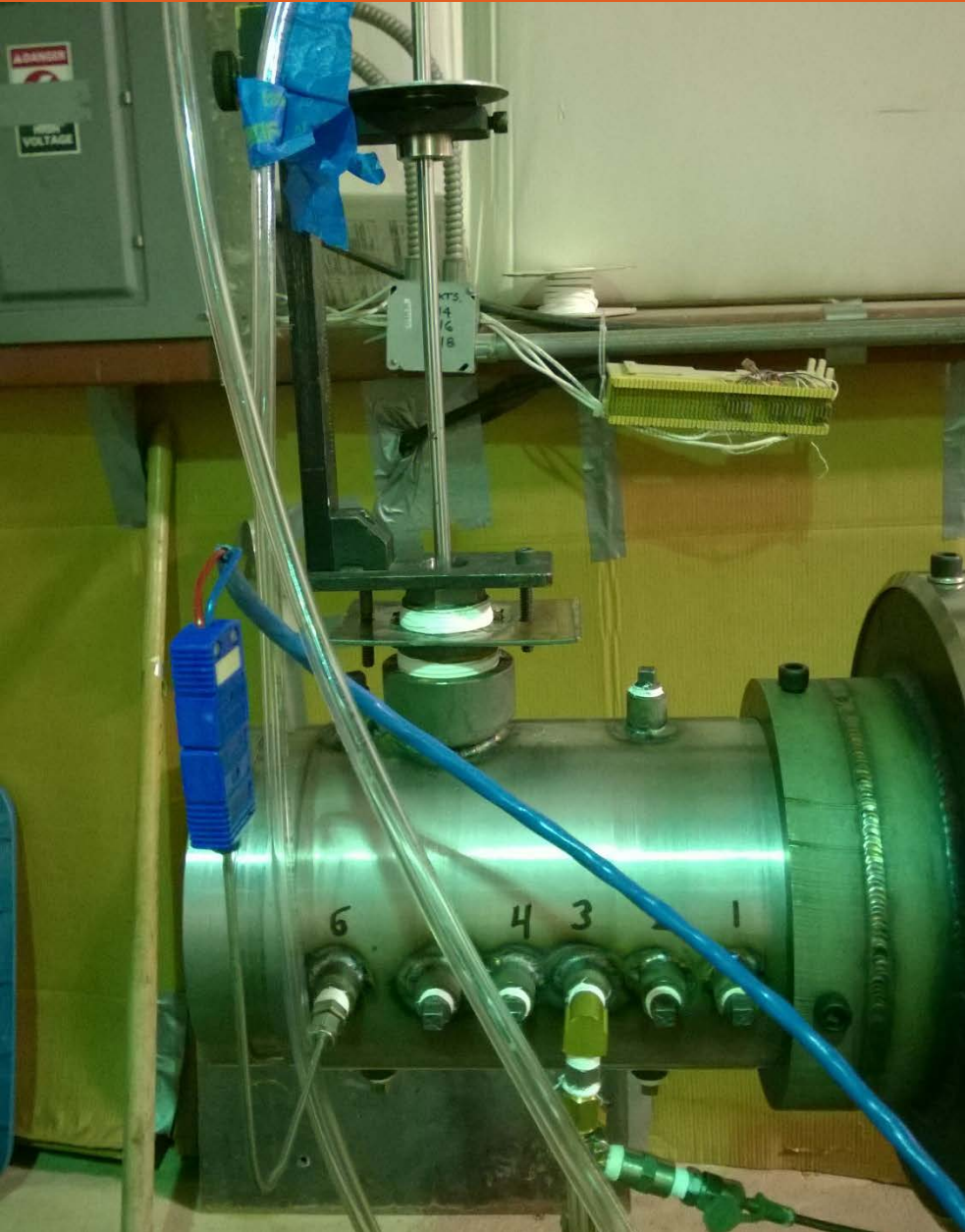
**The expanded uncertainty of the Pitot-static flow coefficient (K) at two-sigma is 1.24%**

- Individual averages of all three experimentally determined flow coefficients were within the estimated uncertainty of 0.62% at one sigma of the theoretically calculated flow coefficient.
- Flow coefficient deviations were likely a result of imperfections in the Pitot-static tube's surfaces and geometry, and the turbulence levels during testing.
- Better uncertainty could be achieved using more accurate DP transducers which contributed greatly to the uncertainty budget.
- $\pm 0.5\%$  DP transducers would have produced a 0.9 % uncertainty at two sigma.

# Similar Testing (Added a Throat Extension)



# Extended Throat & Close-up of Pitot Tubes



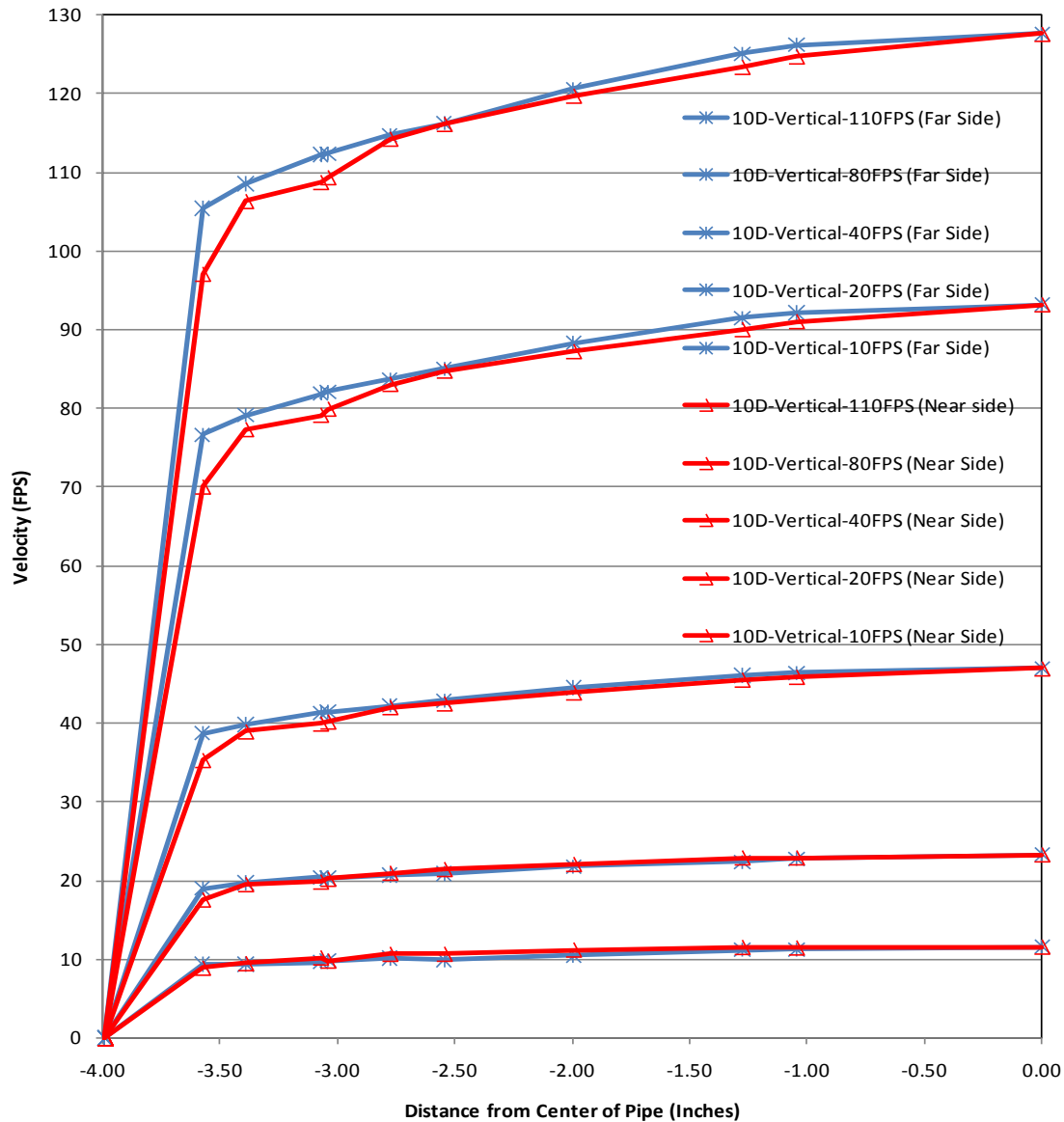
# Checking For Leaks



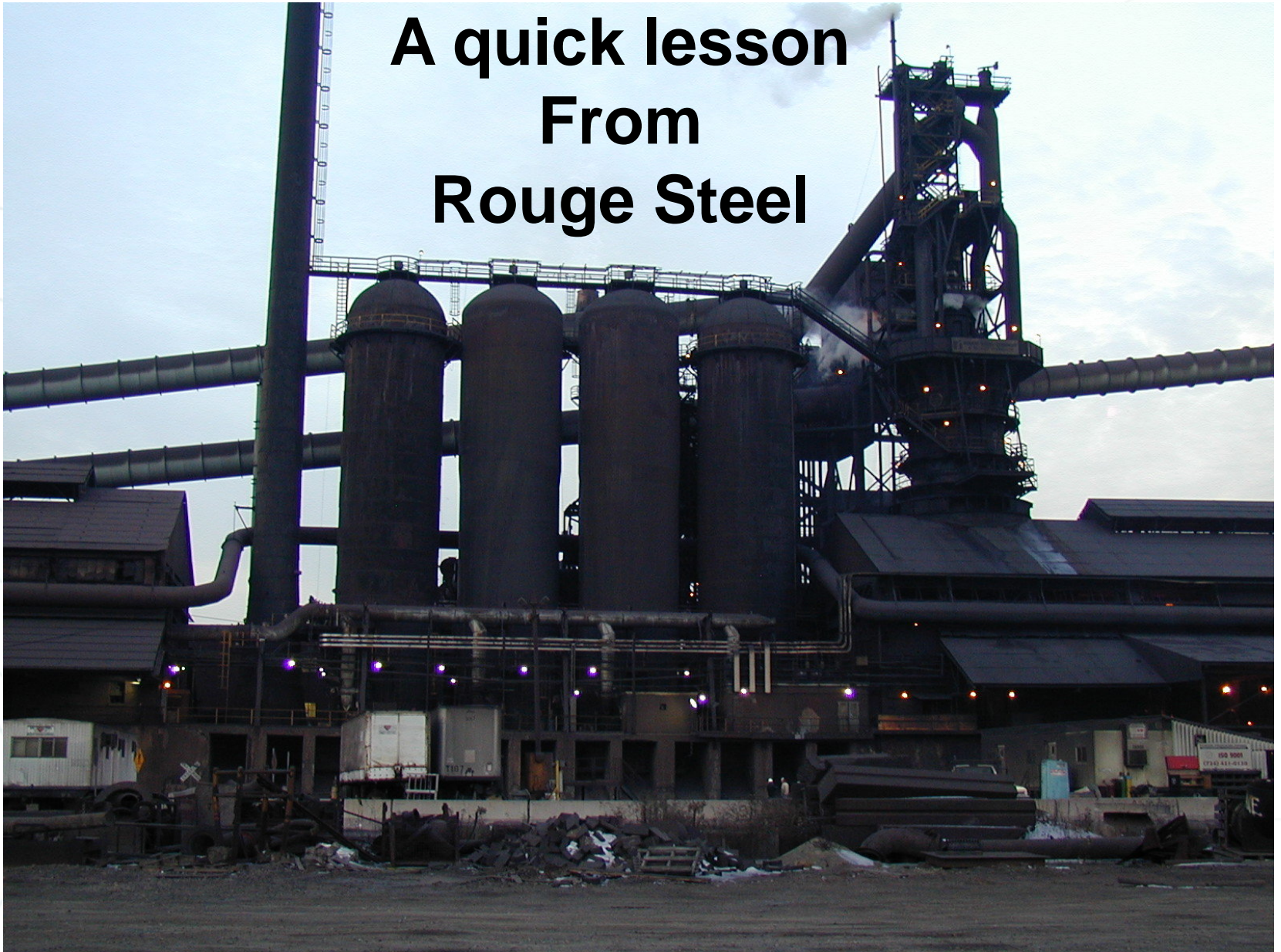


**Eureka A Leak !**

# Don't Forget about Blockage



## A quick lesson From Rouge Steel





## Flare Gas



# Stack Flow Measurement



**OOPS!**





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