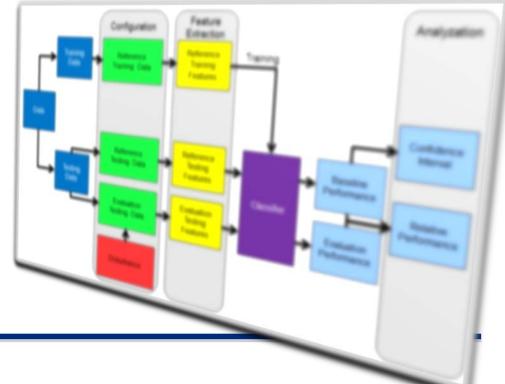
DERMALOG

On Testing the Robustness of Liveness Detection Feature Extractors for Fingerprint Live Scanners



Patrick Schuch

Outline

- Why liveness detection?
- Typical Workflow
- Known challenges
- How to overcome
- An example

Discussion & Conclusion



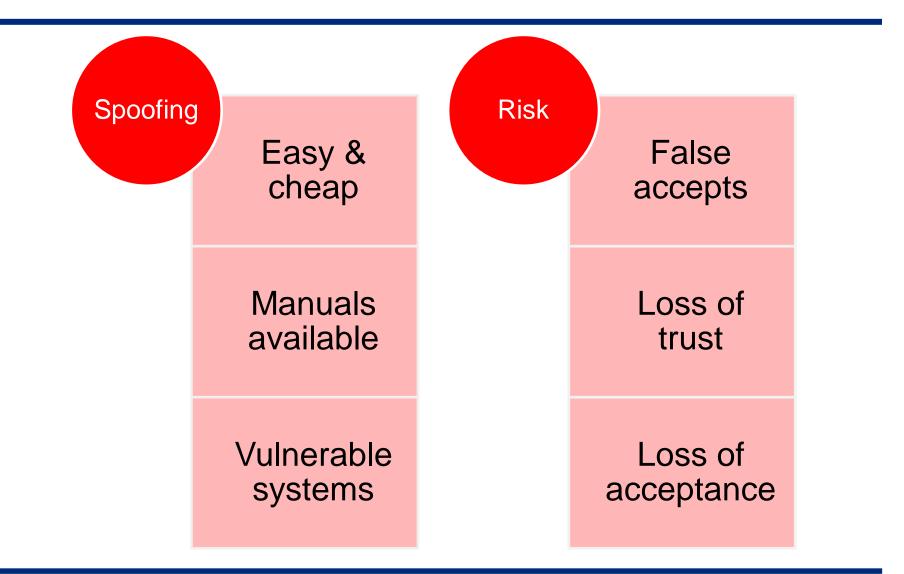
- HQ in Hamburg, Germany
- Outpost in Kuala Lumpur, Malaysia
- Modality: fingerprints
- Main Products:







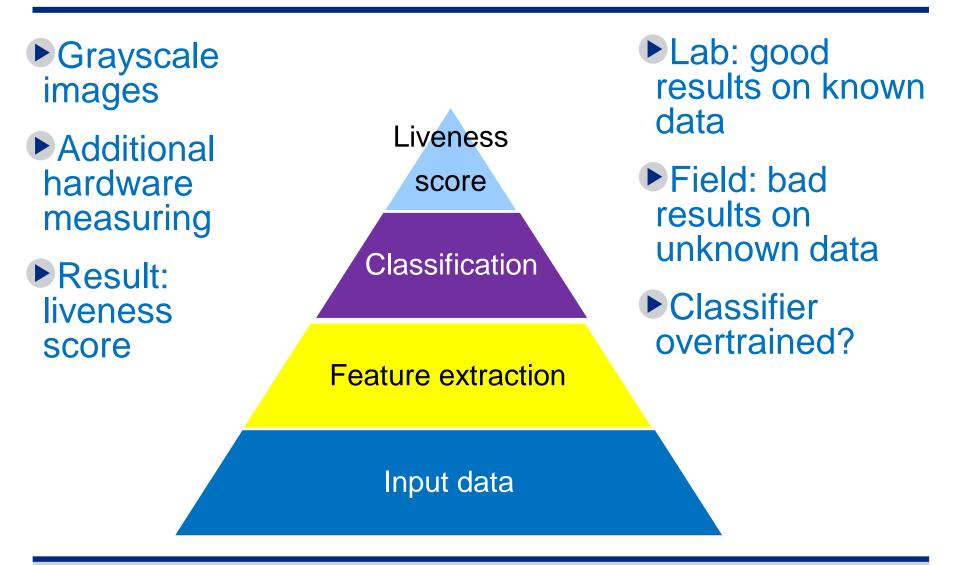
Why Liveness Detection?



Why Liveness Detection?



Typical Workflow



Known Challenges

External

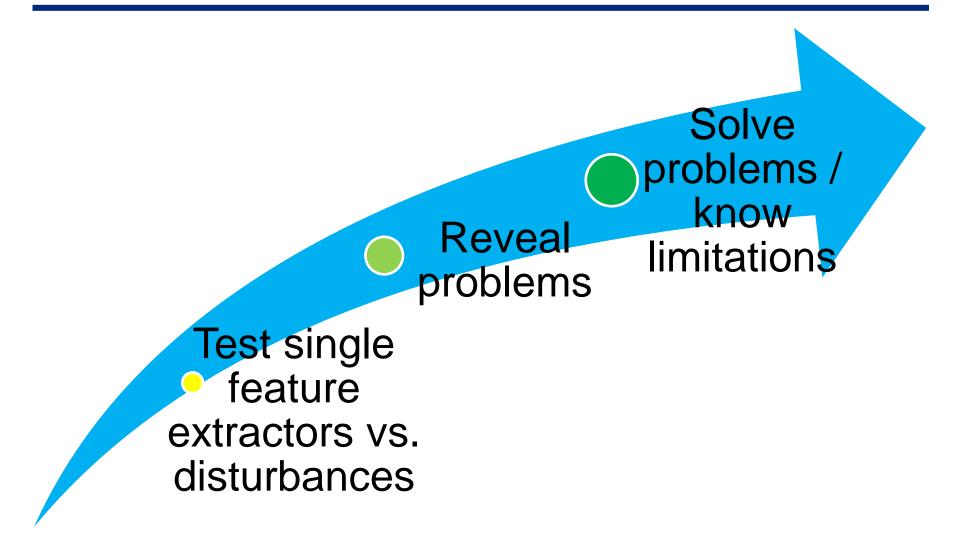
- Illumination
- Temperature
- Humidity
- Dust/Dirt
- Latents
- Population (skin etc.)

Internal

- Noise
- Defects
- Sharpness
- Fabrication tolerances
- . .

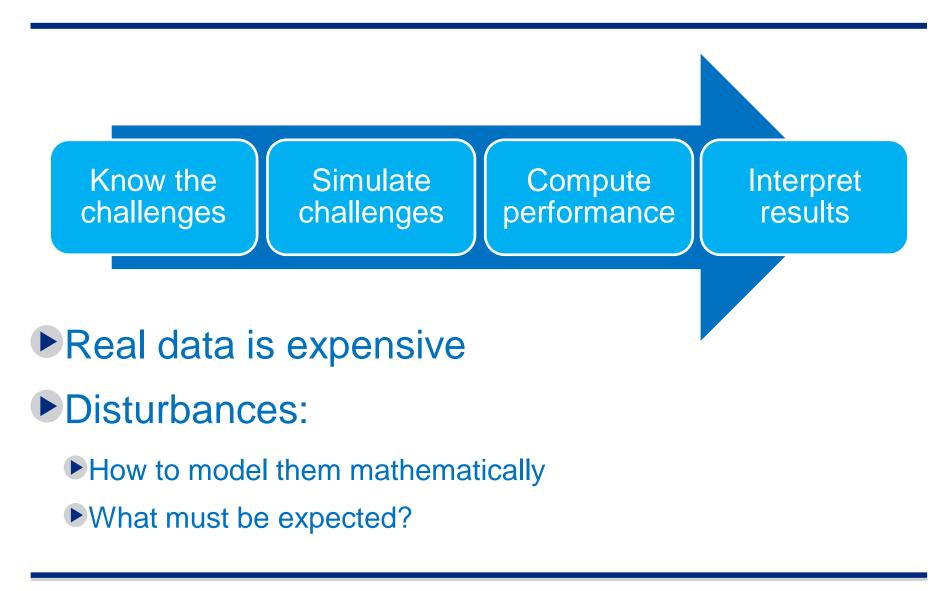
ISO/IEC 29197: Evaluation Methodology for Environmental Influence in Biometric Systems Performance

Known Challenges

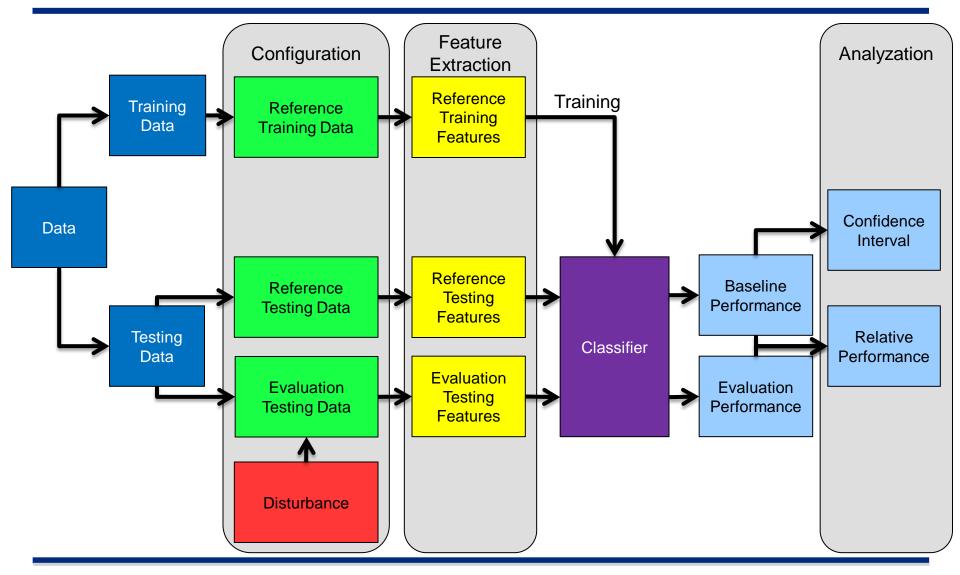




How to Test



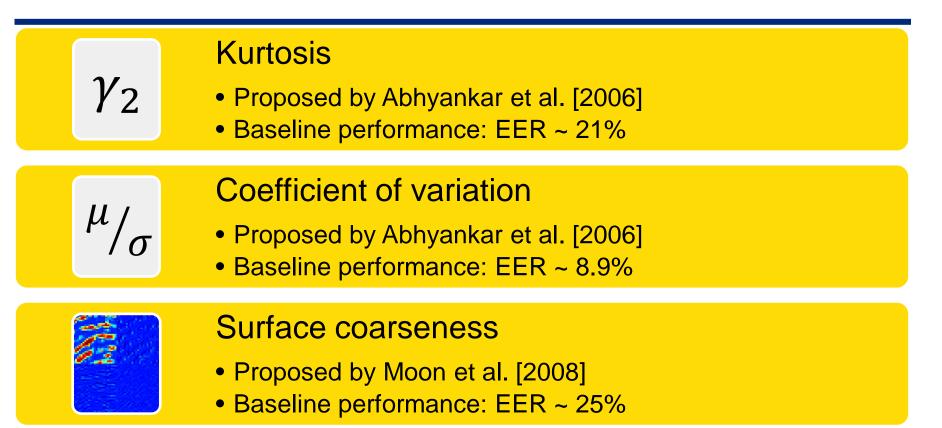
How to Test



Example - Data



Example - Tested Feature Extractors





Combined

- Combination of the previous three
- Baseline performance: EER ~ 8.4%

Example - Disturbances to be Tested





White Gaussian Noise

Noise in components



Shot Noise

- A.k.a. "Salt and Pepper Noise"
- Defect pixels

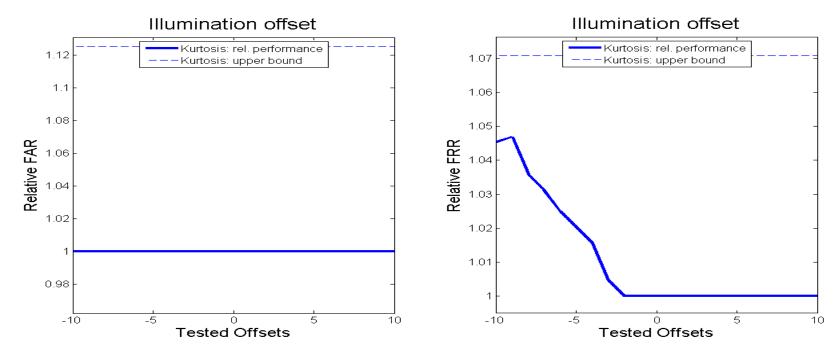
Latents

- "Dirt" from previous acquisitions
- Simulated latents

►Naive Bayes Classifier

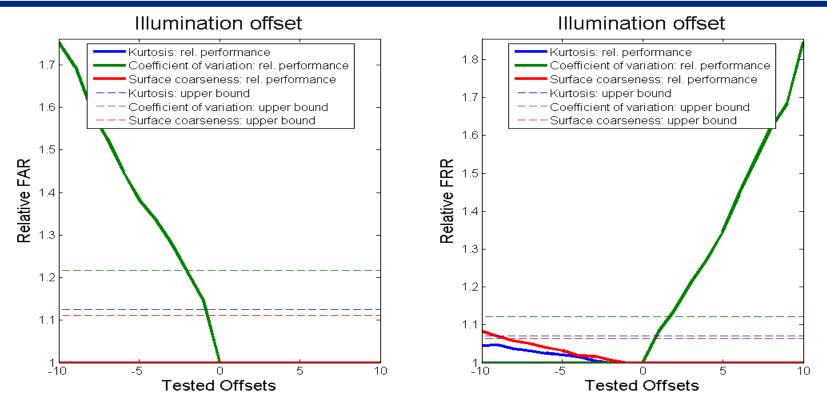
- ► False suspicious presentation detection rate (false SP-DR aka FRR)
- ► False suspicious presentation non-detection rate (false SP-NDR aka FAR)
- •Use upper bounds of Confidence Intervals (significance level $\alpha = 0.05$)
- Only relative error rates will be used

Feature Extractor	EER on Testing Set	Upper Bound for Relative FRR	Upper Bound for Relative FAR
Kurtosis	21.3%	1.07	1.12
Coefficient of variation	8.9%	1.12	1.22
Surface coarseness	25.0%	1.06	1.11
Combined	8.4%	1.13	1.23



- Baseline performance for offset 0
- Tendencies revealed in relative error rates
- Apply confidence intervals
- Crop to relative performance 1.0

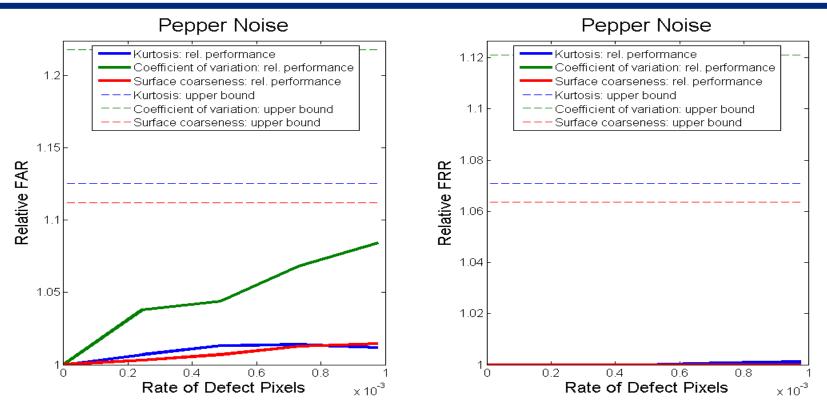




Parameter range [-10 10]

Strong decay for coefficient of variation

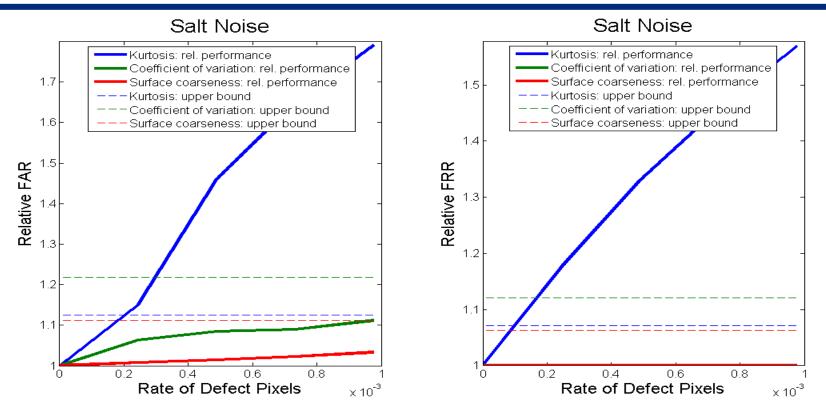




Parameter: Rate of defect pixels

Pepper Noise": All seem to be robust.

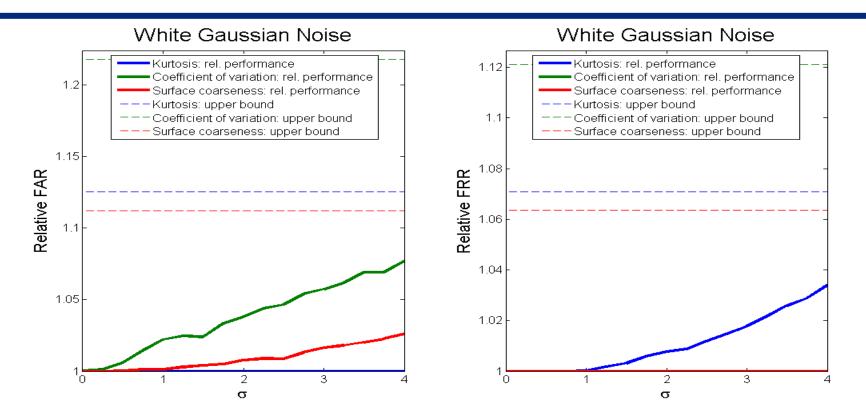




Parameter: Rate of defect pixels

"Salt Noise": Kurtosis is not robust.

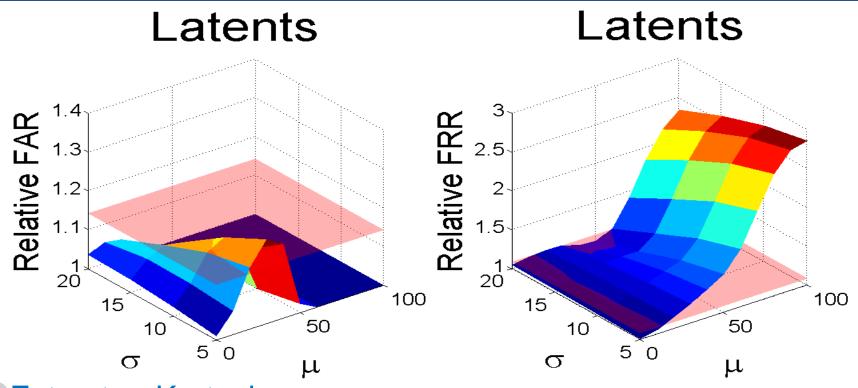




Parameter range [0 4]

All extractors seem to be robust.



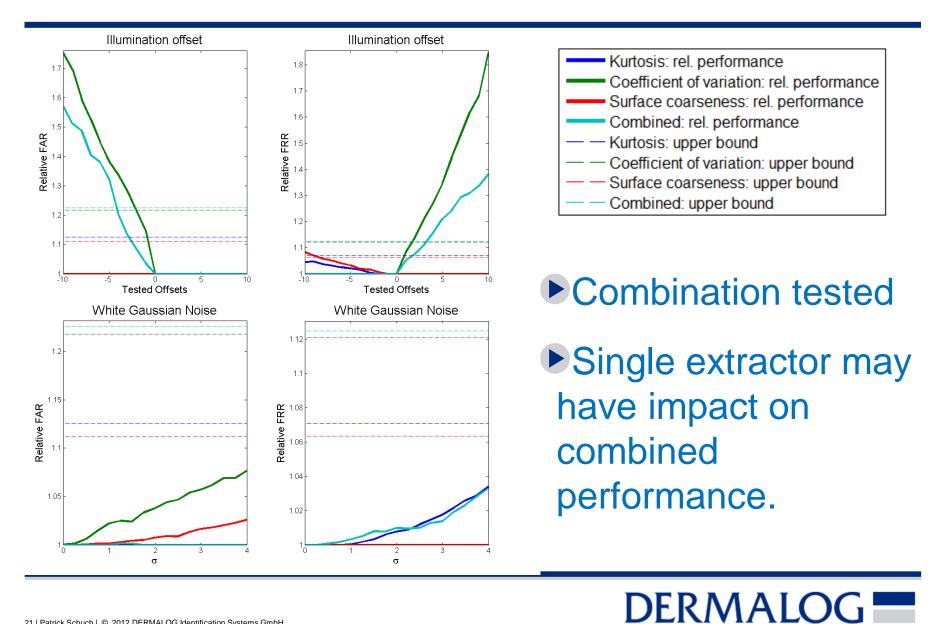


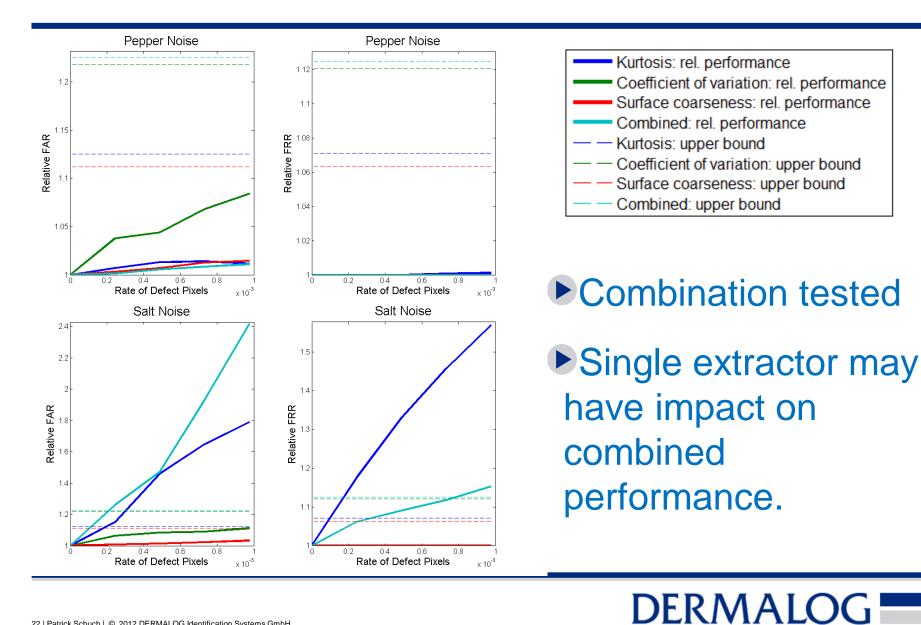
Extractor: Kurtosis

Parameter range: mean [0 100], deviation [0 15]

Decay when mean gets close to common ridge mean.

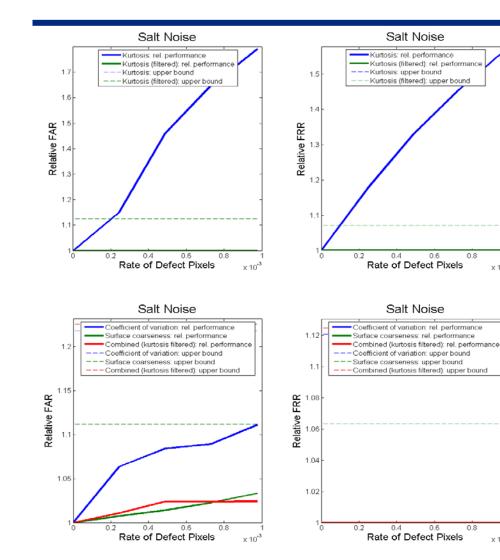






x 10⁻³

x 10⁻³



Revealed problem: Kurtosis vs. "Salt Noise"

Solution: apply special filter

Robustness gained

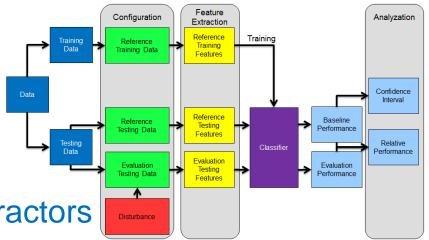
Iterative process

- Testing simulations...
 - ▶ shall not replace real data.
 - ▶is cheaper.
 - ▶ is better than no testing.
- Curse of dimensionality: testing all combinations
- Classifiers influence needs inspection.



Summary

- Proposed method:
 - Easy workflow
 - Concentration on feature extractors
 - Know and model the environment
 - Tendencies observable in relative error rates.
 - Not limited to fingerprint
- Weakest link may have serious impact





Revealed weaknesses in our own extractors

- Robustness gained
- Performance stabilized in the field
- Robustness over performance
- More disturbances to be modeled
 - More sophisticated models

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Do you have any questions? Thank you.

Patrick Schuch DERMALOG Identification Systems GmbH Hamburg, Germany patrick.schuch@dermalog.com

