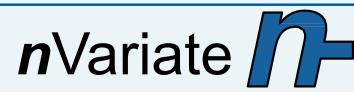
The Secret Life of Geometric Modeling in the Digital Thread: PMI & PDQ & Features, Oh My!

2024 MBE Summit *16 April 2024*

Ben Urick

co-founder, *n*Variate

benurick@nvariate.com



Outline

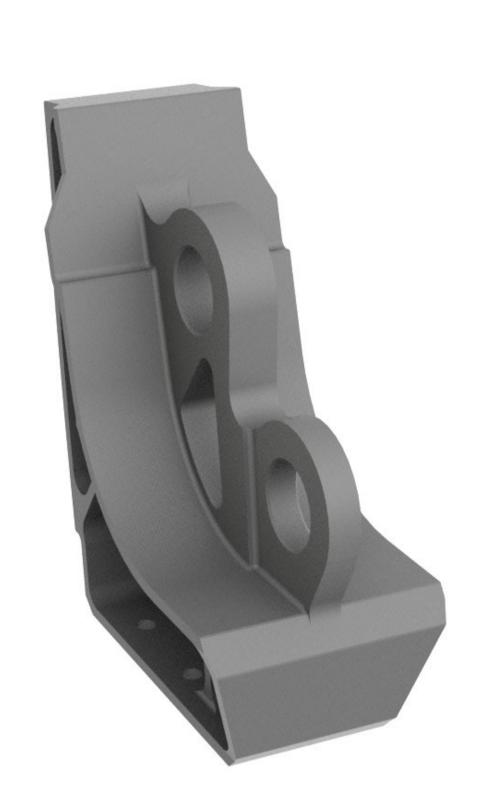
Background

Current MBD issues

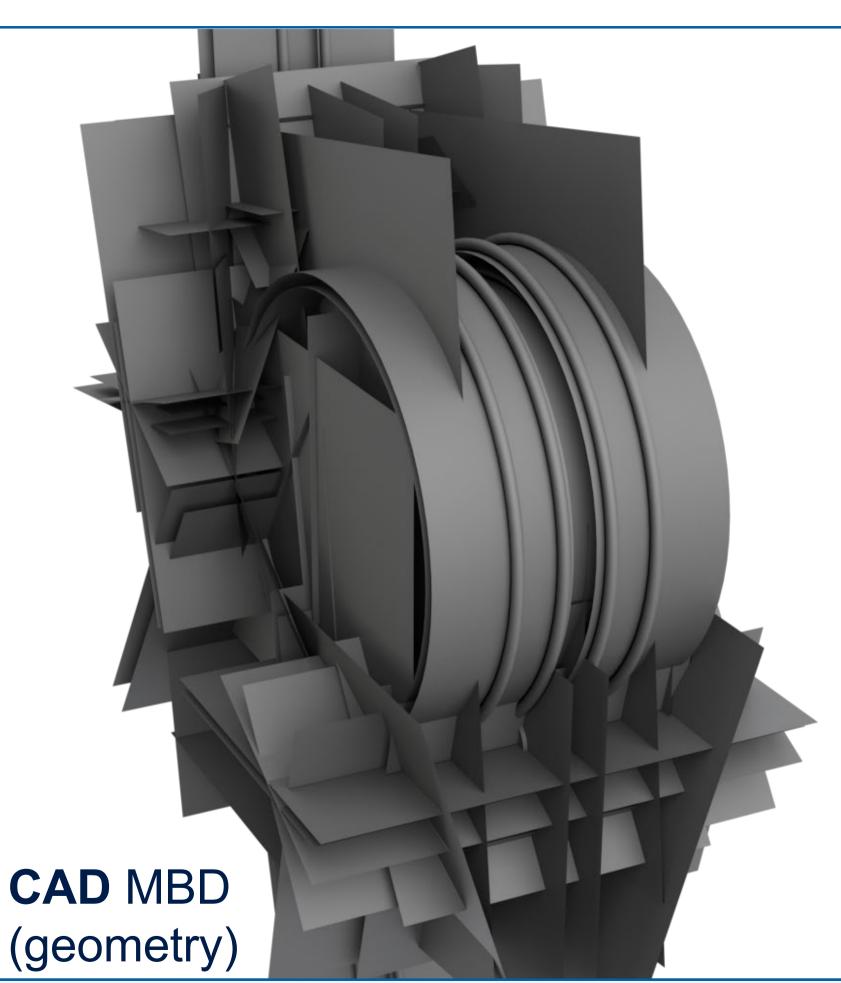
Background

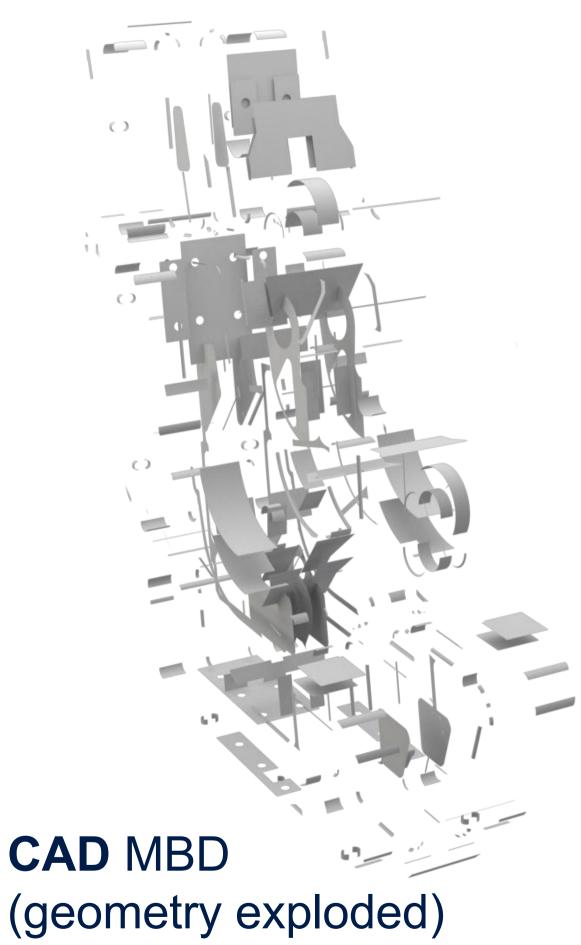
- 10+ years in industry in structural mechanics and analysis
- frustrated **user** → **researcher** (focus Isogeometric Analysis)
 - researcher -> inventor
 - inventor → developer
- co-founder and president of nVariate Inc.

CAD representations

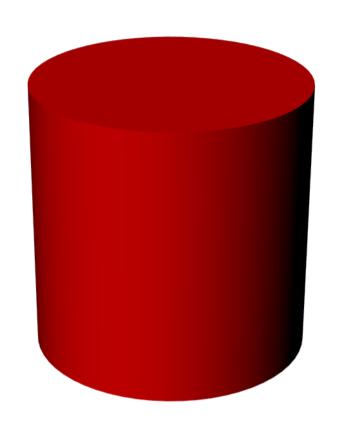


CAD MBD (graphical)



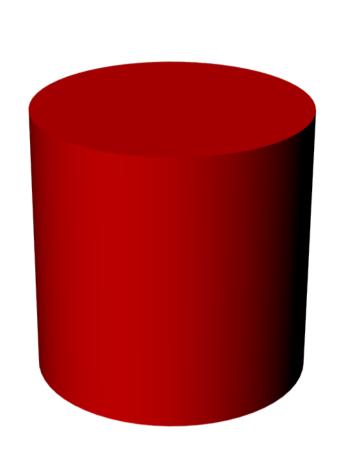


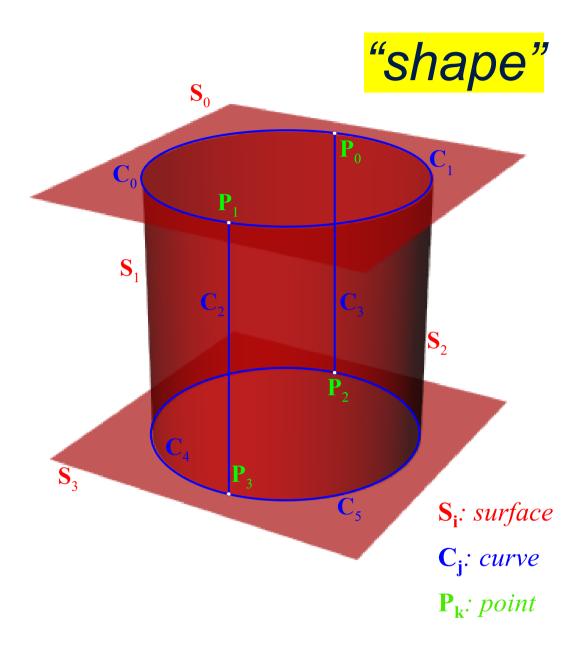
*n*Variate //-



B-rep *graphical rendering*





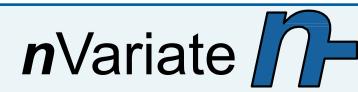


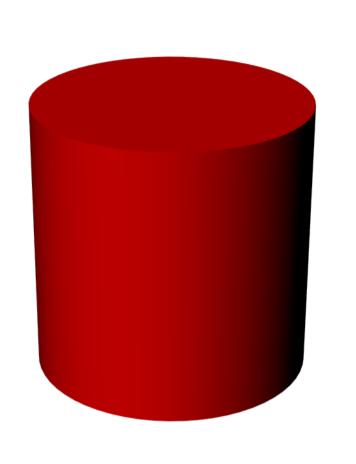
B-rep *graphical rendering*

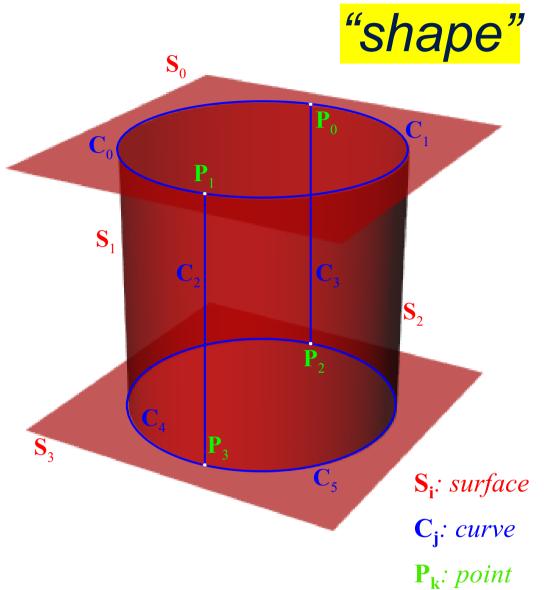
B-rep geometry

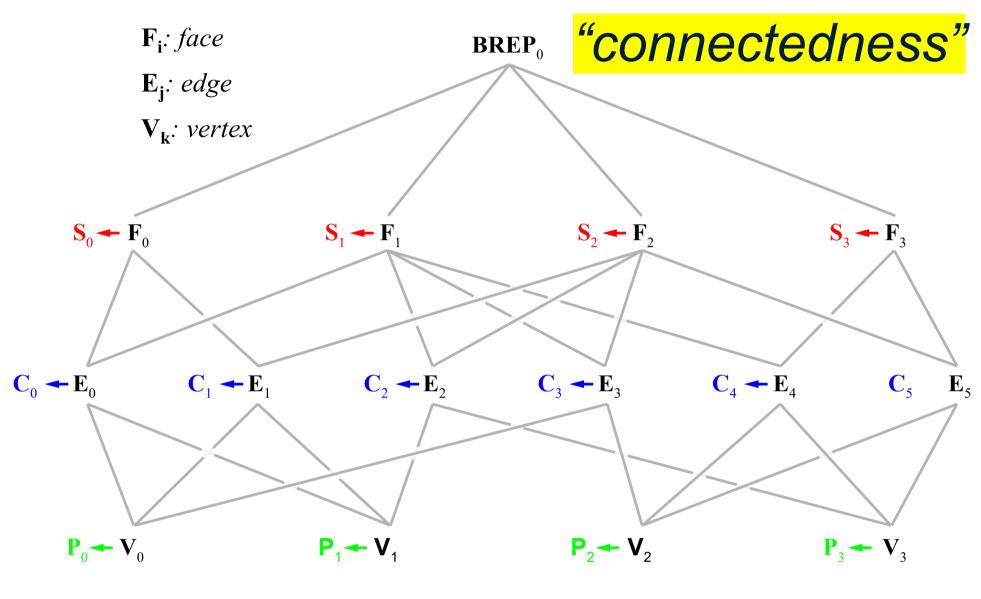
geometrically <u>non</u>-watertight:

lacking G^n , C^n continuity









B-rep *graphical rendering*

B-rep geometry

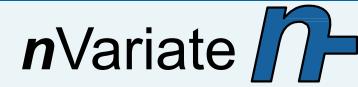
geometrically <u>non</u>-watertight:

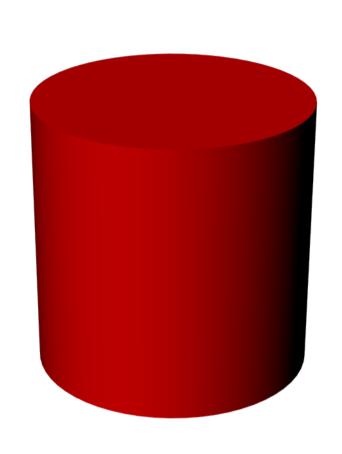
lacking G^n , C^n continuity

B-rep topology

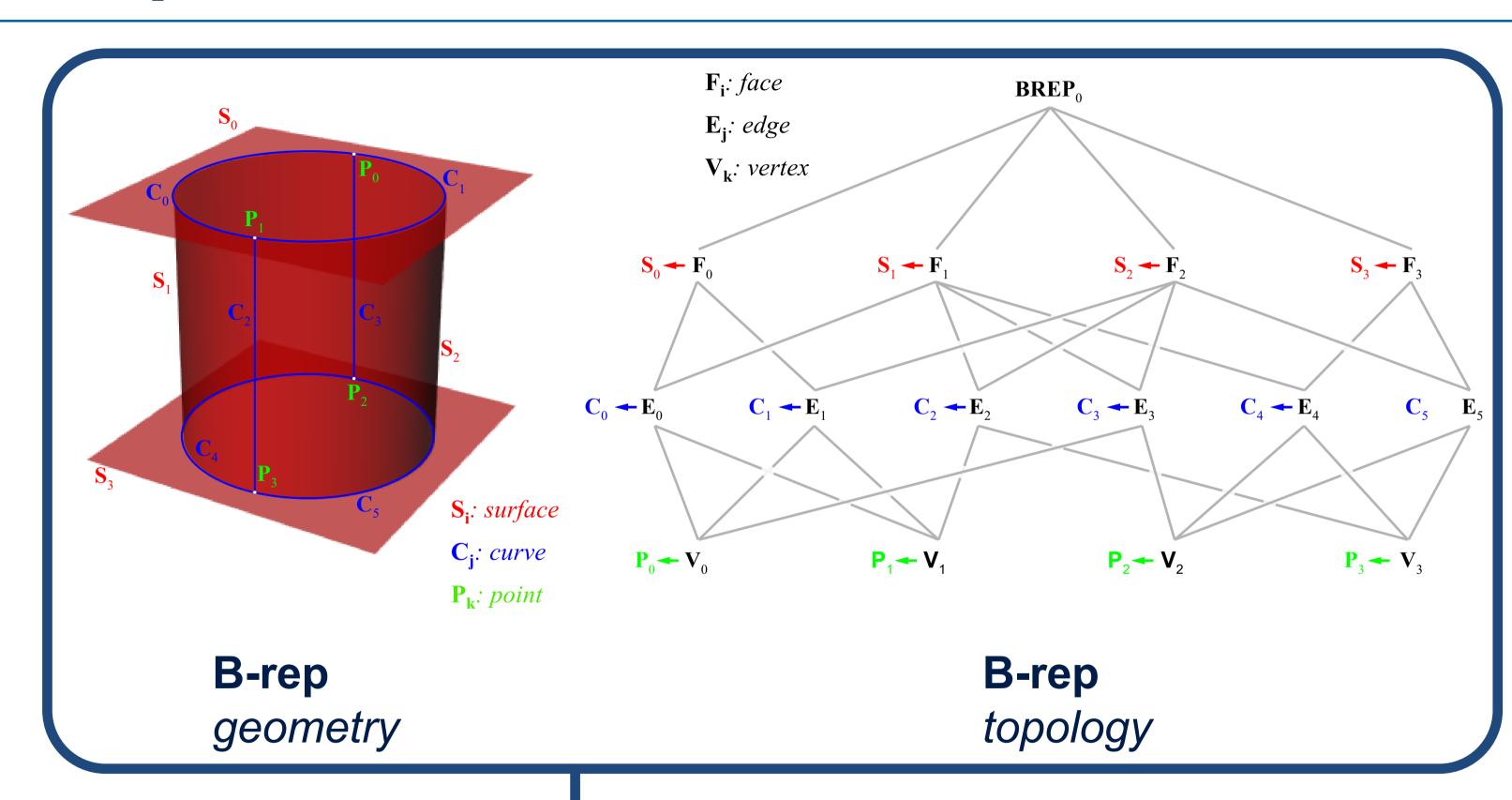
topologically watertight:

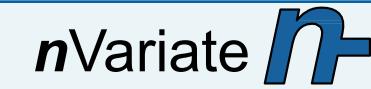
graph ("face-edge-vertex") satisfying closure metric



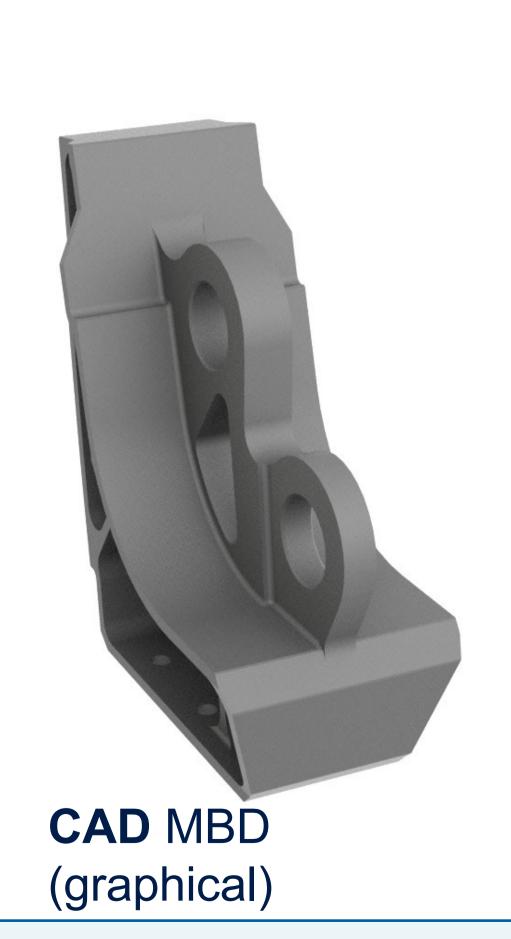


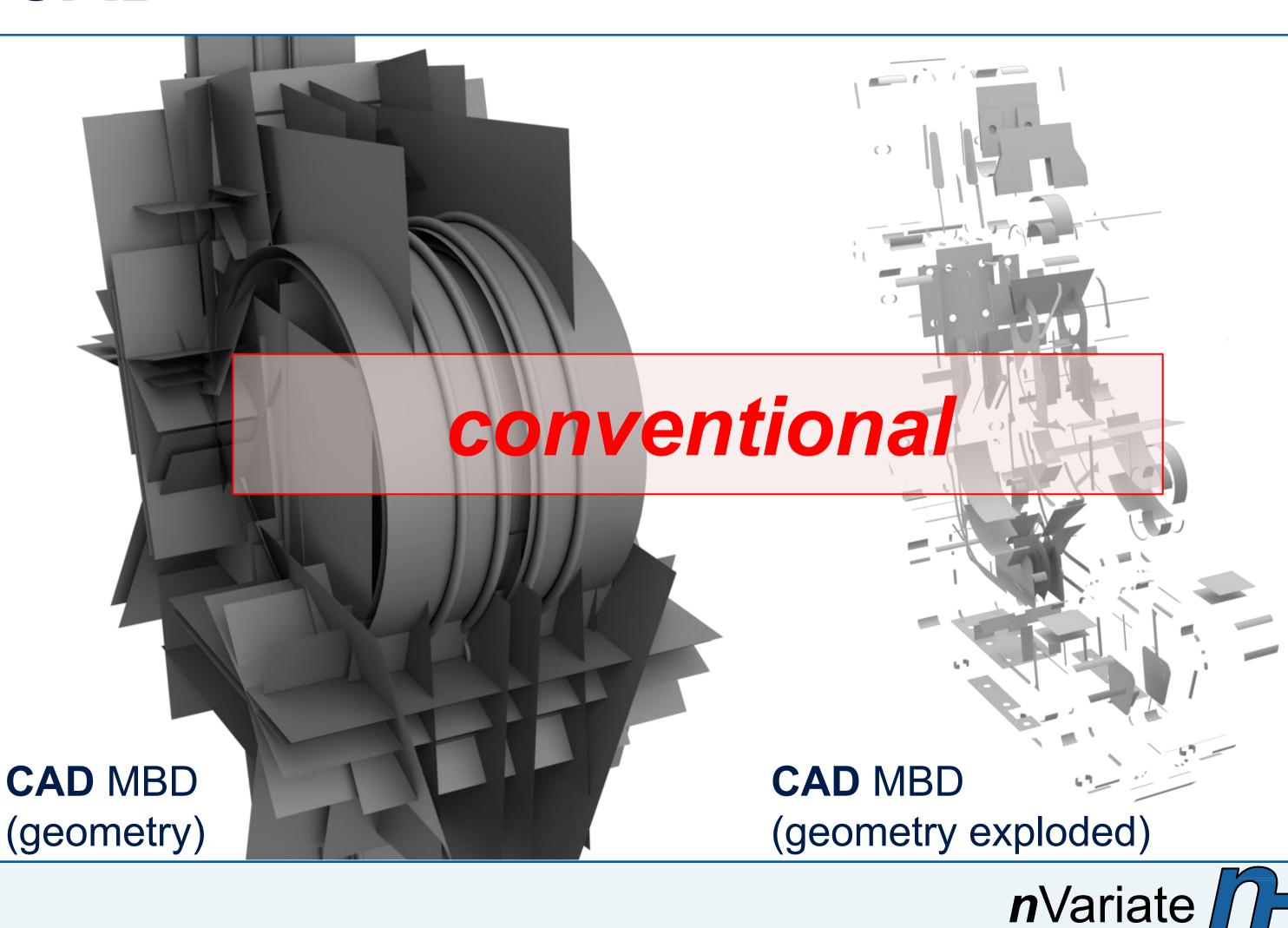
B-rep *graphical rendering*



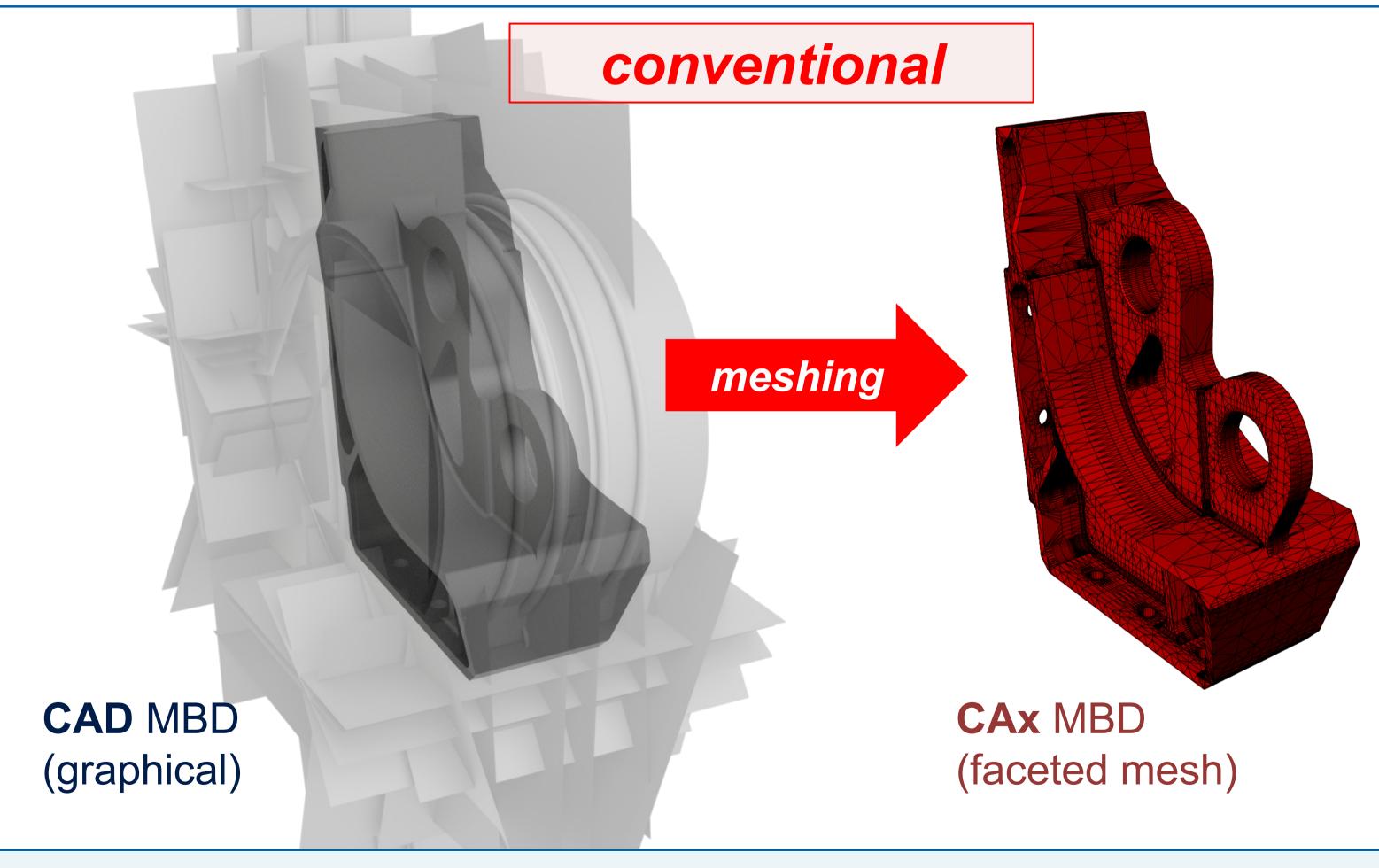


Conventional CAD

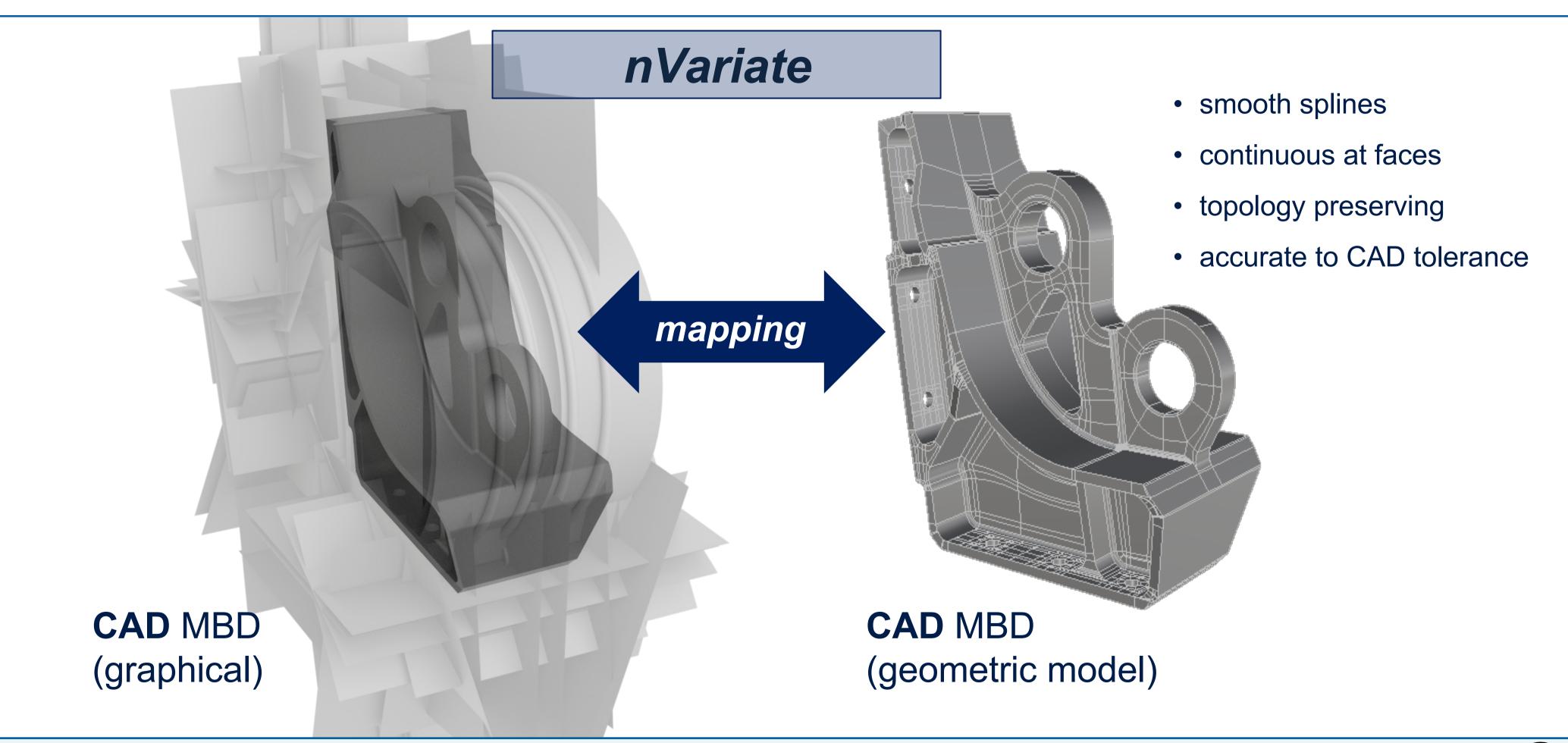




Conventional CAD-CAx meshing workflow



The nVariate approach



The nVariate approach

B. Urick, B. Marussig, E. Cohen, R. H. Crawford, T. J. R. Hughes, and R. F. Riesenfeld, Watertight Boolean operations: A framework for creating CAD-compatible gap-free editable solid models, Computer-Aided Design 115 (2019) 147–160.

Computer-Aided Design 115 (2019) 147-160



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Computer-Aided Design

journal homepage: www.elsevier.com/locate/cad



Watertight Boolean operations: A framework for creating CAD-compatible gap-free editable solid models*,**



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Trimmed surfaces NURBS Surface intersections SSI Trim problem Direct modeling

Keywords

ABSTRACT

Boolean operations are fundamental for geometric modeling, but the resulting objects, defined by trimmed surfaces, are often difficult to edit directly, possess robustness issues, and lead to problems of watertightness for downstream users. We propose a framework that helps resolve these adverse side-effects based on a new modeling philosophy for dealing with the inevitable approximations involved with surface-to-surface intersections. The methodology uses a three-stage process of analysis of parametric space, reparameterization, and model space update to provide a well-defined mapping between conventional trimmed models and gap-free versions. The resulting models are watertight, consisting of un-trimmed surface patches of explicit continuity, and accurate to the same model tolerance employed in existing CAD systems. The core procedure uses information computed during conventional Boolean operations, and thus it can be easily integrated into existing CAD frameworks utilizing B-rep data structures. We also present several extensions to the basic framework that allow for further modeling options such as feature-based imprinting, partial Boolean operations, and compatibility with unstructured spline schemes.

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1. Introduction

Boolean operations form an essential pillar of any solid modeling approach. The framework presented herein introduces a new paradigm for addressing the unavoidable geometric inconsistencies of trimmed surface models resulting from Boolean operations. Based on the information provided by a trimmed model, a mapping to a watertight spline representation is established, as shown in Fig. 1. Isoparametric curves (isocurves) of this surface represent surface intersections to model tolerance.

This paper has been recommended for acceptance by Pierre Alliez, Yong-Jin

Early research focused on developing robust algorithms to perform Boolean set operations among objects [1]. This established the paradigm of using Boolean operations as a fundamental modeling tool for hierarchically creating complex objects through set operations of simpler ones. Most current CAD modelers have adopted Non-Uniform Rational B-splines (NURBS) surfaces, which are generalizations of polynomial surfaces, because of their rich representational power, from conic sections to freeform geometry [2–4]. Hence, the canonical solid modeling intersection problem has become a problem of computing the intersection between two parametric surfaces [5,6]. This surface-to-surface intersection (SSI) problem has been shown to be mathematically intractable to compute in closed form [7], leading to the development of a large number of approximation schemes.

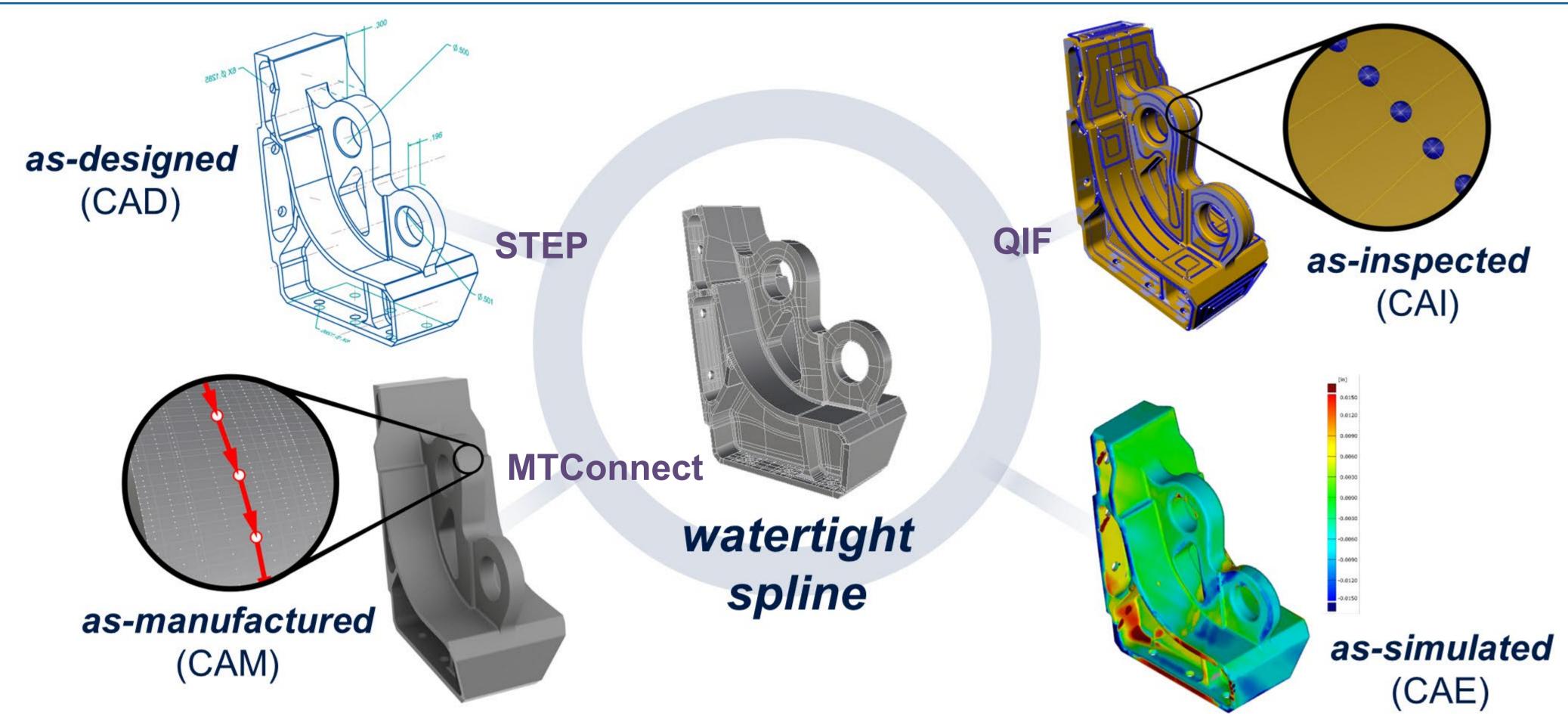
Boolean operations involving parametric surfaces can result



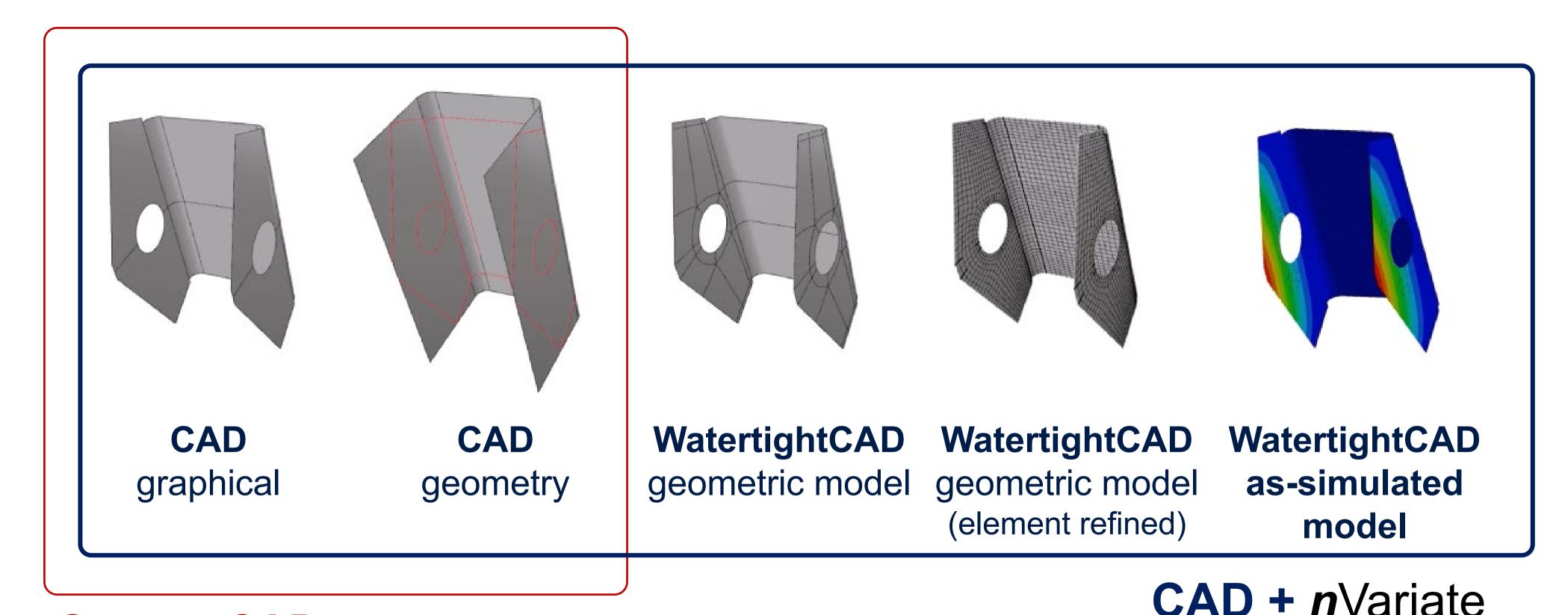
The nVariate approach: as-x modeling



The nVariate approach: as-x modeling



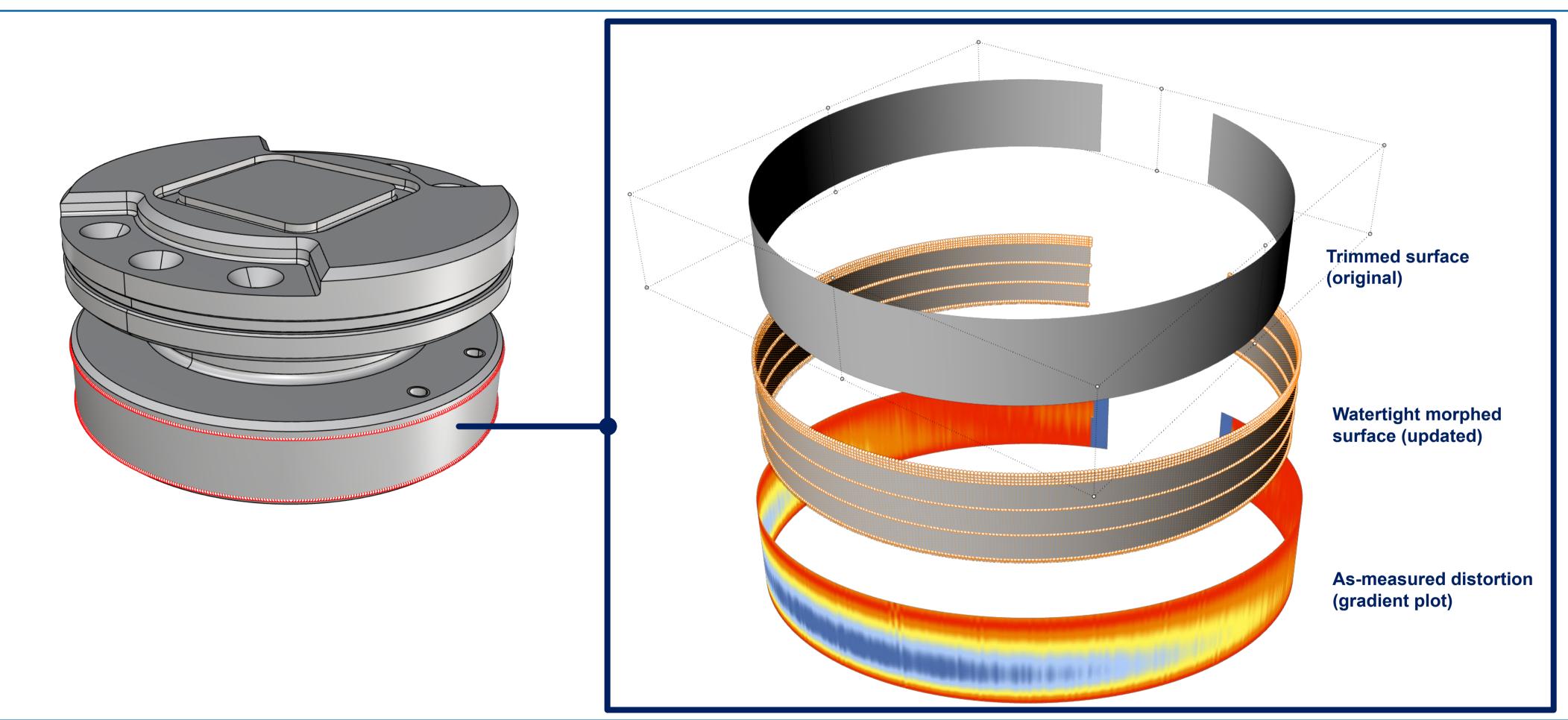
The nVariate approach: as-simulated (CAE)



Current CAD

*n*Variate

The nVariate approach: as-inspected (CAI)





Background

Ben Urick
 ISO 10303 (STEP) leader – geometry and topology
 (ISO SC4 TC184 WG12 T1)

International Organization for Standardization

TC 184 Technical Committee 184, "Automation systems and integration"

SC 4 Subcommittee 4, "Industrial data"

WG 12 Working Group 12, "STEP product modelling and resources"

Technical group 1, "Geometry and Topology"

support from:

National Institute of Standards and Technology (NIST)

Communications Technology Laboratory (CTL)

The Smart Connected Systems Division (SCSD)

Smart Connected Manufacturing Systems Group



Current MBD issues

Current MBD issues

Consistent theme:

- Blind implementation / expectations of MBE technology
 - Unclear use-cases
 - Undefined value-adds

Current MBD issues

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- Blind implementation / expectations of MBE technology
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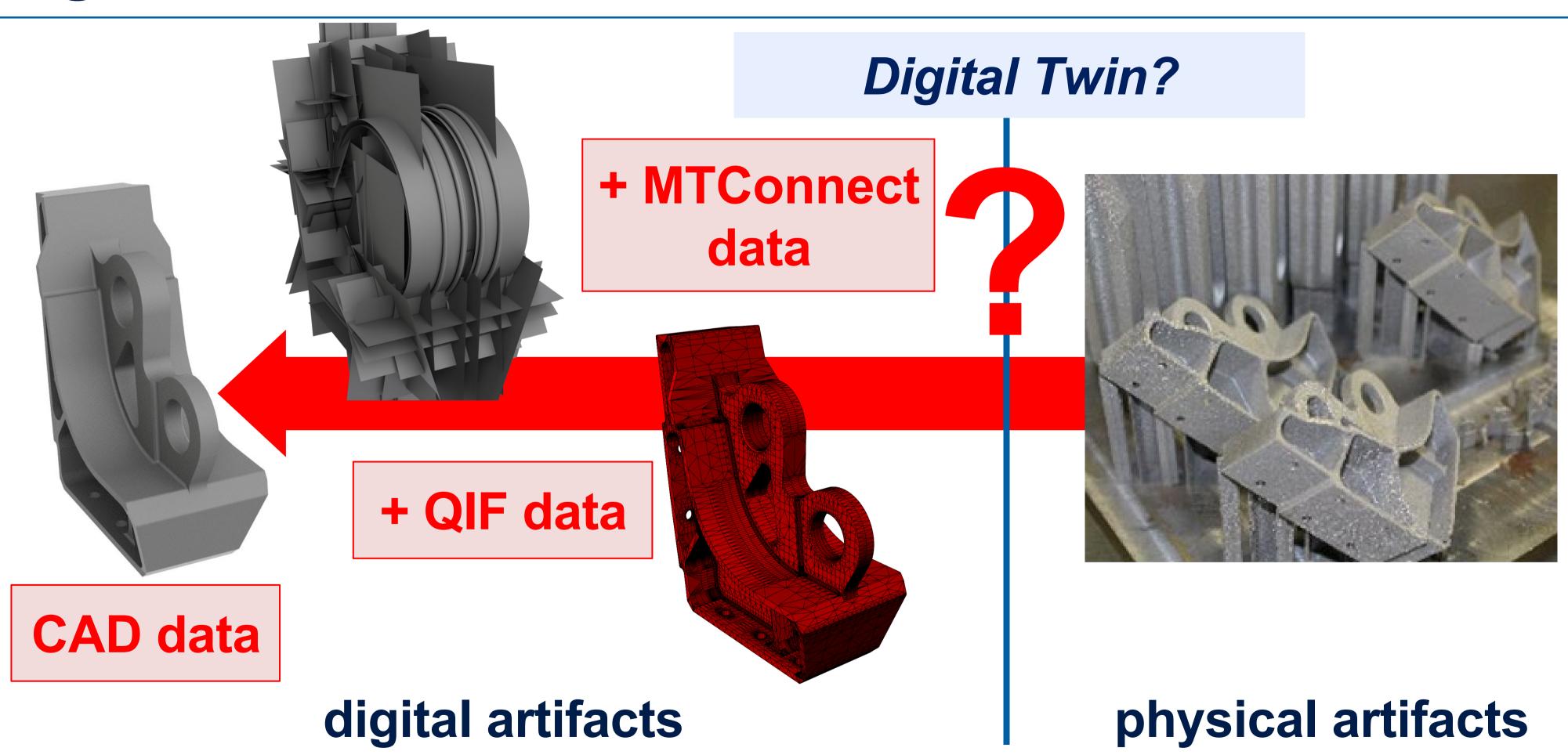
MBD manager questions:

- Do you have clearly defined deliverables / requirements?
- Do you have a defined workflow to achieve those deliverables?
 - ...is it model-based???



Digital Twins

Digital Twins



Digital Twins in MBD

- current digital twin definitions used contain vague "boxes and arrows" as descriptions
- from a geometric and solid modeling perspective
 - aspirational goals or actual MBD implementations?
 - not based in real data / use cases / workflows
 - no "there there" from a geometric / solid modeling perspective

Digital Twins in MBD

- current digital twin definitions used contain vague "boxes and arrows" as descriptions
- from a geometric and solid modeling perspective
 - aspirational goals or actual MBD implementations?
 - not based in real data / use cases / workflows
 - no "there there" from a *geometric / solid modeling* perspective

- digital twin only can be defined by use-case / value add
- there is no digital twin without a digital twin use-case
 what are you going to do with this "twin" and what value does it give to your business?



MBD: STEP AP242 OR QIF?

MBD: STEP AP242 OR QIF?

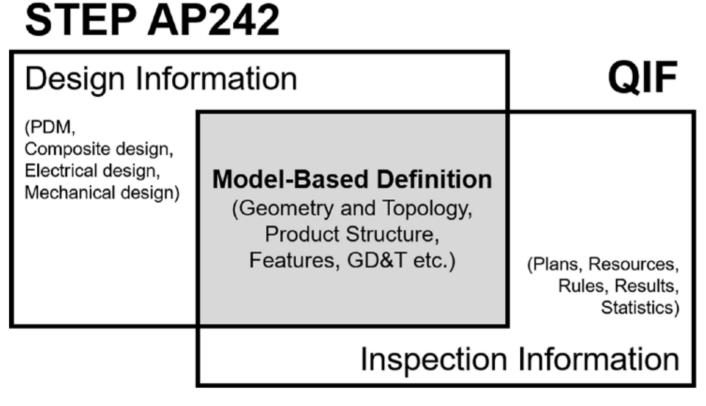
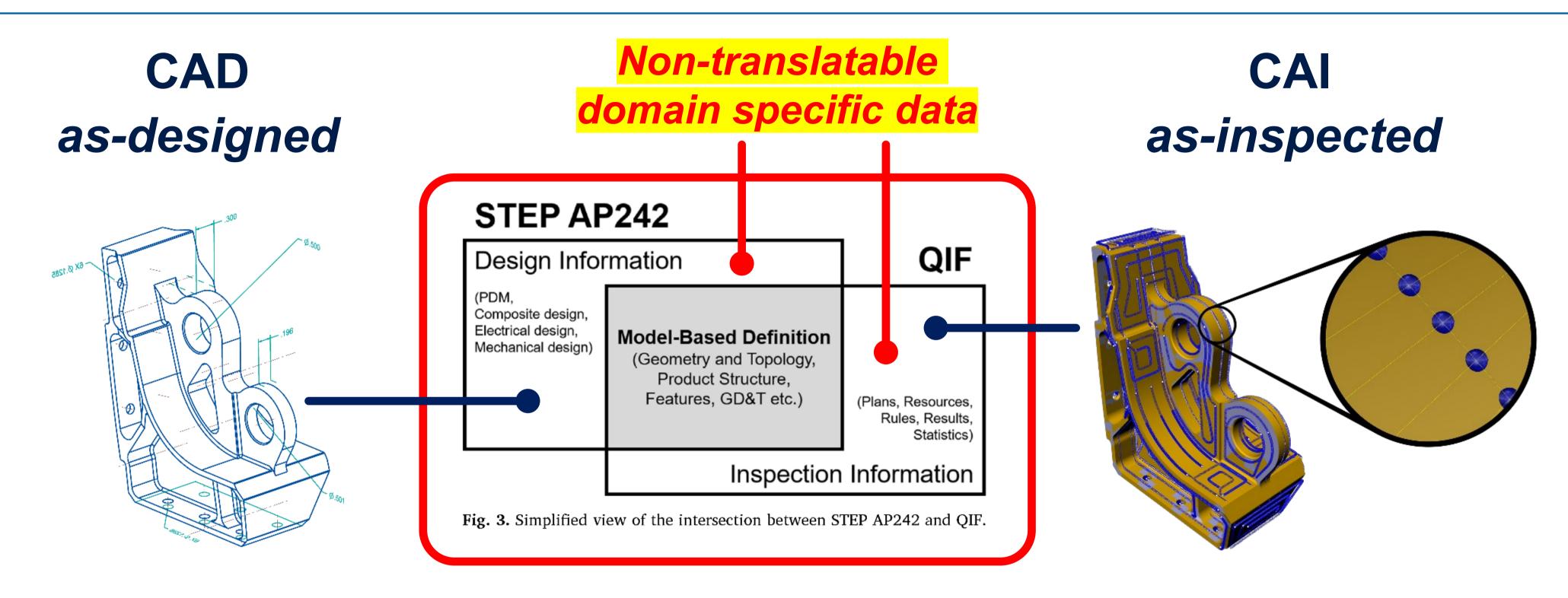


Fig. 3. Simplified view of the intersection between STEP AP242 and QIF.

S. Kwon, L. V. Monnier, R. Barbau, and W. Z. Bernstein, "Enriching Standards-Based Digital Thread by Fusing As-Designed and As-Inspected Data Using Ontologies," vol. 46, Aug. 2020.

MBD: STEP AP242 AND / OR

QIF?



S. Kwon, L. V. Monnier, R. Barbau, and W. Z. Bernstein, "Enriching Standards-Based Digital Thread by Fusing As-Designed and As-Inspected Data Using Ontologies," vol. 46, Aug. 2020.

MBD: STEP AP242 AND / OR



- STEP and QIF manage different domains of data (design and inspection, respectively)
- These data domains contain unique elements that are non-translatable
- Having both CAD and CAI data requires managing MBD and PMI
- MBD and PMI exchange is ultimately driven by use-case / value-add needs managed by personnel to be made business specific

"Features"

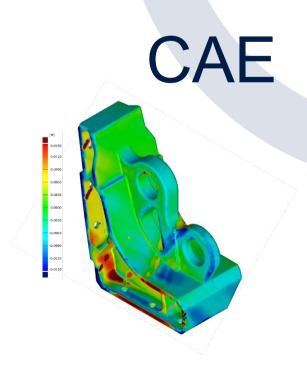
"Features"

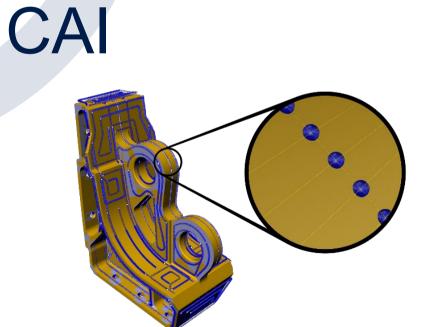
design features



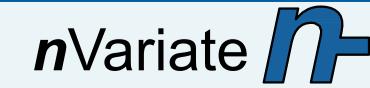
manufacturing features

engineering features

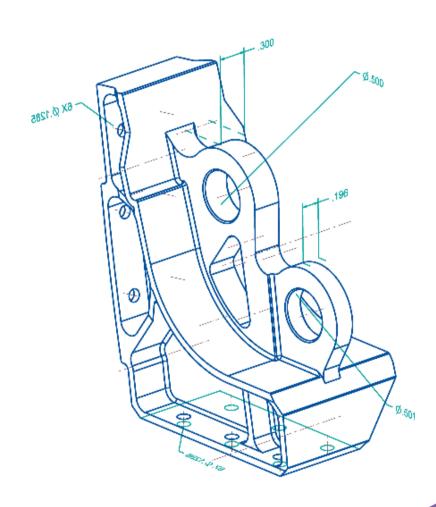




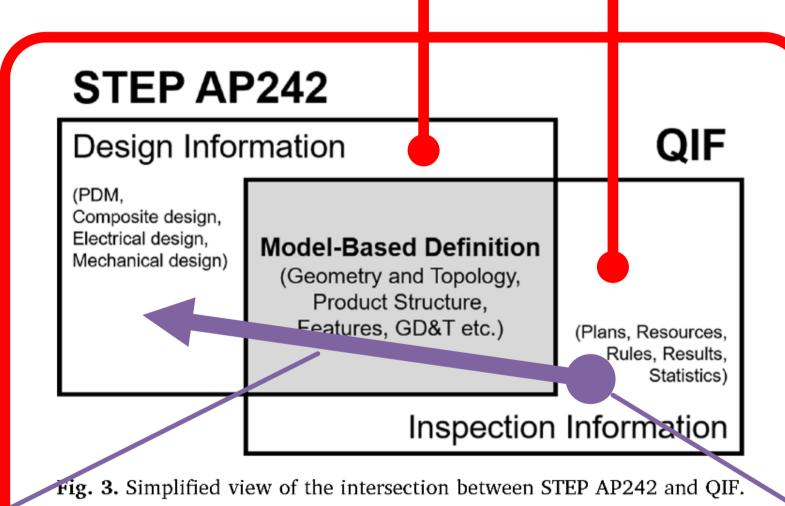
inspection features



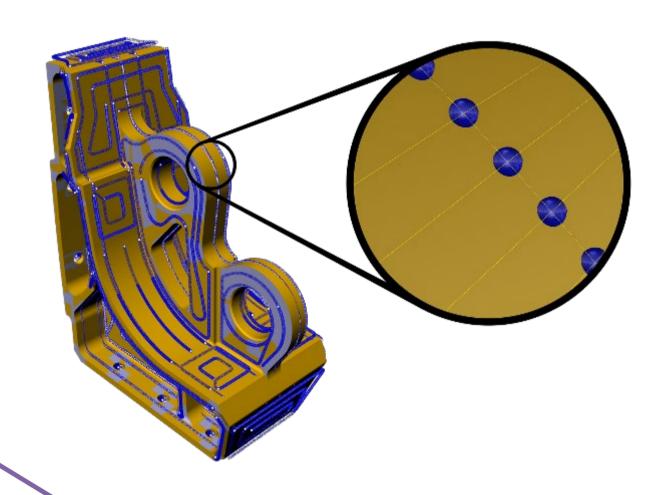
CAD as-designed



Non-translatable domain specific data



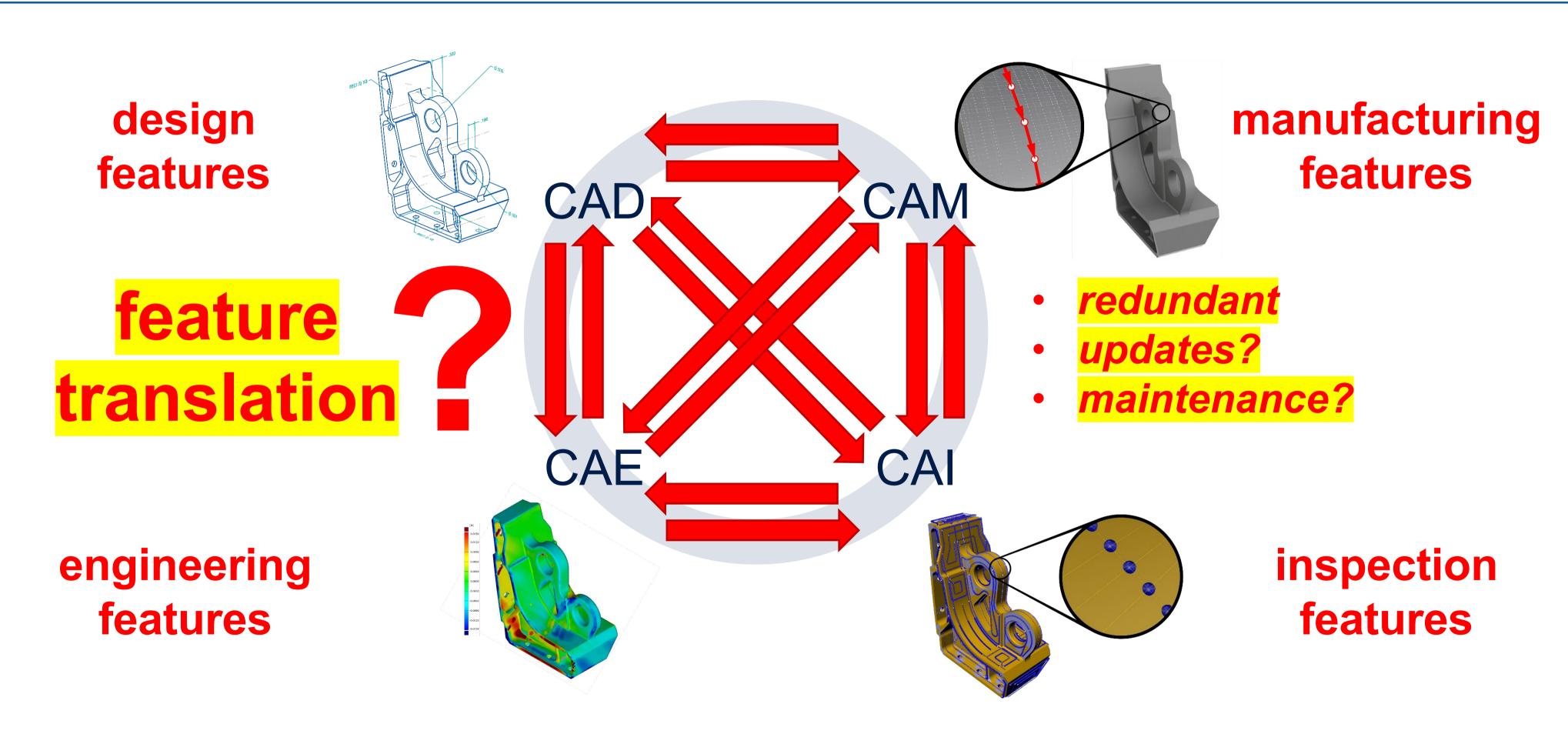
CAI as-inspected

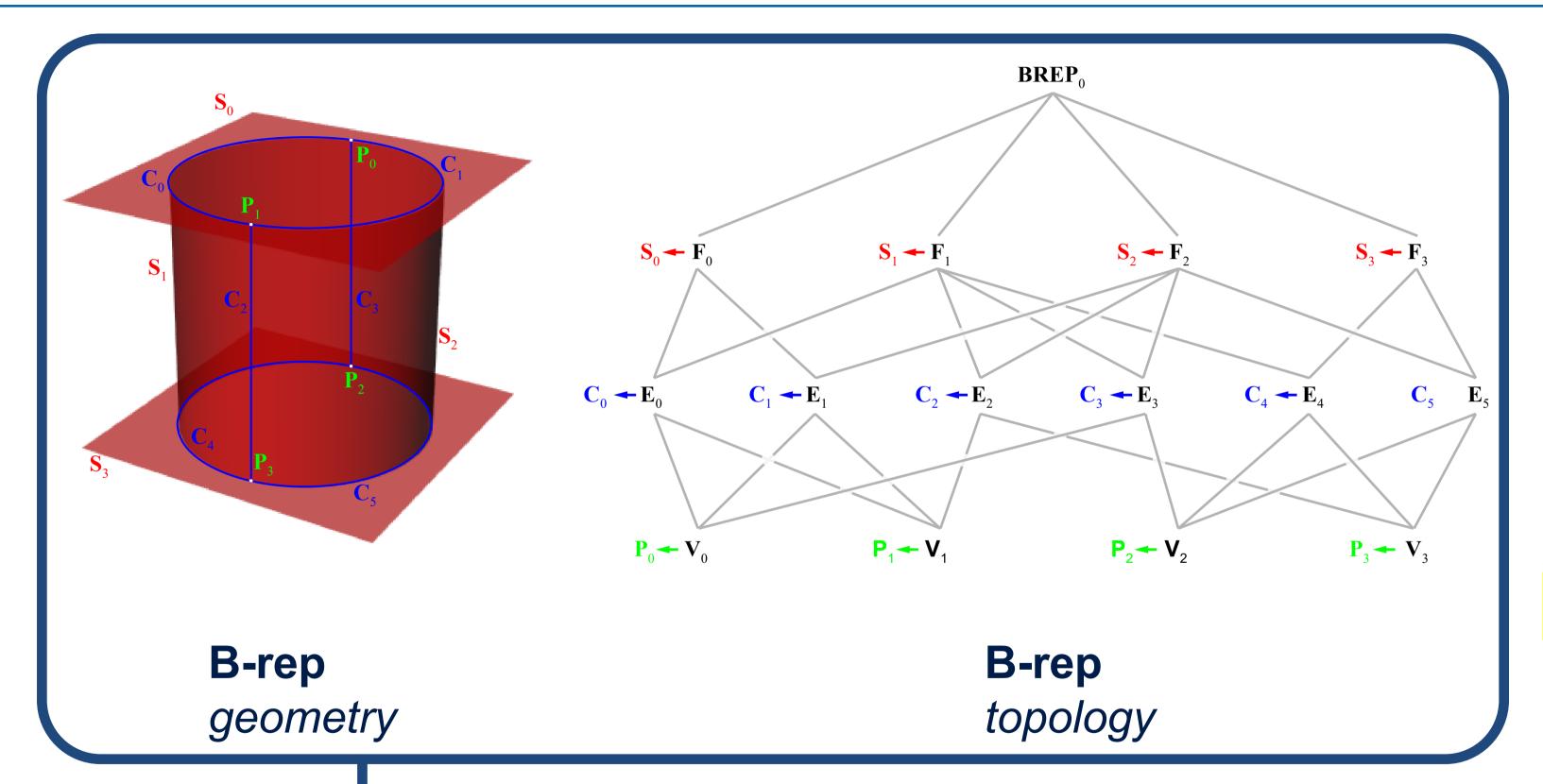


mapping?

S. Kwon, W. Z. Bernstein, L. V. Monnier, and R. Barbau, "Enriching Standards-Based Digital Thread by Fusing As-Designed and As-Inspected Data Using Ontologies," vol. 46, Aug. 2020.

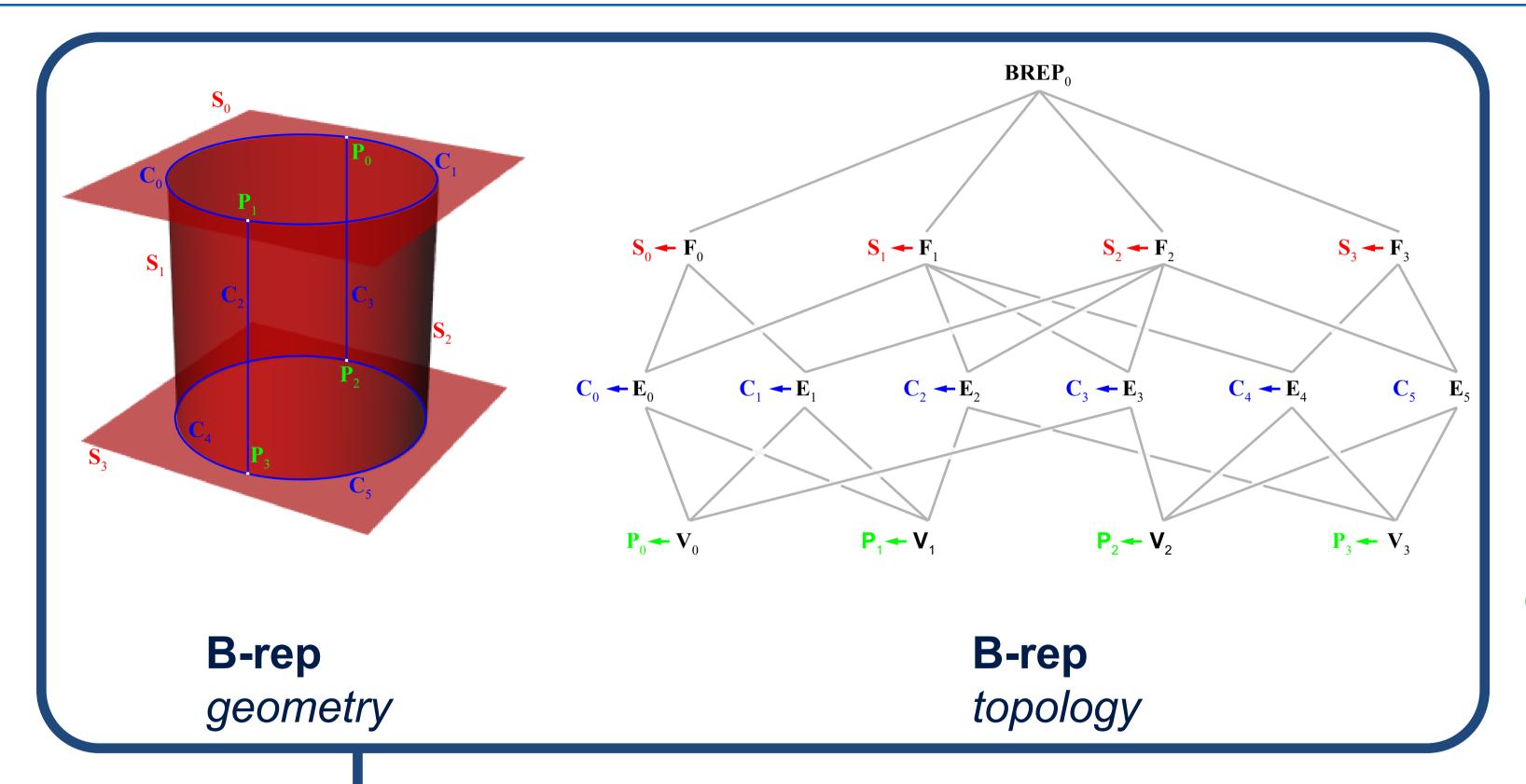
inspection features





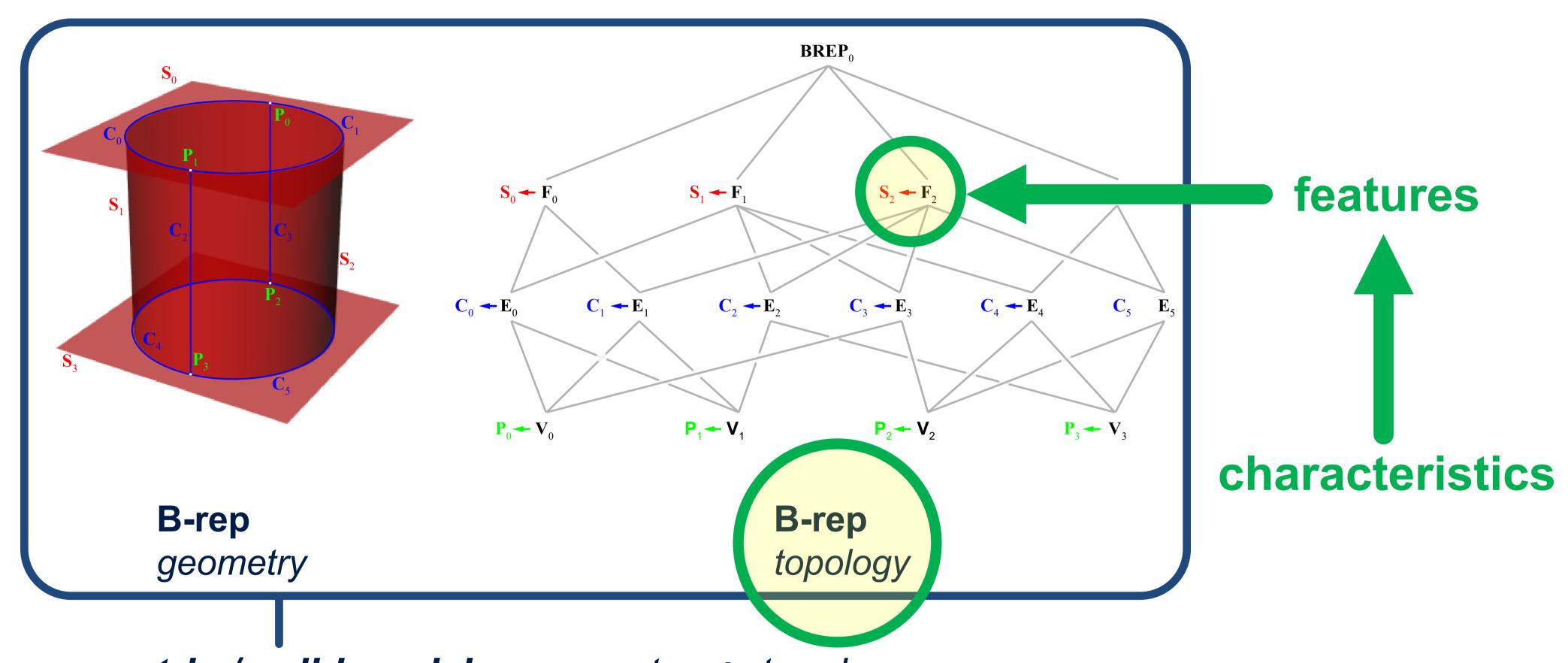
characteristics











Across CAx domains:

Feature mapping



Feature reference / tracking



How to distinguish in data exchange?
 graphical and semantic are in dedicated scopes of standards

- How to distinguish in data exchange?
 graphical and semantic are in dedicated scopes of standards
- What standard are CAD models for downstream CAx use authored to?

ASME Y14.41 MBD

- 1. "geometry"
- 2. annotations
- 3. attributes
- 4. presentation



How to distinguish in data exchange?
 graphical and semantic are in dedicated scopes of standards

What standard are CAD models for downstream CAx use authored to?

ASME Y14.41 MBD

1. "geometry"

2. annotations

3. attributes

4. presentation

no reference to:

geometric model, topology

graphical vs semantic

PMI



- How to distinguish in data exchange?
 graphical and semantic are in dedicated scopes of standards
- What standard are CAD models for downstream CAx use authored to?

ASME Y14.41 MBD

- 1. "geometry"
- 2. annotations
- 3. attributes
- 4. presentation

no mapping:



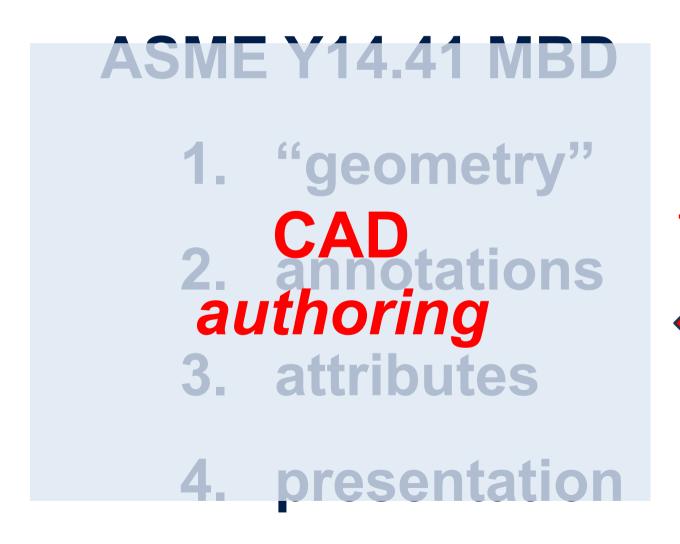
geometric model, topology

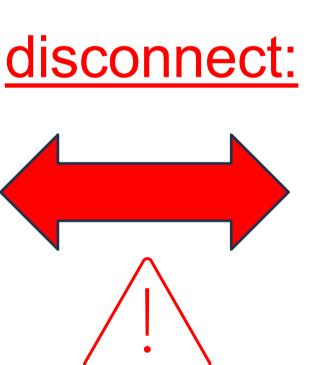
graphical vs semantic

PMI



- How to distinguish in data exchange?
 graphical and semantic are in dedicated scopes of standards
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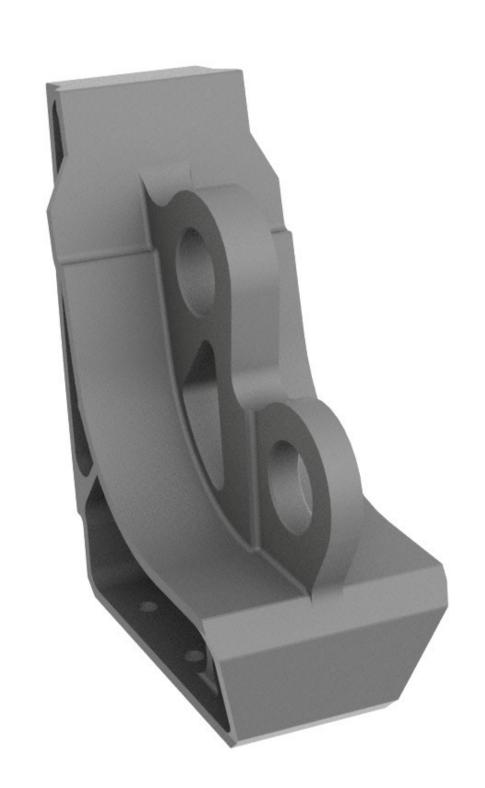




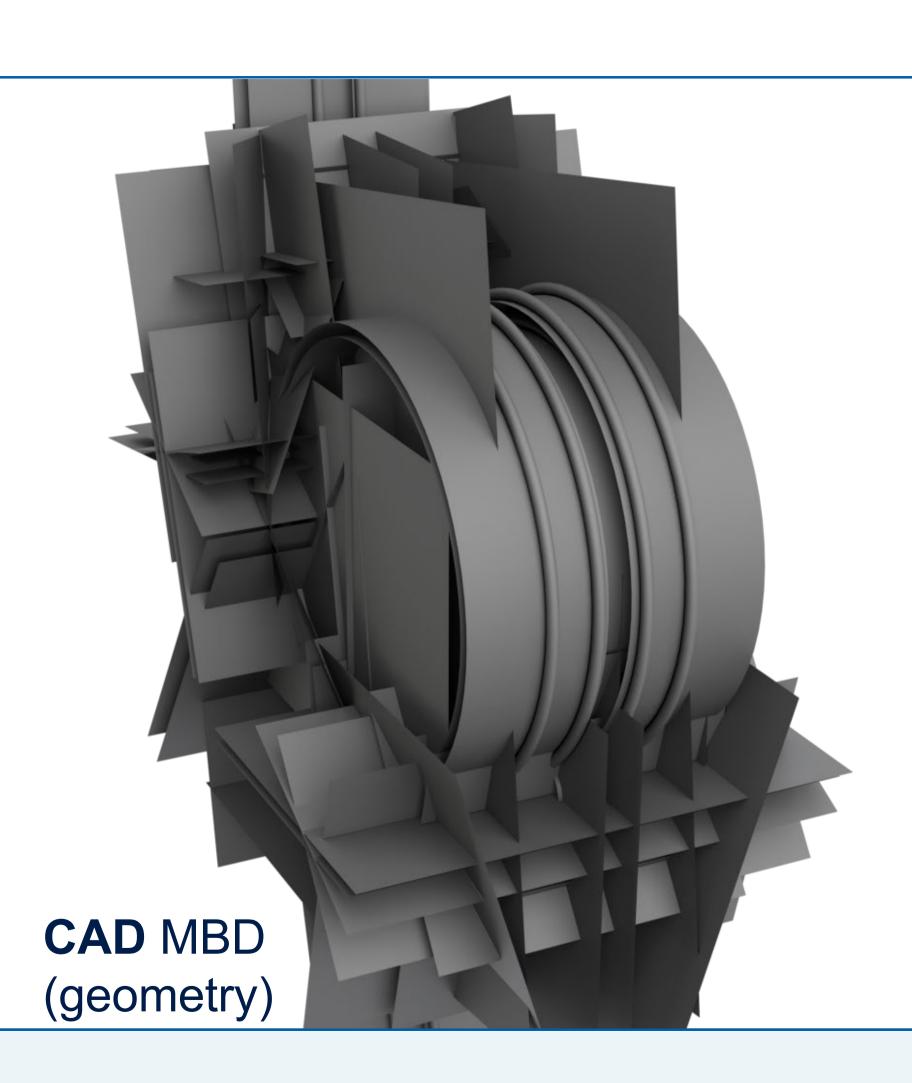
geometric model, topology
CAI, CAM, CAE
graphical vs semantic
downstream consumption
PMI

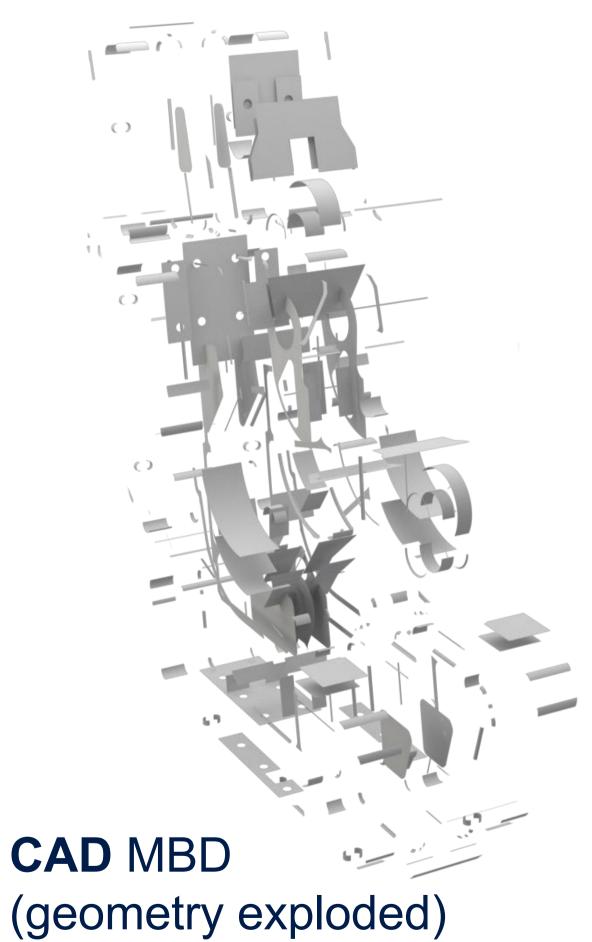


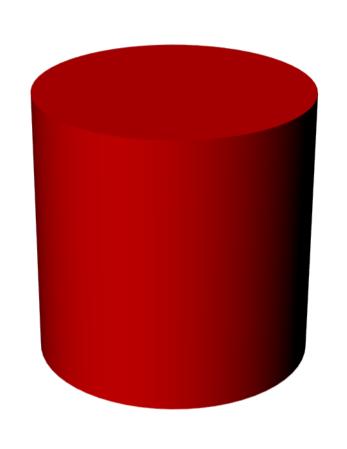
PDQ := "Product Data Quality"



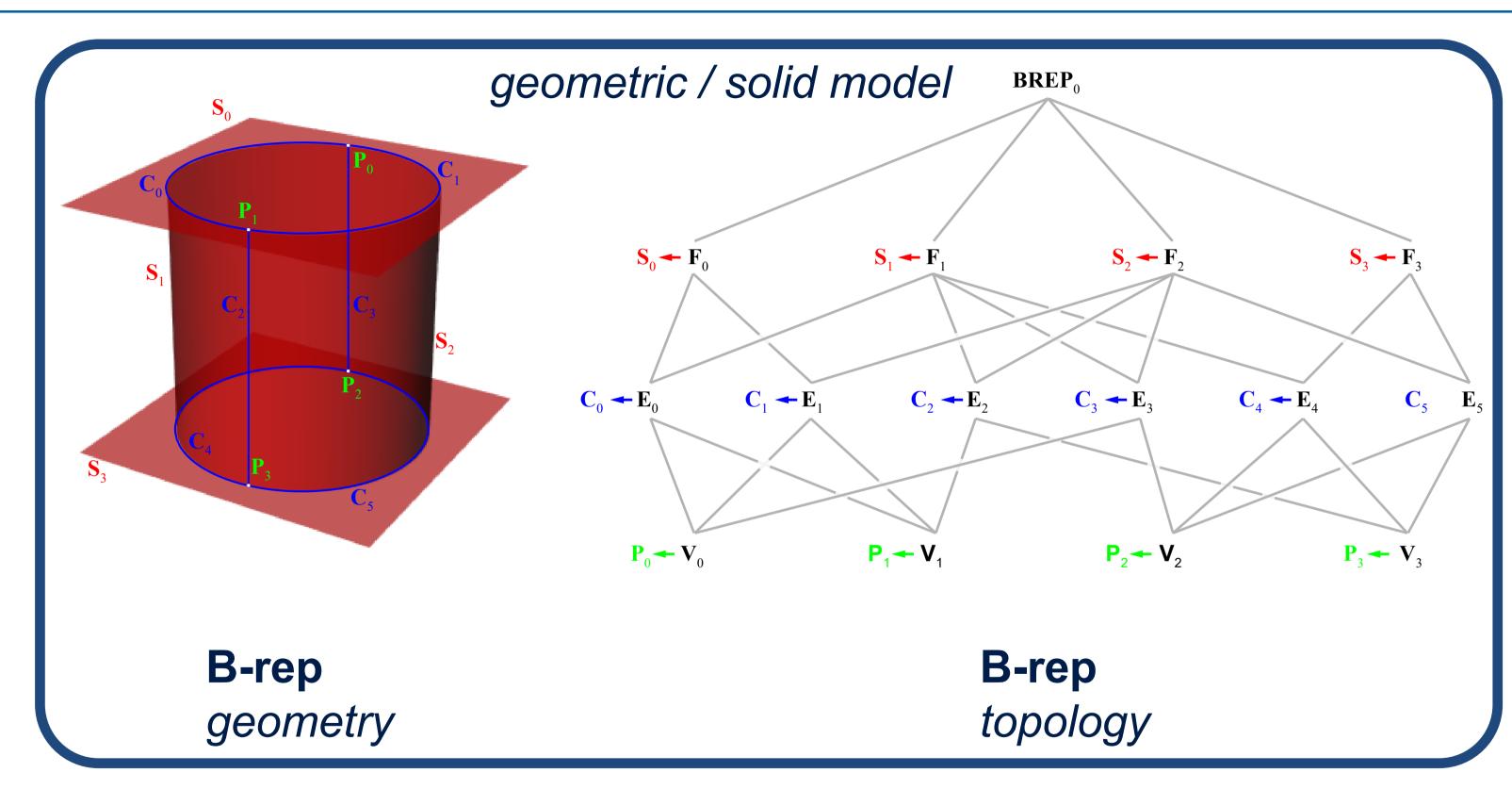
CAD MBD (graphical)







B-rep *graphical rendering*



geometrically <u>non</u>-watertight:

lacking G^n , C^n continuity

topologically watertight:

graph ("face-edge-vertex") satisfying closure metric



- PDQ := "Product Data Quality"
- ASME Y14.41 see new additions for model accuracy in next edition

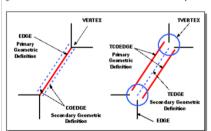
ACIS was developed as an exact modeler, because accurate models are both robust and reliable. A model's geometry which contains the mathematical definitions describing the intersections, agrees with the topology, which shows how model elements are connected together

with the topology, and takes the geometric error in the topology into consideration during modeling operations

ACIS uses SPAresabs as a tolerance value for all calculations on an exact model. Tolerant modeling assigns a tolerance value to each tolerant edge and tolerant vertex as part of the topology. This happens only when required to maintain model topology integrity.

six faces, 12 edges, and 24 coedges. In an exact model, a coedge of one face references the same underlying geometric definition as a coedge of an adjacent face. There is one edge intersection for both. However, if one of the faces of the rectangular block isn't lined up properly with another adjacent face, the pair of associated adjacent coedges do not reference the same underlying geometric definition. The coedge(s) and edge do not represe same geometric position, and the model is considered

Figure 6-1 shows the difference between an exact edge and a tolerant edge. The left side of the figure illustrates the exact topology, where the EDGE contains the primary geometric definition and the COEDGE the secondary.



Tolerance Variables

order to maintain model integrity, the modeler must work to specified tolerances. Applying ances insures proper interpretation of positions, such as maintaining that the points of cess lie on the curves of the edges they bound or correctly determining if a position is

ACIS uses the tolerance variables SPAresabs, SPAresnor, and SPAresfit to control modeling All modeling operations in ACIS use these tolerance variables to maintain consistency of mathematical operations. Although SPAresnor should not be changed by the application, SPAresabs and SPAresfit may be changed, with great care, as explained in this chapter.

SPAresabs

SPAresabs is named for resolution absolute. It is the smallest meaningful quantit representable in ACTS. This can be interpreted as the distance below which ACIS co we points to be coincident. If two points, A and B, are separated by less than SPAresabs. they are considered to be the same point.

SPAresabs also represents the smallest feature being modeled, since it is the smallest distance between two points. The default value is 10%. The default value was chosen assuming that at least an order of magnitude guard band around SPAresabs is required. Refer to the section Dynamic Range for more information.

SPAresnor

SPAresnor is named for resolution normalized. This is the ratio of the smallest meaningful quantily representable in ACIS (SPAresabs) to the largest. This reflects the precision to which numerical values are calculated and stored. The default value is 10⁻¹⁰.

largest =
$$\frac{\text{SPAresabs}}{\text{SPAresnor}} = \frac{10^{-6}}{10^{-10}} = 10^4$$

SPAresfit

SPAresfit is named for resolution fit. This is used as a guide to the fitting algorithms for the fit tolerance of an approximate curve or surface. The default value is 10⁻³.

Polynomial approximations are computed for some curves and surfaces in ACIS. The approximations are stored in the model together with their corresponding curve or surface definitions. The approximations are used:

- Alone when approximate geometry is sufficient (e.g., for drawing).





Models imported from other applications may be less accurate (use lower precision) compared with the high-accuracy models created in Parasolid. As a result, errors may become apparent in the imported model, for example, gaps arising between edges that would be considered coincident in the lower accuracy Tolerant modeling modeler.

> Parasolid uses Tolerant Modeling to accommodate low precision data by applying local tolerance information. This enables downstream modeling operations to proceed without errors arising due to the inaccuracy of the imported data.



About Part Accuracy

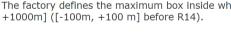
The accuracy settings for parts control the accuracy of geometry calculations. The valid range of part accuracy is from 0.01 through 0.0001. The default value of the default_abs_accuracy configuration option is 0, which creates a new empty part with an accuracy of 0.00039 inches, unless another value is defined. The smaller the value of part accuracy, the longer the regeneration time.



There are two types of accuracy

- Relative—The value should be set as less than half the ratio of the length of the smallest edge on the model to the length of the longest diagonal of the bounding box of the model. Use relative accuracy when you do not need to copy or import geometry from other parts or models.
- Absolute (default)—The value should be set as the smallest recognized size, measured in the current units. Use absolute accuracy when importing a part created using a different system or when copying geometry from one model to another. You must set a uniform absolute accuracy or select the smallest absolute accuracy value as the common accuracy value to make the parts compatible.

When matching absolute accuracy of two models defined with relative accuracy, determine the part sizes using Tools > Investigate > Model Size and multiply each by its respective relative accuracy. If the results differ, select a relative accuracy value that yields the same result for both parts. You may need to increase the part precision of the larger part by using a smaller relative accuracy value. For example, if the size of one part is 100 and its accuracy is 100 and its accurac product of these numbers is 1. If the size of the other part is 1000 and the accuracy is .01, the product of these numbers is 10. Change the second part to .001 to yield the same result.



Model Size: the Bounding Box of the CGM Model

The factory defines the maximum box inside which the geometric objects must be. This box is defined by the Model Size, fixed to 10^6mm (10^5mm before R14). As the unit is the millimeter, all the objects must be inside the box [-1000m,

Resolution: the Lower Valid Length of an Object of the CGM Model

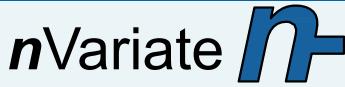
The Resolution defines the minimum length of a valid object. It is fixed to 10^-3.unit. As the unit is mm, lines of length smaller than 1micro-m are not valid.

The management of confusions ("Do two objects have the same geometry?") is a direct consequence of the resolution: if the distance between to geometric points is less than the resolution, the two points are considered to be geometrically at

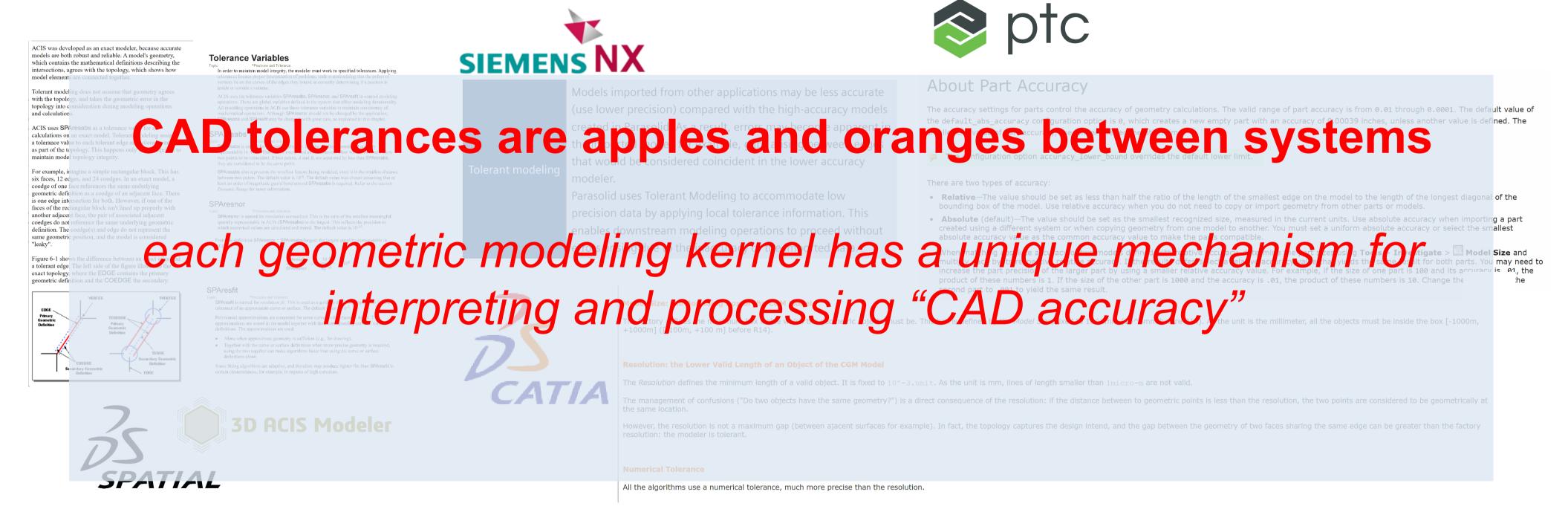
However, the resolution is not a maximum gap (between ajacent surfaces for example). In fact, the topology captures the design intend, and the gap between the geometry of two faces sharing the same edge can be greater than the factory resolution: the modeler is tolerant.

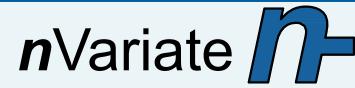
Numerical Tolerance

All the algorithms use a numerical tolerance, much more precise than the resolution

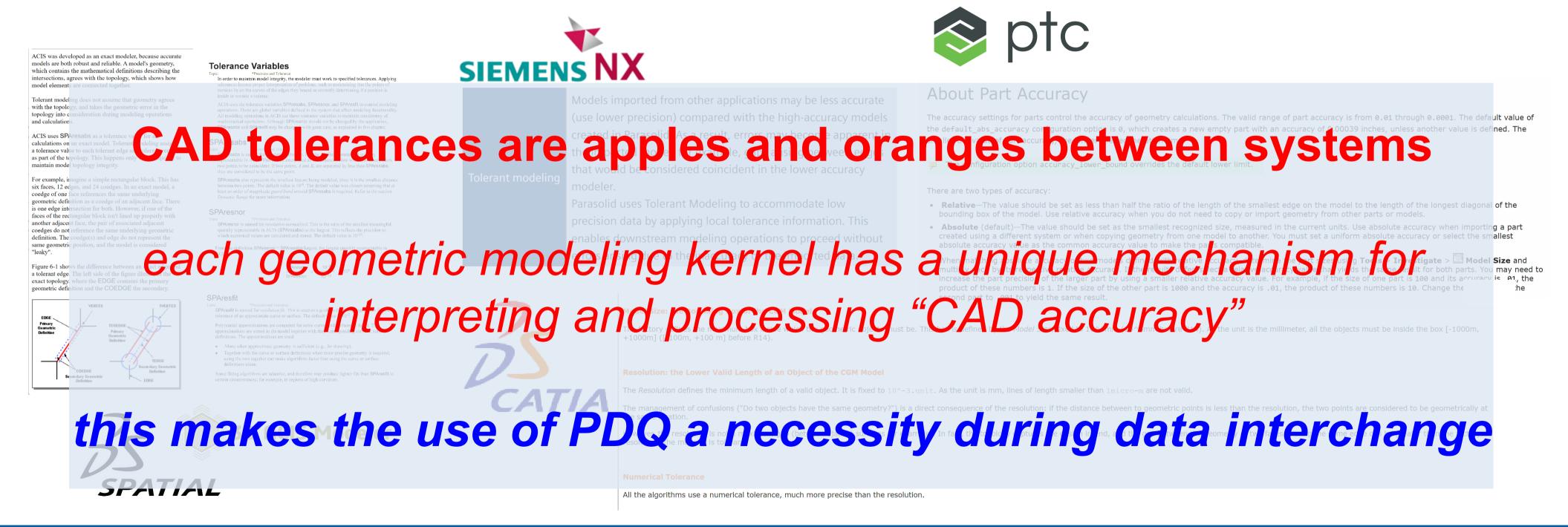


- PDQ := "Product Data Quality"
- ASME Y14.41 see new additions for model accuracy in next edition





- PDQ := "Product Data Quality"
- ASME Y14.41 see new additions for model accuracy in next edition





 a good reference on what PDQ is and what value it has in MBE Proceedings of the ASME 2007 International Design Engineering Technical Conferences & Computers and Information in Engineering Conference IDETC/CIE 2007
September 4-7, 2007, Las Vegas, Nevada, USA

DETC2007-34748

PDQ (PRODUCT DATA QUALITY): QUALITY GUARANTEED PRODUCT DATA REPRESENTATION AND APPLICATION TO SHAPE MODEL

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Department of Mechanical Systems Engineering,
Faculty of Engineering,
Toyama Prefectural University

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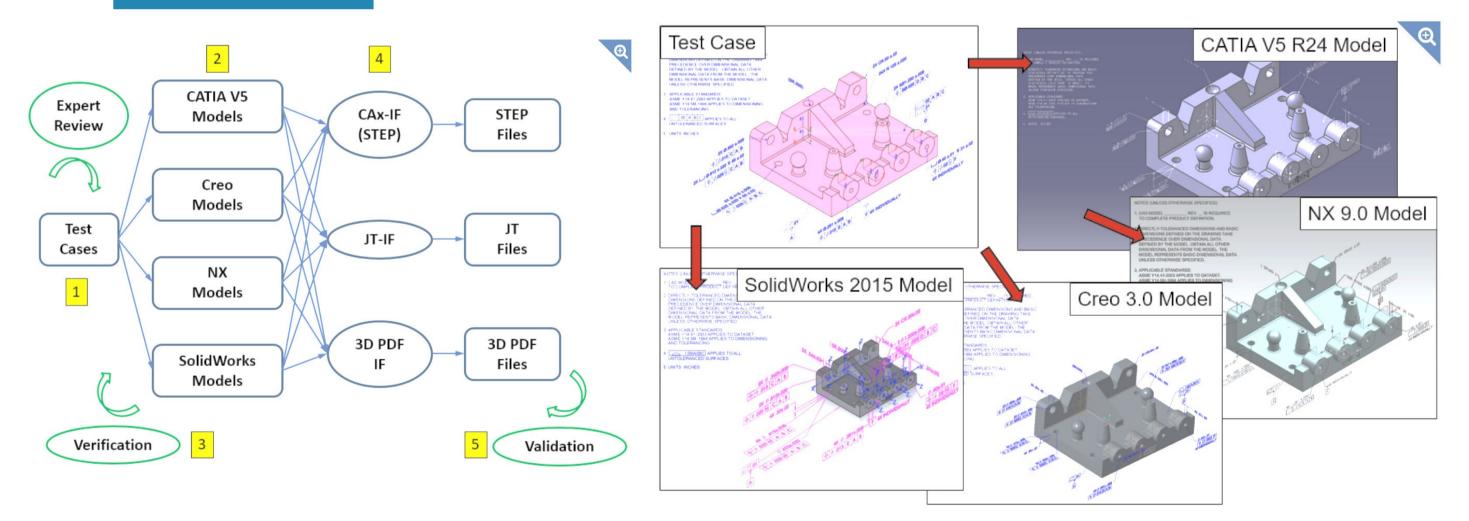


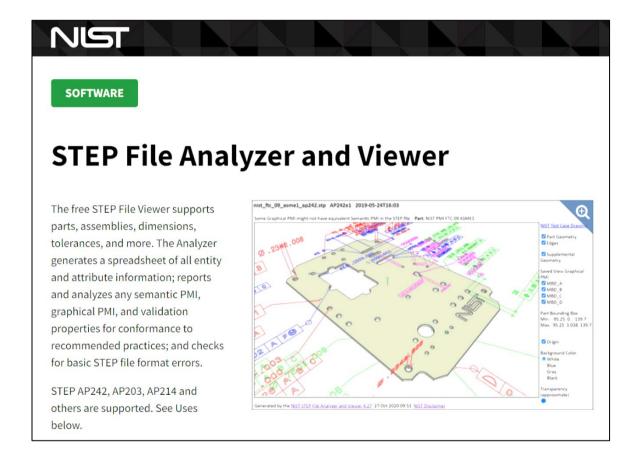


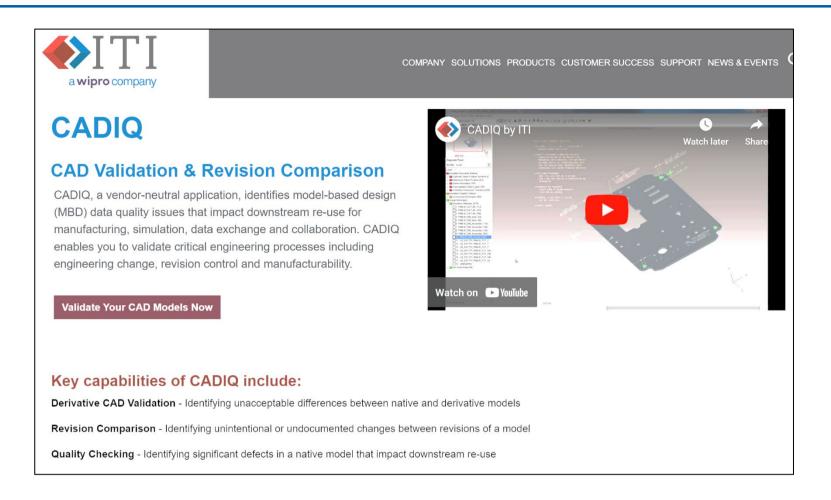
SMART CONNECTED MANUFACTURING SYSTEMS GROUP

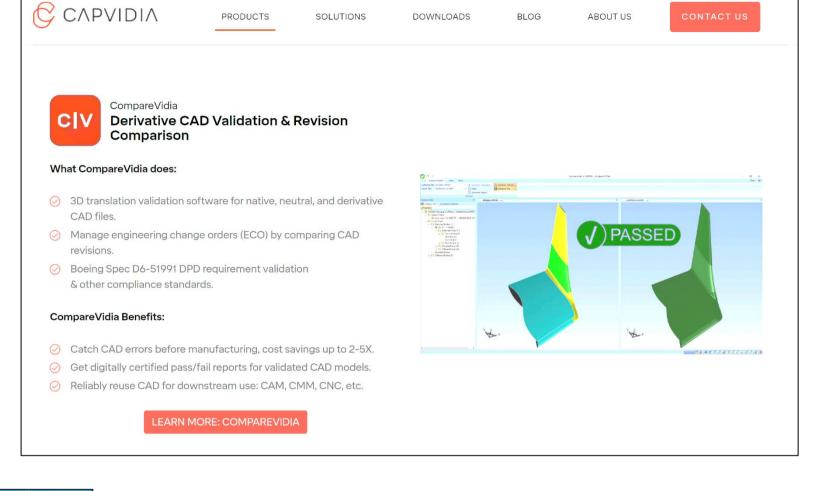
MBE PMI Validation and Conformance Testing Project

MBE PMI Validation and Conformance Testing Project

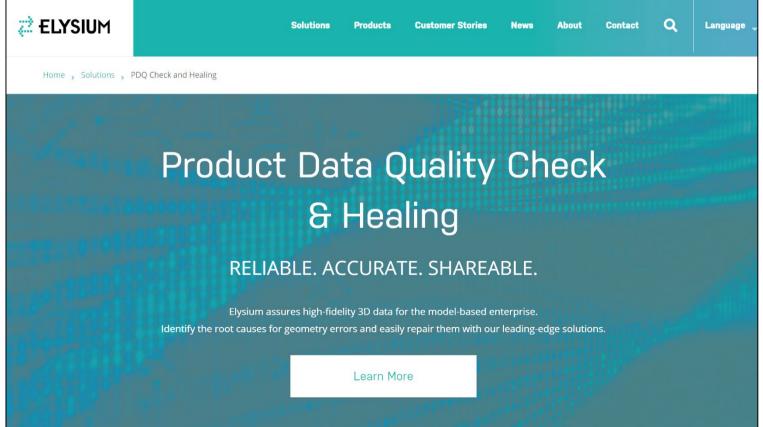


















- Generally underutilized; should be ubiquitous in digital thread (should ideally almost be running continuously in the background)
- Applies to both MBD and PMI (especially semantic checking!)
- PDQ criteria is ultimately driven by use-case / value-add
 needs managed by personnel to be made business specific

• UUID := Universally Unique Identifier

909c0b15-c752-4f4b-864c-fe41dcd5b2a2

• **IDs** (non-unique)

```
#23=OPEN SHELL('', (#24));
\#24 = \text{ADVANCED FACE}('', (\#25), \#54, .T.);
#25=FACE OUTER_BOUND('', #26,.T.);
#26=EDGE LOOP('',(#27,#28,#29,#30));
#27=ORIENTED EDGE('',*,*,<mark>#46</mark>,.T.);
#28=ORIENTED EDGE('',*,*,#47,.T.);
#29=ORIENTED EDGE('',*,*,#48,.T.);
#30=ORIENTED EDGE('',*,*,#47,.F.);
#31=PCURVE('', #54, #35);
#32=PCURVE('', #54, #36);
#33=PCURVE('', #54, #37);
#34=PCURVE('', #54, #38);
#35=DEFINITIONAL REPRESENTATION('', (#39), #8130);
#36=DEFINITIONAL REPRESENTATION('', (#40), #8130);
#37=DEFINITIONAL REPRESENTATION('', (#41), #8130);
#38=DEFINITIONAL REPRESENTATION('', (#42), #8130);
#39=B SPLINE CURVE WITH KNOTS('',1,(#7930,#7931),.UNSPECIFIED.,.F.,.F.,
(2,2), (0.,6.28318530717959),.UNSPECIFIED.);
#40=B SPLINE CURVE WITH KNOTS('',1,(#7990,#7991),.
```

STEP

```
. . .
<CylinderFeatureNominal id="4738">
 <Attributes n="2">
   <AttributeStr name=" 3dv.DefaultFittingAlgo" value="LEASTSQUARES" />
   <AttributeStr name=" 3dv.TrueGeomAlgo" value="Y14.5-2009" />
 </Attributes>
 <Name>Nominal 4738</Name>
 <FeatureDefinitionId>4737
 <Axis>
   <AxisPoint>0.75 0.5 -0.75
   <Direction>0 0 1</Direction>
 </Axis>
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   <Direction>0 0 1</Direction>
 </Axis>
</CylinderFeatureNominal>
```



UUID := Universally Unique Identifier

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Department of Defense INSTRUCTION

NUMBER 8320.03

November 4, 2015

Incorporating Change 3, October 25, 2021

USD(A&S)

SUBJECT: Unique Identification (UID) Standards for Supporting the DoD Information

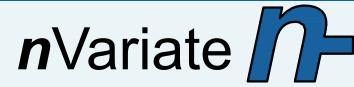
Enterprise

References: See Enclosure 1

1. <u>PURPOSE</u>. This instruction:

- a. Reissues DoD Directive (DoDD) 8320.03 (Reference (a)) as a DoD Instruction (DoDI) in accordance with the authority in DoDD 5135.02 (Reference (b)) to establish policy and assign responsibilities for creation, maintenance, and dissemination of UID standards to account for, control, and manage DoD assets and resources.
- b. Supports the National Military Strategy of the United States of America (Reference (c)) and the requirements of DoDI 8320.02 (Reference (d)) for sharing data, information, and information technology (IT) services by enabling sharing, analyzing, and disseminating

DoD warns of daily UUID conflicts when applied to all data generated



• UUID := Universally Unique Identifier

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• UUID's can be expensive (non-trivial costs involved)

reference checking can be complex

should not be employed indiscriminately or to every element in the data set; should be used where required

• UUID := Universally Unique IDentifier

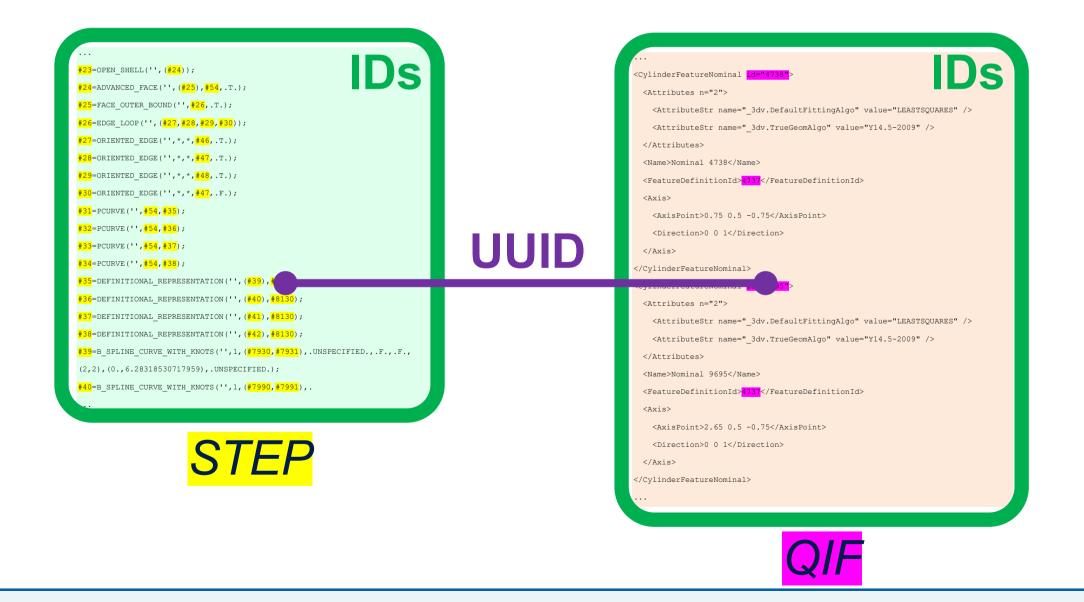
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#23=OPEN SHELL('', (#24));
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#39=B SPLINE CURVE WITH KNOTS('',1,(#7930,#7931),.UNSPECIFIED.,.F.,.F.,
(2,2), (0.,6.28318530717959),.UNSPECIFIED.);
\frac{40}{8} SPLINE CURVE WITH KNOTS('',1,(\frac{47990}{8},\frac{47991}{8}),.
```

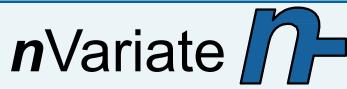
STEP

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<CylinderFeatureNominal id="4738">
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 </Attributes>
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</CylinderFeatureNominal>
```

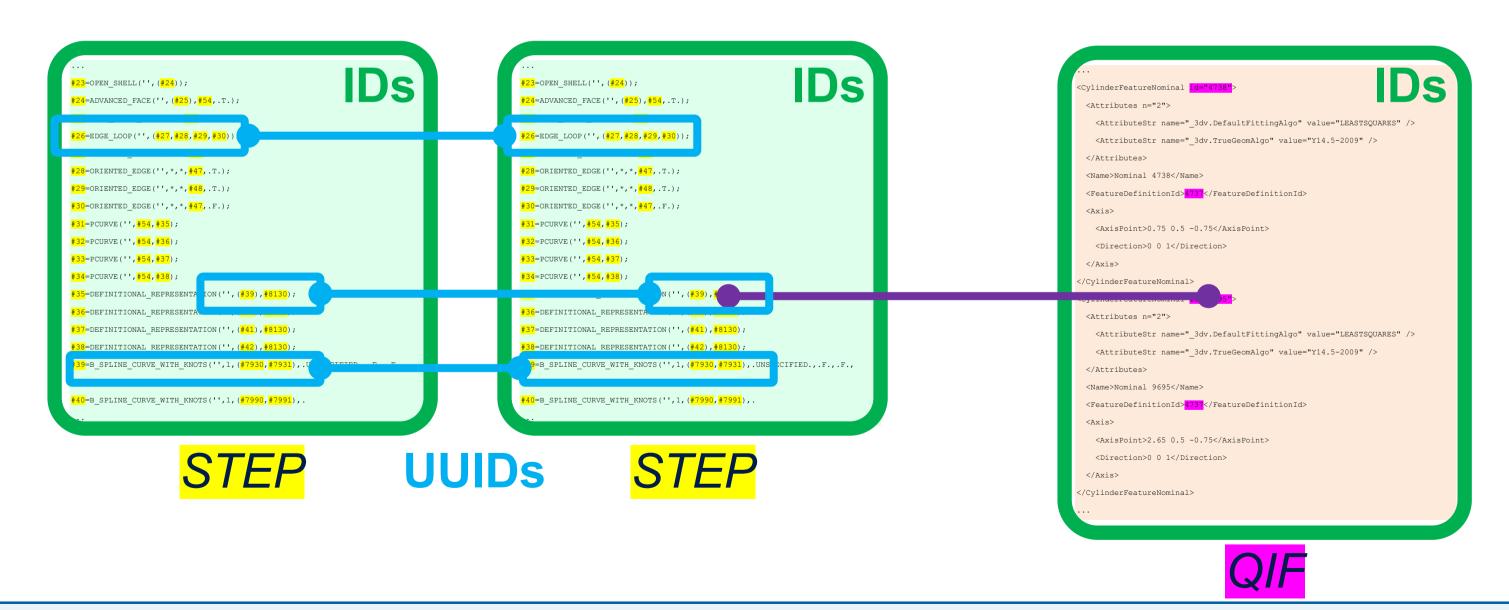


- UUID := Universally Unique IDentifier
- closed world VS open world workflows / use-cases





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- diffs, changes, conversions, translations, and updates





- UUID := Universally Unique IDentifier
- closed world VS open world workflows / use-cases
- diffs, changes, conversions, translations, and updates
- V4 UUID (random) VS

V5 UUID (namespace)

better persistence, link to authoring system namespace



- UUID := Universally Unique IDentifier
- closed world VS open world workflows / use-cases
- diffs, changes, conversions, translations, and updates
- V4 UUID (random) VS V5 UUID (namespace)
- UUID necessity is ultimately driven by use-case / value-add





Consistent theme:

- Blind implementation / expectations of MBE technology
 - Unclear use-cases
 - Undefined value-adds

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use - cases value - adds

MBE technology semantic PMI
features
UUIDs
PDQ
digital twins

Consistent theme:

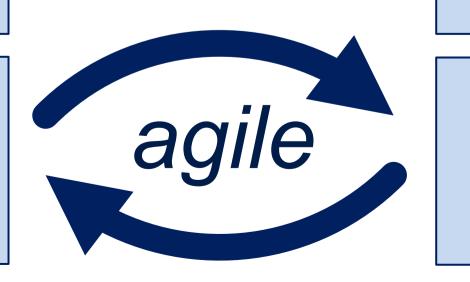
- Blind implementation / expectations of MBE technology
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use - cases value - adds



use - cases value - adds



MBE technology

MBE technology semantic PMI

UUIDs
features
PDQ
digital twins
semantic PMI

semantic PMI
features
PDQ
digital twins



Questions? Comments?

Contact:

benurick@nvariate.com dankeller@nvariate.com

